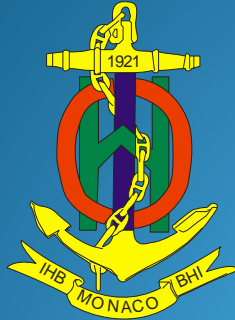


Introduction to Tidal Theory



R.E. FARRE BSc Cert. Nat. Sci.
Superintendent Tidal Information
SA Navy Hydrographic Office




Tidal Theory



“ The tide is the periodic vertical movement of water on the earth’s surface.”



Admiralty Manual of Navigation

- Introduction
- Short history
- Who uses tidal information
- Definitions
- Tidal theory
- Simple planetary motion
- Tide raising forces
- Tidal patterns – types
- Factors affecting tide form
- Installing a Tide Gauge
- Types of tide gauges





A Brief History



“Tide was just the sea advancing and retreating once or twice a day”


- Legends explained the movement of the sea
 - Whales breathing cycle



- Greeks and Romans not bothered by tide
 - Mediterranean tides are imperceptible
 - Caesar lost war on the English shores





- 3rd Century
 - Aristotle first to make reference to tidal motion
- 10th Century
 - Arabs related tide to the cycles of the moon
- 13th Century
 - First tide table compiled by an English Monk
- 17th Century
 - Sir Isaac Newton and his universal theory of gravitation (1687)
 - Gravitational theory became the established theory for all tidal theory
- Baron Kelvin/ George Darwin
 - Developed harmonic analysis
 - Kepler, Newton and Laplace








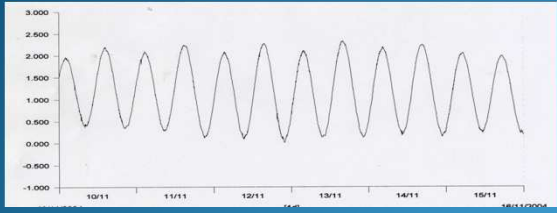
Who Uses Tidal Predictions

- The Hydrographic Surveyor
 - To reduce soundings to a common datum
- The Navigator
 - Safe navigation of estuaries and coastal waters
- Harbour and coastal engineers
 - Construction of harbours, bridges etc.
- The general public
 - Fishing, sailing, hiking etc.

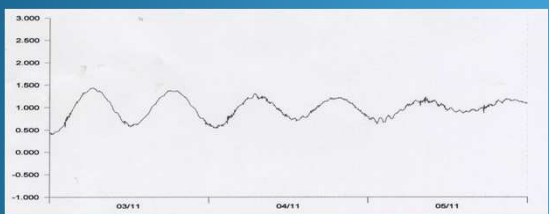


Definitions

- Tide
 - Vertical rise and fall of the oceans and other large bodies of water in response to the gravitational attraction of the moon and sun.
- Tidal stream
 - The horizontal movement that accompanies the rise and fall (vertical) movement of the tide
 - In the USA known as tidal current

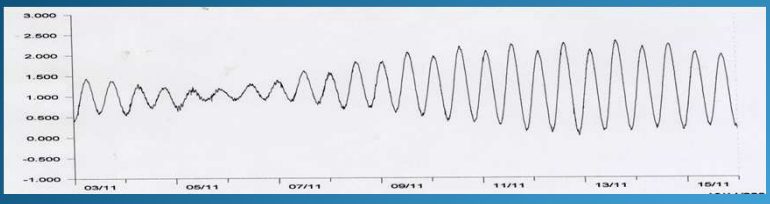


- Spring tide
 - Highest high tide and lowest low tide

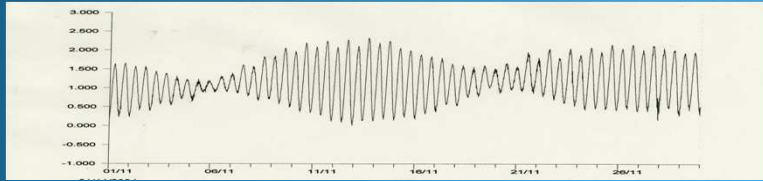


- Neap tide
 - Lowest high tide and highest low tide

The slide features two tide graphs. The first graph, titled 'Spring tide', shows a sinusoidal wave with a vertical axis from -1.000 to 3.000 and a horizontal axis from 10/11 to 15/11. The wave has a high amplitude, with peaks near 2.500 and troughs near -0.500. The second graph, titled 'Neap tide', shows a sinusoidal wave with the same vertical axis and a horizontal axis from 03/11 to 05/11. This wave has a much lower amplitude, with peaks around 1.500 and troughs around 0.500.



- Tide progressing from neaps to springs





- Tide over one month

The slide features two tide graphs. The first graph, titled 'Tide progressing from neaps to springs', shows a sinusoidal wave with a vertical axis from -1.000 to 3.000 and a horizontal axis from 03/11 to 15/11. The wave's amplitude increases over time, starting with a low amplitude and reaching a high amplitude by the end of the period. The second graph, titled 'Tide over one month', shows a sinusoidal wave with the same vertical axis and a horizontal axis from 01/11 to 25/11. The wave's amplitude also increases over time, starting with a low amplitude and reaching a high amplitude by the end of the period.




- **Chart Datum (CD)**
 - The datum to which all soundings on large scale navigational charts of an area are reduced
 - Lowest Astronomical Tide (LAT) in RSA

- **Land Leveling Datum (LLD)**
 - The datum to which all altitudes above sea level and all depths below it are referred
 - Sometimes referred to as Mean Sea Level (MSL)
 - Ordinance Datum






- **MHWS**
 - Mean high water springs
 - The average HEIGHT of the HIGH water SPRING tides



- **MLWS**
 - Mean low water springs
 - The average HEIGHT of the LOW water SPRING tides

- **MHWN**
 - Mean high water neaps
 - The average HEIGHT of the HIGH water NEAPS tides

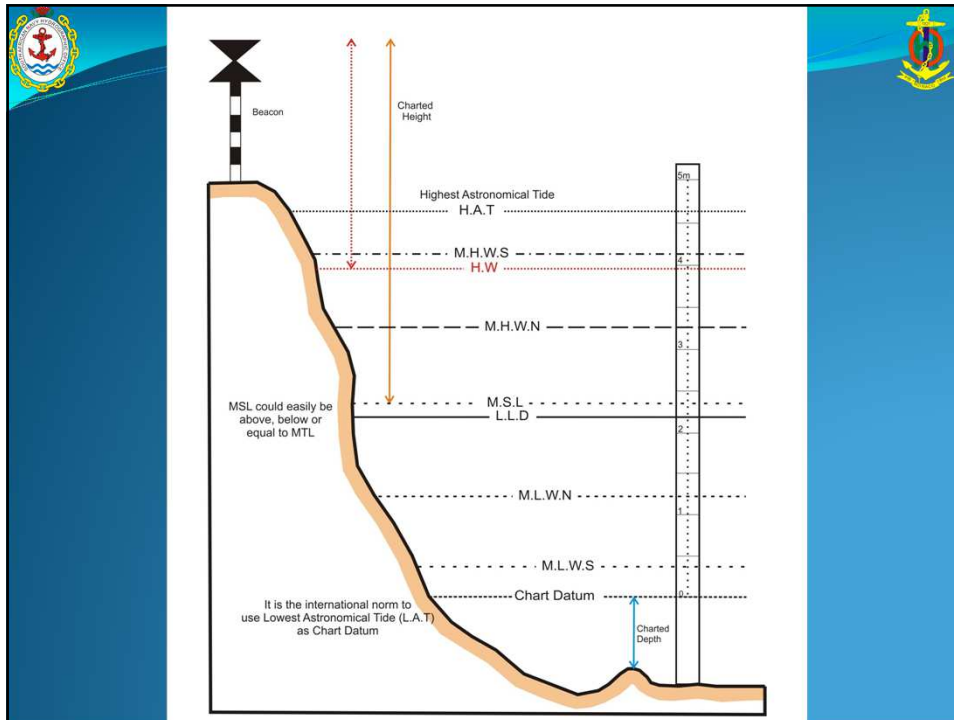
- **MLWN**
 - Mean low water neaps
 - The average HEIGHT of the LOW water NEAP tides

- **MHW**
 - Mean high water
 - Average height of high water levels at a given location over a period of 19 years.
- **MLW**
 - Mean low water
 - Average height of low water levels at a given location over a period of 19 years.
- **Mean Sea Level (MSL)**
 - The average position of the sea level across all tidal periods during a 18.6 year interval
 - This is different to Land Leveling Datum/ Ordinance Datum
- These levels vary with change in MSL, from year to year in a cycle of 18,6 years.
- When the average maximum declination of the moon is $23\frac{1}{2}^{\circ}$, the range of the tide is at it's greatest.






- **Declination**
 - Inclination from the vertical
 - Angular distance from celestial equator
- **Apogee**
 - The point at which the moon's orbit is the furthers from the earth's gravitational center
- **Perigee**
 - The point at which the moon's orbit is the closest to the earth's gravitational center
- **Syzygy**
 - Occurs when the right ascension of the sun and moon are co-incident to one another (in line) when the moon is full or new
- **Lunitidal Interval**
 - Interval between the moon's transit (upper or lower) over the local time meridian (Or Greenwich meridian) and the following high or low water.
 - Upper transit: crosses the time meridian near the tide gauge
 - Lower transit: crosses the meridian that is 180° from the tide gauge



Tide Raising Force




- Newton's law of motion and gravity
- The earth- moon system
- The earth - sun system
- The gravitational force
- Earth's rotation
- Declination
- The lunar orbit
- The earth-sun-moon system

Gravitation

Newton's laws of motion and gravity

- 1st LAW
 - Every body continues in a state of rest or uniform motion in a straight line unless acted upon by an external force
- 2nd LAW
 - When a body is acted upon by an external force, its acceleration is directly proportional to that force and inversely proportional to the mass of the body. Acceleration is in the direction in which the force acts
- 3rd LAW
 - If a body exerts a force on a second body, the second body exerts a force that is equal in magnitude and opposite in direction to the first force.
 - For every action there is an equal, but opposite reaction.

- Newton's universal law of gravitation states that for any two heavenly bodies, a force of attraction is exerted by each one on the other:
 - Proportional to the product of their masses
 - Inversely proportional to the square of the distance.




$$F_g = G \frac{m_1 m_2}{r^2}$$

- Tides are caused by the gravitational pull of a heavenly body on the earth and the water lying on the earth's surface



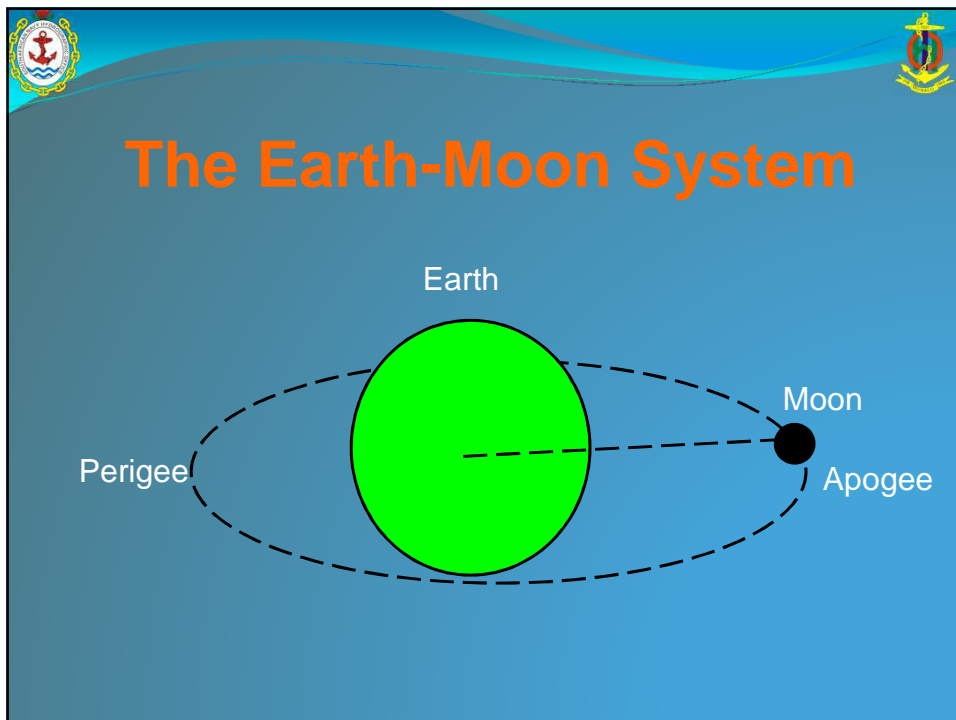
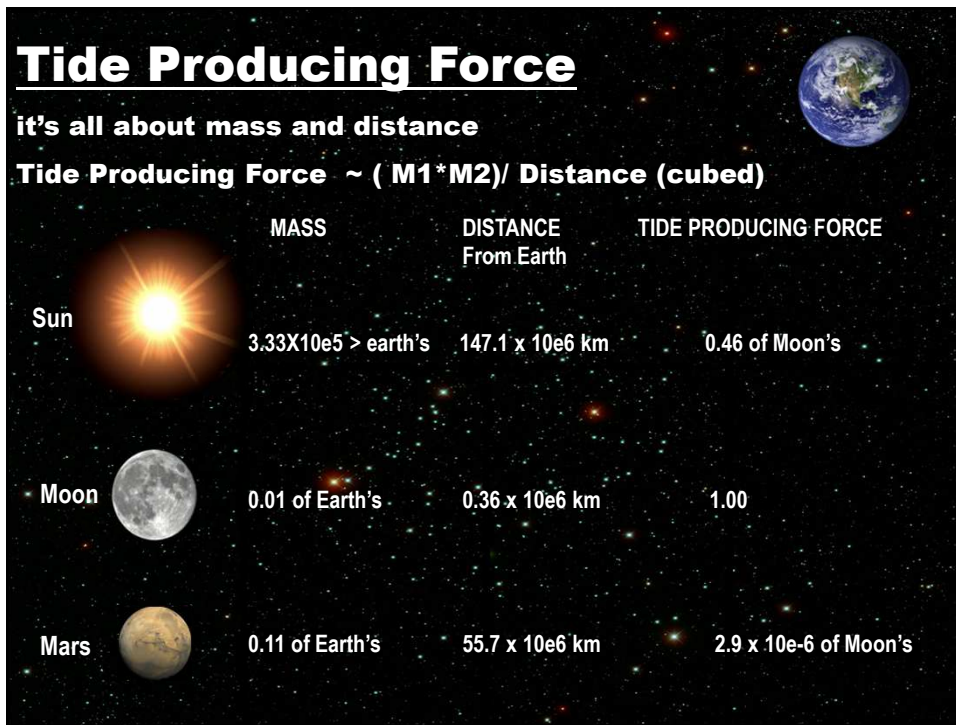

Basic Tidal Theory


- Equilibrium tidal theory
 - Imaginary earth that is totally covered in water
 - **No** land masses/ continents
 - **No** declination
 - **Nothing** like real tide theory
- Real tide theory
 - The real earth
 - Has land masses
 - Has declination
 - Has rotation
 - More dynamic

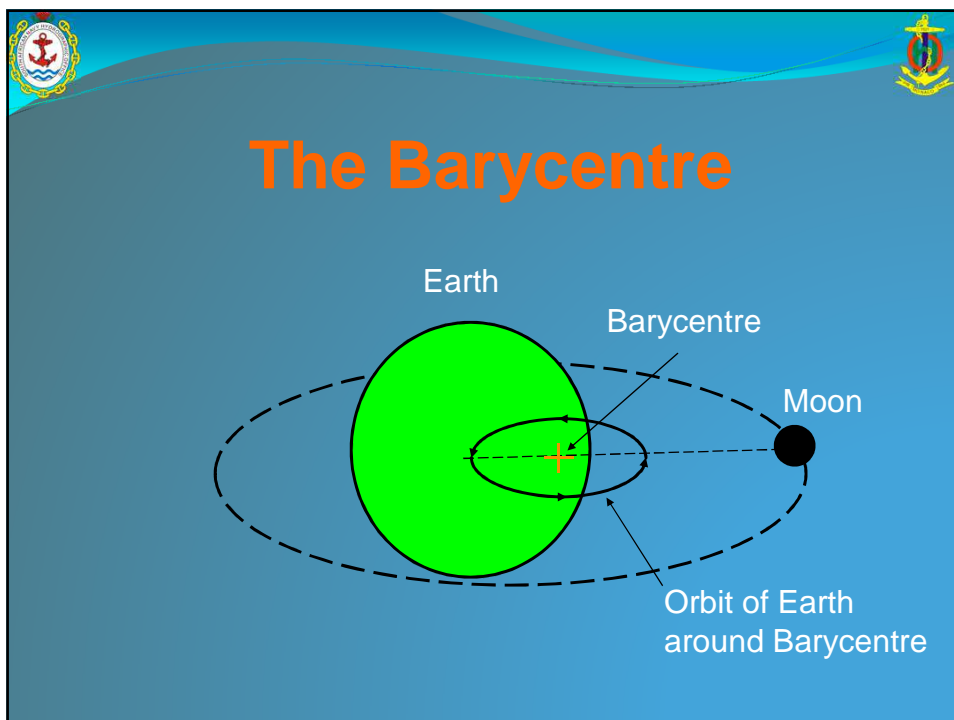
Equilibrium Theory

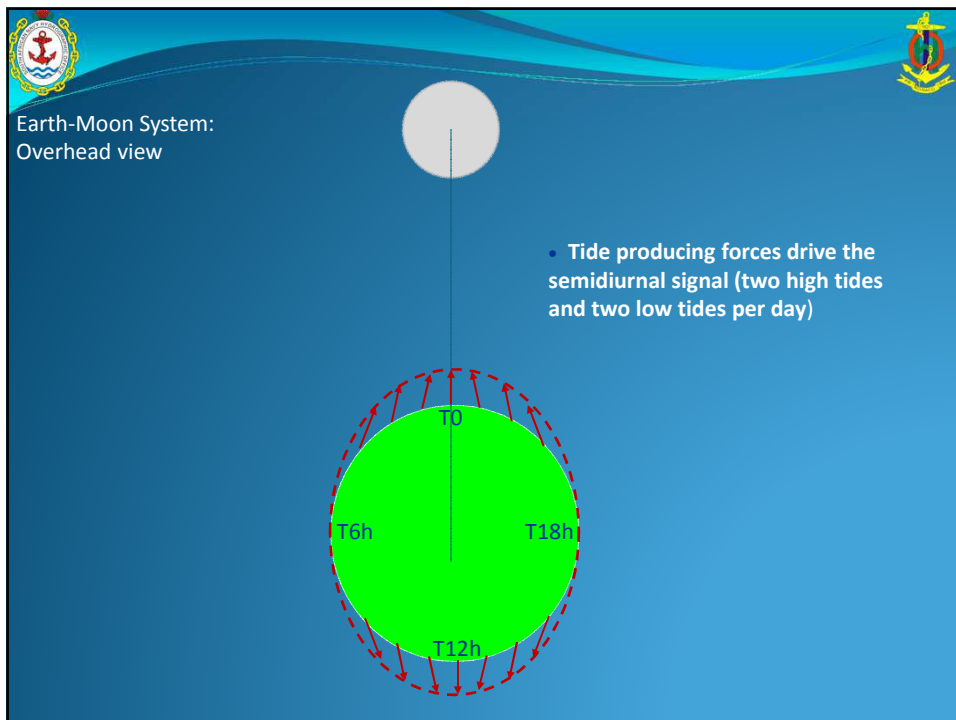
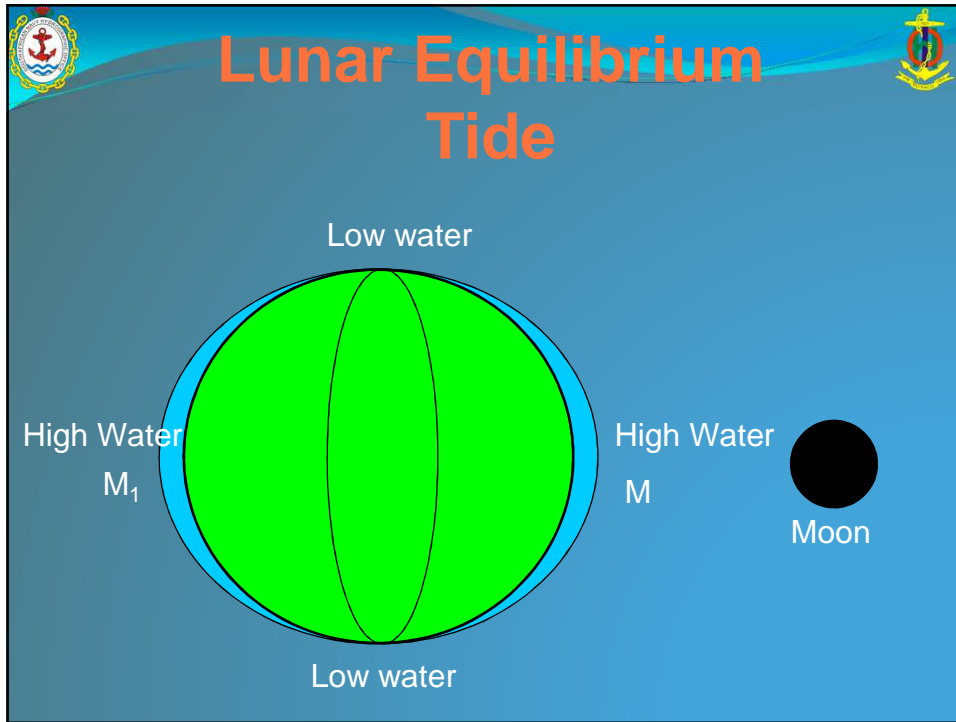
- Gravitational attraction between sun/earth and earth/moon
 - Mass of sun= **27 million** times mass of moon
 - Distance between sun and earth = **390** times the distance between moon and earth
 - $\frac{F_g(\text{sun})}{F_g(\text{moon})} = \frac{27 \times 10^6}{(390)^2}$
 - $F_g(\text{Sun}) = 178$ times that of the moon
- The moon's tide producing force is **2x** the sun's gravitational effect
- Moon's gravitational effect is 1/10 000 000th of the earth's gravitational effect

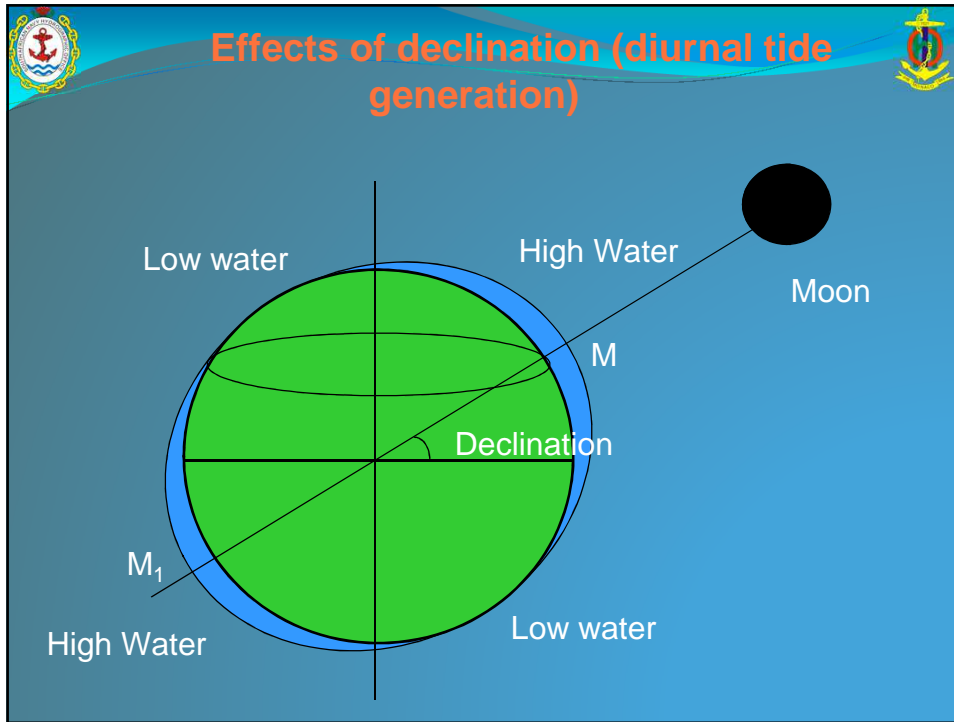




- The earth/moon rotate around a common centre of gravity
- Known as the barycentre
 - Approx. 1700km below the surface of the earth
- (Earth and the sun both rotate around a common centre of mass which is less than 500km from the centre of the sun)









Lunar Orbit

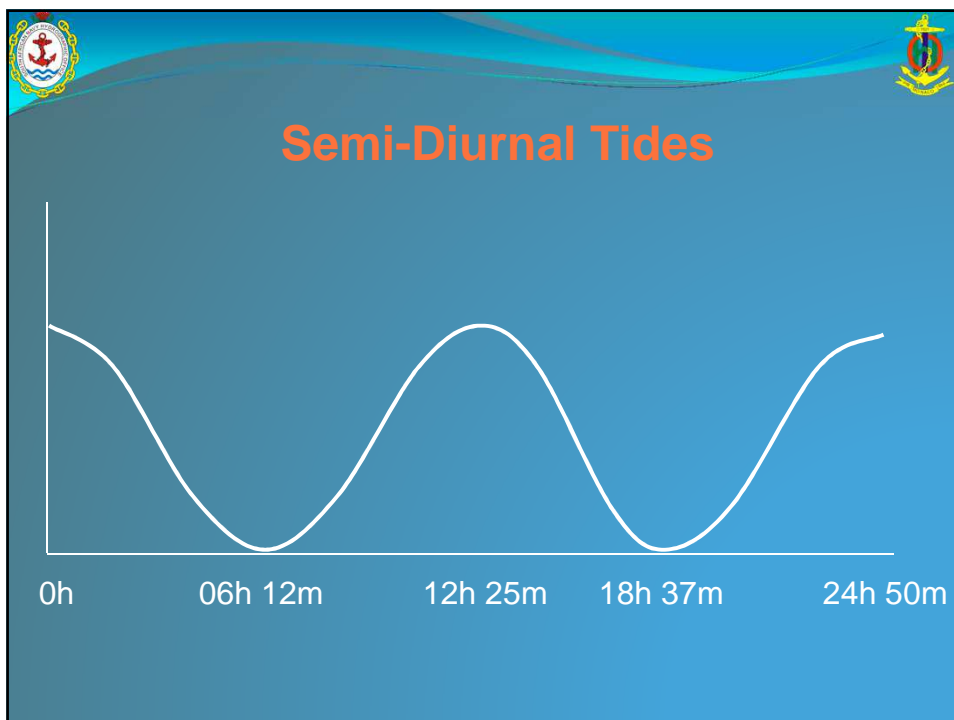
The diagram shows the Moon's orbit around Earth. The Earth's equator and ecliptic are shown. The Moon's orbit is an ellipse. The angle between the plane of the Moon's orbit and the Earth's equatorial plane is labeled 'I'. The diagram shows the Moon's orbit, the Earth's equator, and the ecliptic. The angle I is highlighted in a red box.

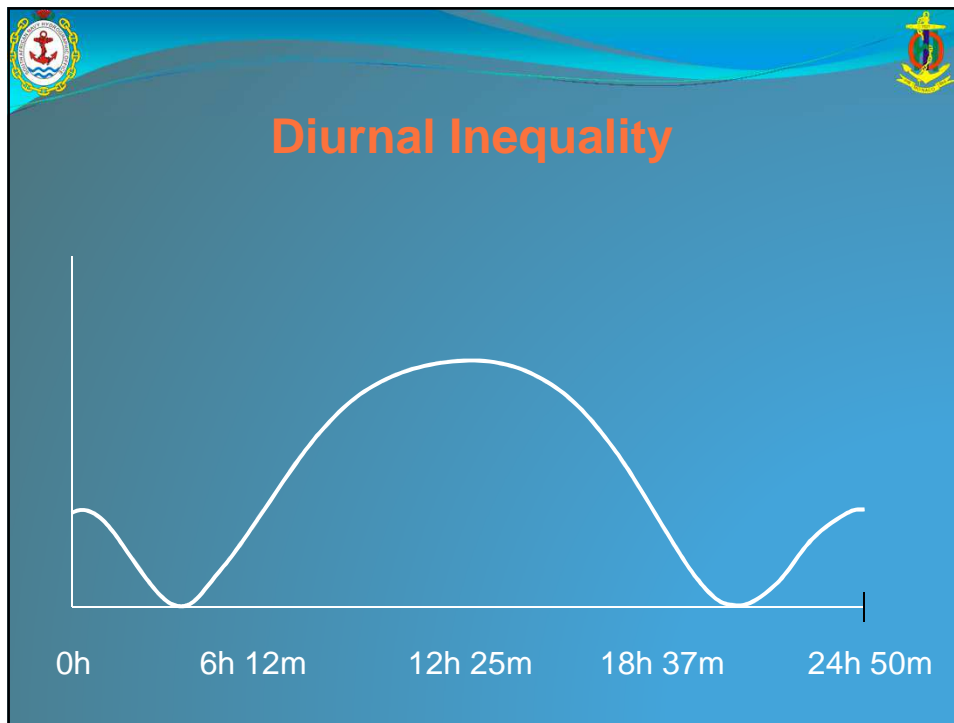
- Angle I is angle between the plane of moon's orbit and Earth's equatorial plane
- I varies over an 18.6-yr period between 28.5° to 18.5°
- Cycle called the *lunar nodal regression*
 - Has a $\pm 4\%$ effect on M_2 and a $\pm 11\%$ on diurnal frequencies



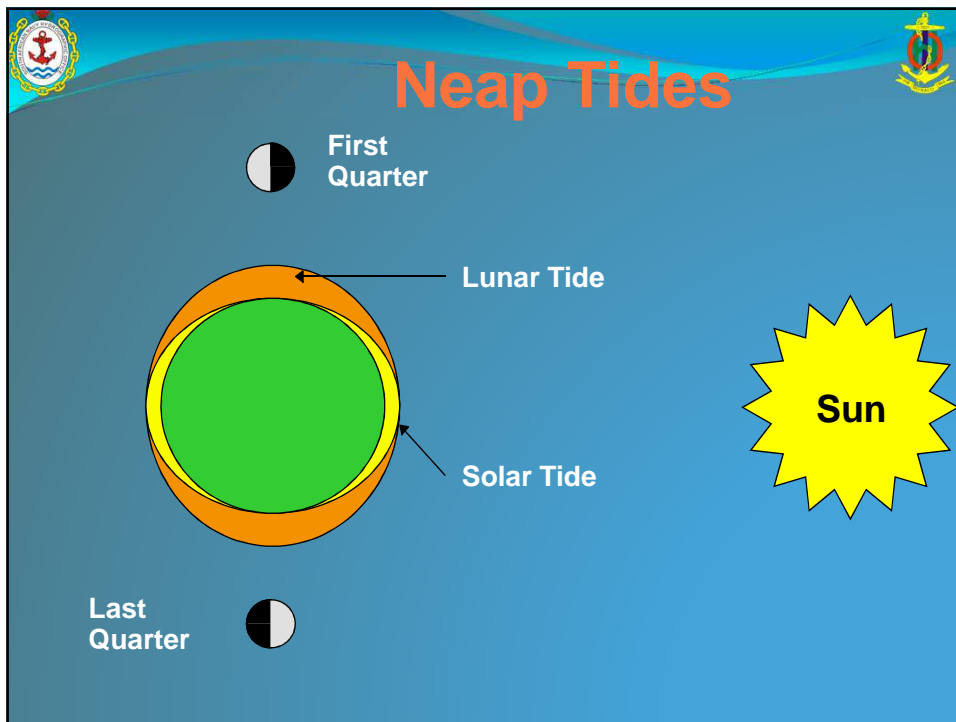
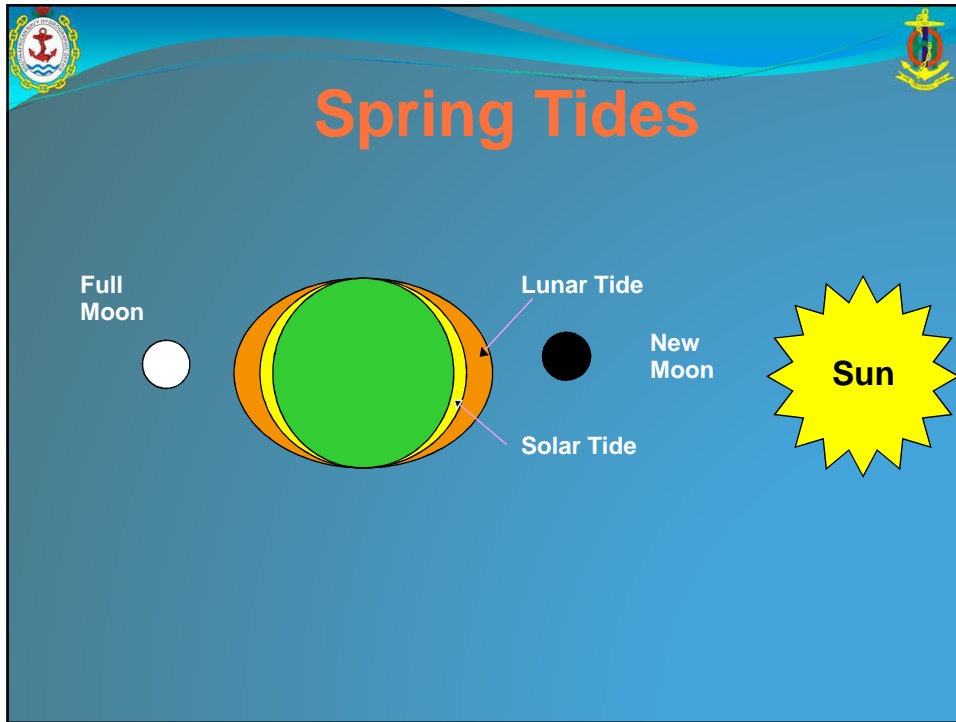
Tidal Patterns

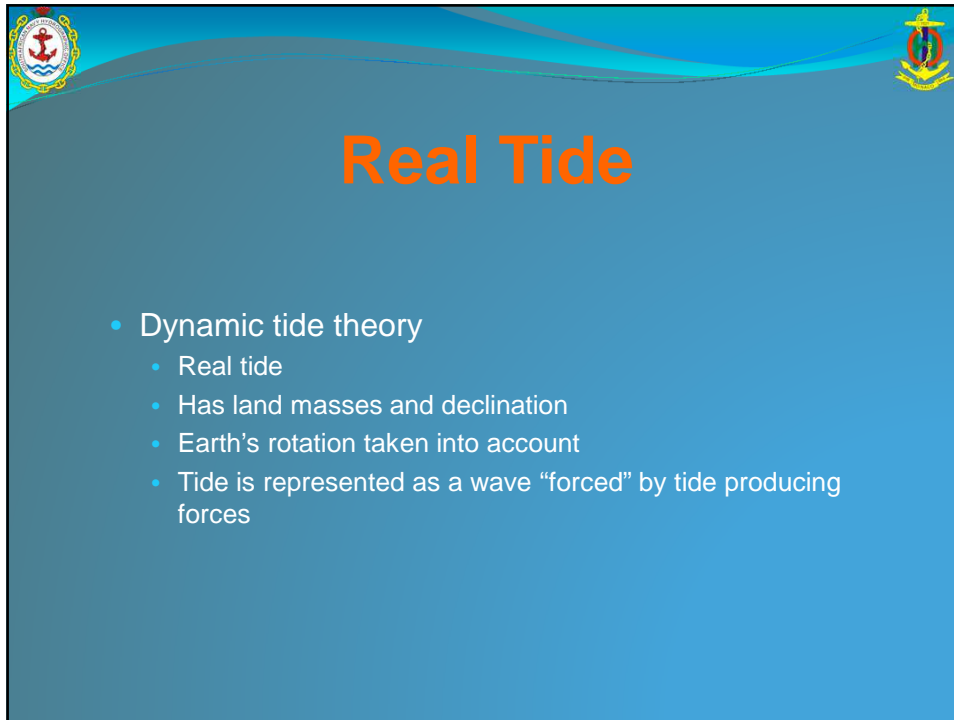
- Semi- diurnal tides
 - Two high tides
 - Two low tides
 - Approximately 6 hours apart
- Diurnal tides
 - One high tide
 - One low tide
 - Approximately 12 hours apart
- Mixed tides
 - Characteristics of semi- diurnal and diurnal tides





- Spring tides
 - Highest high tide
 - Lowest low tide
 - Large range
 - Occurs 1 to 2 days after full and new moon
- Neap tides
 - Lowest high tide
 - Highest low tide
 - Small range
 - Occurs 1 to 2 days after first and last quarter
- Approximately every 7 days alternates between springs and neaps.







Real Tide

- Dynamic tide theory
 - Real tide
 - Has land masses and declination
 - Earth's rotation taken into account
 - Tide is represented as a wave "forced" by tide producing forces






Factors Effecting Tide Form

- Real ocean basins have very complicated coastal and bottom topography.
- The sun/ moon
 - Varies the amplitude and timing of the tide
- Geography
 - Land masses impede and deflect water movement
- Friction
 - Retards movement
- Basin oscillation
 - Natural period of oscillation
- Lunar and terrestrial orbits
 - Shape and plane of earth's orbit around the sun and that of the moon's around the earth
- Natural Resonance
 - Determines how water will behave






- The earth's orbit
 - Eccentric ellipse
 - Perihelion
 - Aphelion
- The earth's tilt/ declination
 - Relative position of the sun and moon in relation to the earth
- The moon's orbit
 - Eccentric ellipse
 - Varying apogee and perigee
- The weather
 - Prevailing winds
 - Frontal movements
 - Atmospheric pressure
 - Storm surges







Natural Resonance

- Every body of water, of any size, has a natural frequency of oscillation
 - Dependent on size and depth of the body of water
- When natural frequency of the oscillation = (or is very nearly the same) the frequency of an imposed force, resonance occurs
 - Wave has similar frequency to the oscillation the wave becomes amplified.
 - Very large movements result from very small applied forces.
- Decisive factor in determining whether the water will respond to diurnal, semi- diurnal or mixed tide raising forces

- Semi-diurnal
 - The Atlantic tends to be more responsive to semi-diurnal forces
 - More influences by the phases of the moon than by declination
 - Largest tide of the year: at springs near the equinox
 - Sun and moon are at the equator
- Diurnal
 - The Pacific tends to be more responsive to diurnal forces
 - Large diurnal component
 - Largest tides are associated with the greatest declination of the sun and moon
 - Summer and winter solstices

- Mixed
 - Where the diurnal and semi-diurnal tide raising forces are both important
 - Tends to be characterized by large diurnal inequalities

Distribution of Tidal Phases

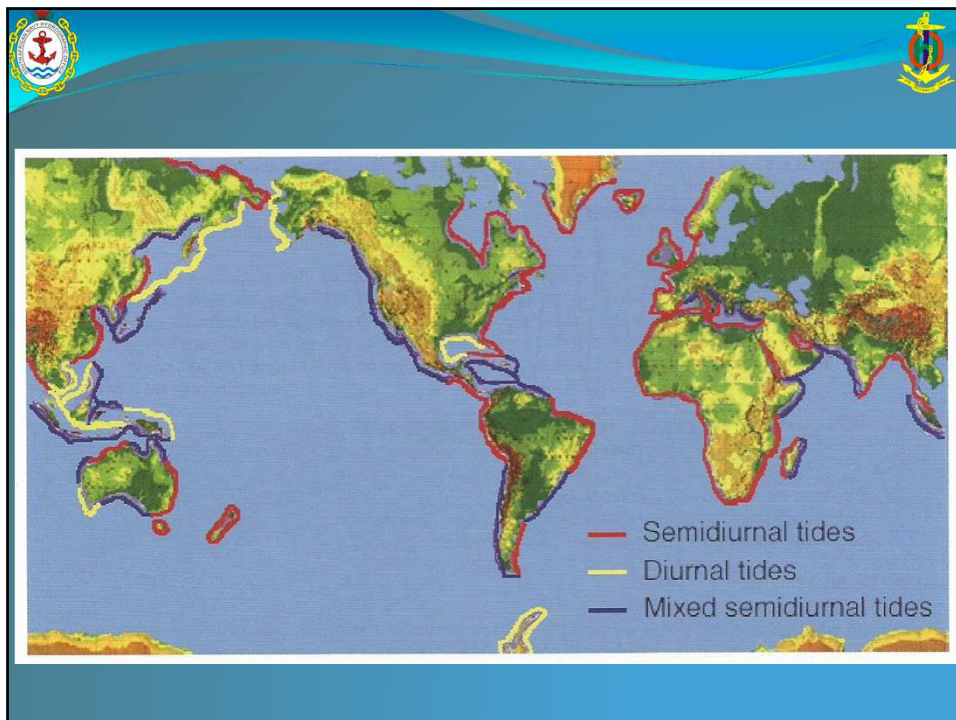
The figure contains three graphs illustrating different tidal patterns:

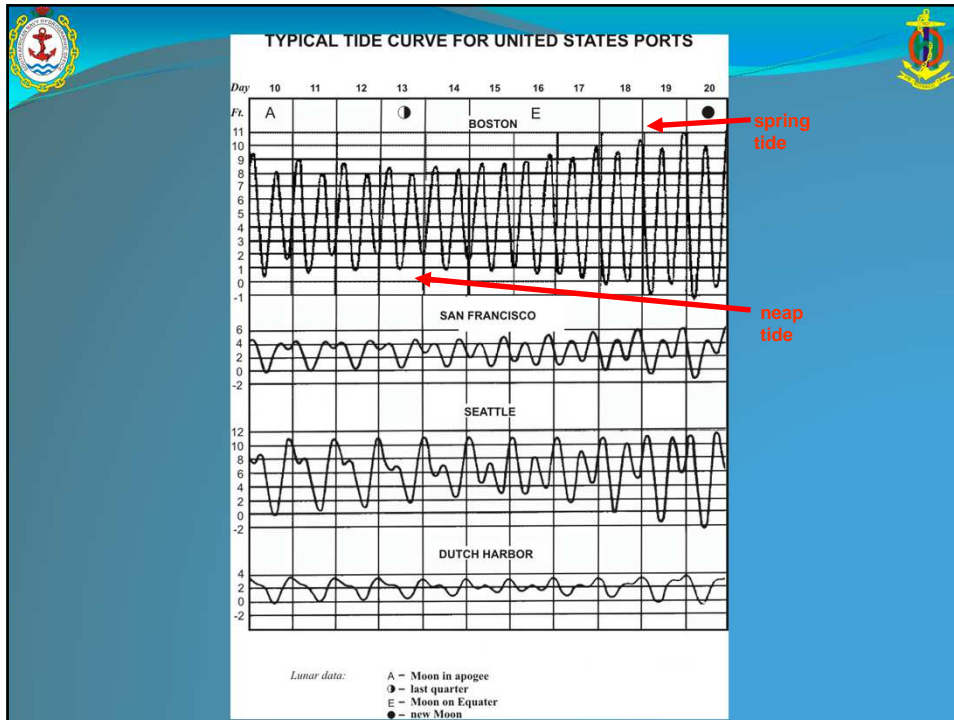
- SEMIDIURNAL TIDE:** Shows two high waters and two low waters within one tidal day. The tidal period is indicated between consecutive high waters.
- MIXED TIDE:** Shows four high waters and four low waters per tidal day, but with unequal heights. Labels include Higher High Water, Lower High Water, Higher Low Water, and Lower Low Water. The tidal period is shown between two consecutive high waters.
- DIURNAL TIDE:** Shows one high water and one low water per tidal day. The tidal period is shown between two consecutive high waters.

The y-axis for all graphs is 'Tidal Height (in feet above or below the standard datum)' ranging from -4 to 3. The x-axis is 'Tidal Day'.



- The Mediterranean Sea and Baltic
 - Resonant period of a few hours
 - Too small to enable any appreciable tide to be generated
- Strait of Gibraltar
 - Too restricted to allow Atlantic tides to have any appreciable effect other than on the extreme western side



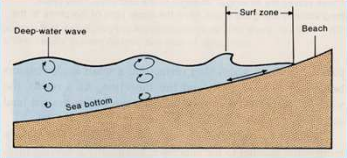


Friction

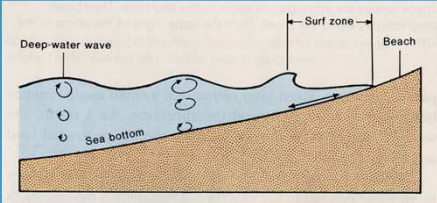
- Friction
 - As with all fluids there is internal drag between water molecules
 - Frictional drag exists between water and the sediments on the sea floor
- Frictional influence extends upwards towards the surface of the water
 - Effect of friction is to slow water flow
 - Actual speed of water is much greater than that occurring near the seabed.
- The lower part of the flow experiencing frictional retardation is known as the *boundary layer*



Land and Shallow Water Effect

- Land
 - Location and shape of various land masses
 - Local conditions of resonance
 - Effect on tidal conditions
- Shallow water
 - When a wave travels into shallow water
 - Its shape is changed
 - Friction causes a distortion
 - Of the tidal curve.
 - The curve steepens
 - The circular motion of the water
 - Particles become elliptical



- As waves approach a shelving shore
 - Orbital motion becomes flattened to an ellipse
 - Wave slows down
 - Crests pile up and eventually wave breaks to form surf



- Incoming tide and river estuaries
 - The amplitude of the tide wave increases as it travels up an estuary
 - Forcing from a wide entrance to a narrower channel
 - Distorts the tidal height
- These distortions can become of great importance
 - Results in very large tides.






Windsor N.S. UK



Qiantang River, China



River Winster, UK



Pettitcodiac River, New Brunswick

- Bores
 - Extreme case of shallow water effect when a tide with a large range is funneled into a river or estuary with a steeply shelving bottom.



New Brunswick



Bay of Fundy, New Brunswick




Pettitcodiac River, New Brunswick

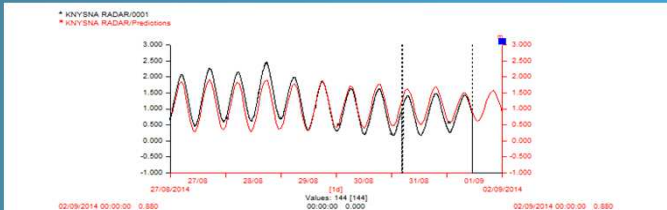
Meteorological Effects


- Meteorological conditions which differ from the average will cause corresponding differences between actual and predicted tides
- Variations are mainly caused by strong/prolonged winds and unusually high or low barometric pressures
- Differences between predicted and actual tide heights are mainly due to wind
- Statistical analysis indicates
 - 1 std deviation of differences between predicted and actual heights and times = 0.2m and 10 minutes respectively

Barometric pressure




- Barometric pressure
 - Tidal predictions are calculated for average atmospheric pressure
 - Low pressure = tendency for sea level to rise
 - High pressure = tendency for sea level to drop/be depressed
- Water level does not adjust immediately to pressure change.
 - It responds to the average change over a considerable area
- Water level seldom exceeds an adjustment of 0.3m due to barometric pressure change





- Effect of wind
 - Very variable and depends largely on the topography of the area
- In general —→ the wind will raise sea level in the direction towards which it is blowing
 - A strong onshore wind will pile up water ∴ high water will be higher than predicted
 - Winds blowing offshore will have the opposite effect
- Winds blowing along a coast
 - Set up long waves that travel along the coastline
 - Wave crest raises the sea level
 - Wave trough lowers the sea level

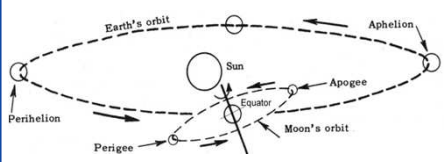


Positive and negative surges

- A change in sea level often caused by wind and barometric pressure.
 - A *rise* in sea level = **positive** surge
 - A *fall* in sea level = **negative** surge
- A **storm surge** is an unusually severe positive surge
- Positive surge
 - Greatest effect in confined area
 - rarely increases general sea height by more than 1m
- Negative surge
 - NB for large vessels navigating with small under-keel clearances
 - Most evident in estuaries and areas of shallow water
 - Falls of up to 2m have been recorded.

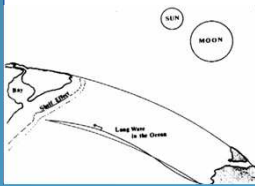
So far...

- Tides are the result of the gravitational forces of the Earth, moon & sun and the centrifugal forces created by the orbit of the moon around the Earth & the Earth around the sun
- Tidal frequencies (constituents) are created due to changes in the moon's orbit around the Earth.
 - Consequently the same applied to the earth's orbit around the sun
- It is the **astronomical forcing** of the tide that is the basis for the tide's predictability.



and...


- hydrodynamics** determines:
 - the size of the tide range,
 - the timing of high and low waters
 - the type of tide
 - the speed and timing of the tidal current
 - etc.
- The range and timing of the tide (and thus the speed/ direction/ timing of the tidal stream) are affected by
 - Length, width & depth of the bay
 - Friction
 - And Storm surges
 - (The hydrodynamics)
- Because of hydrodynamics, the tide (and tidal stream) characteristics vary with horizontal (geographic) distances throughout a waterway.









Tidal Streams

- Influence of water movement on maritime operations
 - Influenced over the whole column from surface to sea bed
- Deep draught vessel navigation
 - Water movement \perp to the course of the ship will influence the course to steer
 - In relatively shallow areas (20-40m) water movement will be largest
 - Friction will cause variation in speed and direction with increasing depth







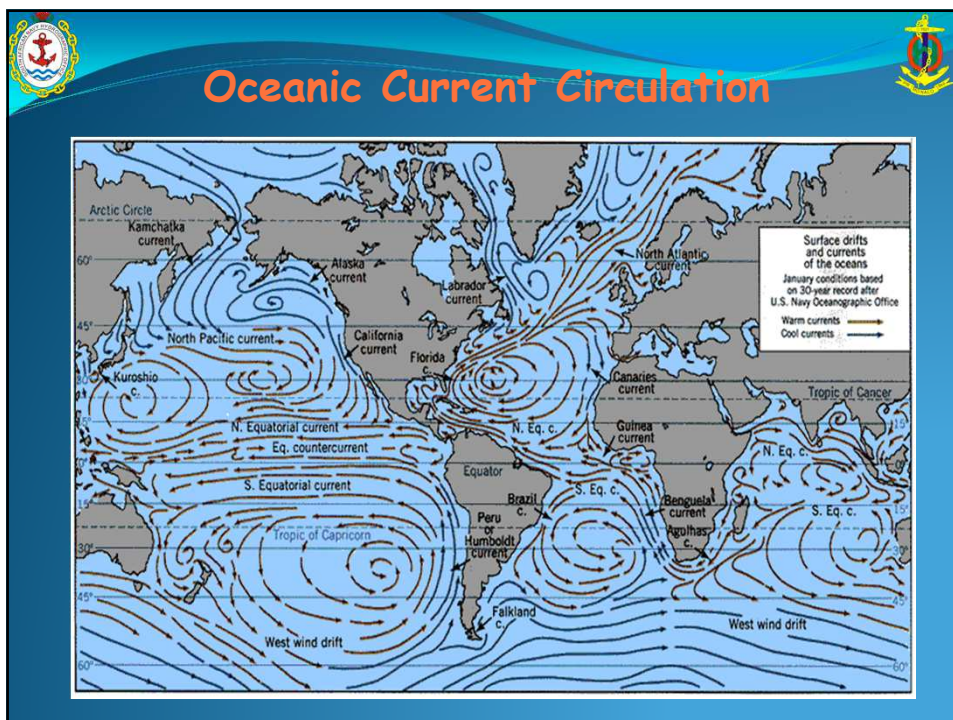
- Submarine navigation
 - Surface water is of little importance, submarines are subject to deep water movement
- During naval exercise - surface and sub-surface vessels are subject to different movements
 - Same courses to steer result in different courses over the “ground”

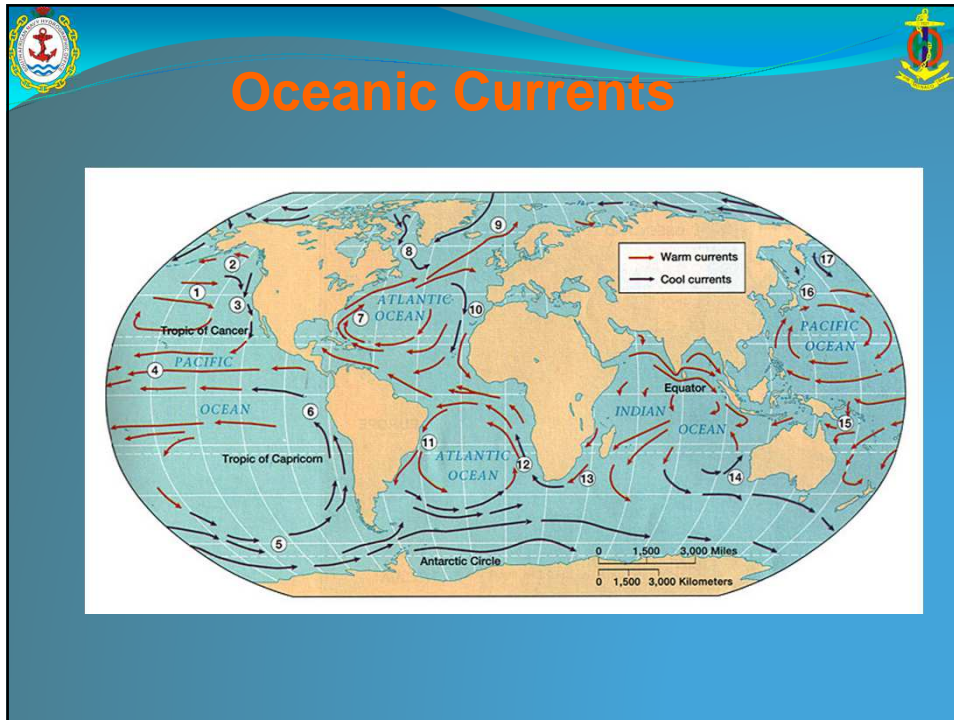


- What is a tidal stream?
 - It is the motion of the water particles *caused by the tide-generating forces* **only**.
 - And it is the horizontal movement of water particles associated with the vertical movement of tide.
- Tidal streams can be modified by meteorological changes, and the effects of any other currents present.
- Tidal streams change direction and strength as a result of man-made structures
 - The direction and rate of the stream may vary, at any instant, with depth below the water surface.
 - **NB** to know the depth at which readings are taken.

- Total flow is the actual movement experienced.
 - Includes the effects of weather, tidal currents and random errors of measurement
 - Expressed as a rate towards a certain direction
 - eg: 1.4 knots, (towards) 137
- Non- tidal currents are mainly meteorological in origin and often involve density changes
 - Approximately constant in rate and direction from day to day
 - May change from month to month in an annual cycle
- The surveyor conducting tidal stream observations wants to measure tidal stream without the effect of weather and current
 - In reality all measurements include some form of non-tidal component
 - When accepting tidal stream measurements assume that the other effects are negligible



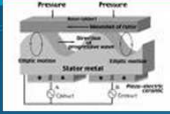
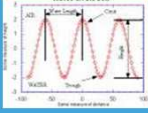


Progressive and Standing waves

- For tide waves, depth is small compared with wavelength
- As progressive wave moves past some fixed point
 - Successive high and low sea levels are observed

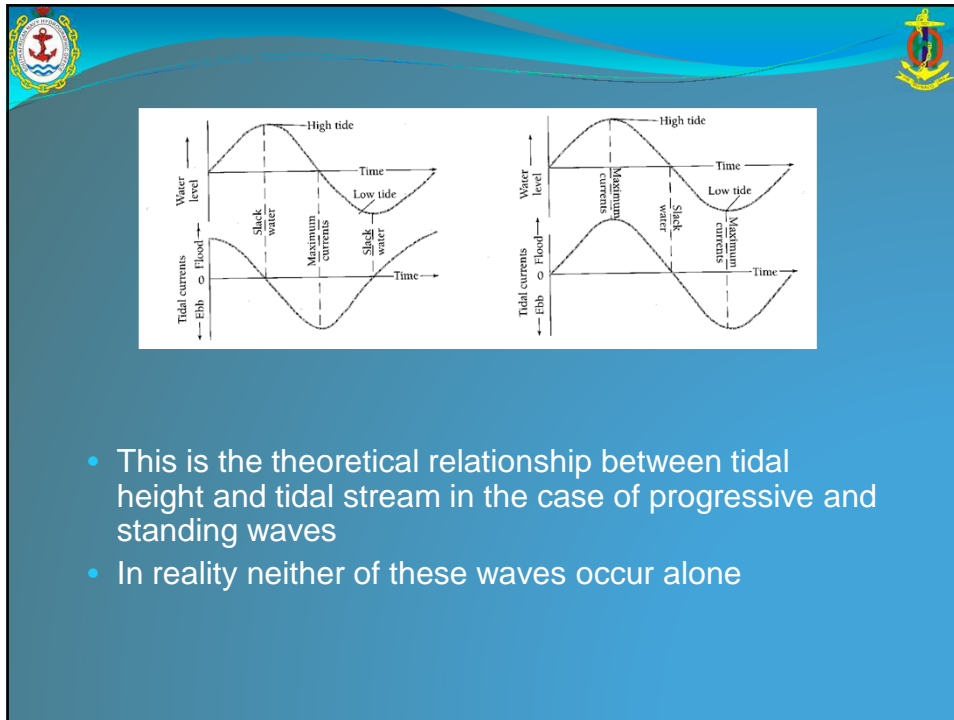
The diagram consists of two vertically aligned graphs sharing a common horizontal time axis. The top graph plots 'Water level' and shows a sinusoidal wave oscillating between 'High tide' and 'Low tide'. The bottom graph plots 'Tidal currents' and shows a sinusoidal wave oscillating between 'Flood' (ebb) and 'Ebb' (flood). Vertical dashed lines connect the two graphs, showing that 'Maximum currents' occur at the points where the water level is changing most rapidly (at the zero-crossings), which are labeled as 'Slack water'.

- At local high water there is a maximum current in the direction of the wave propagation, but at low water there is a current in the opposite direction.

- Tides cannot propagate endlessly as progressive waves.
- Tides undergo reflection at sudden changes of depth and at local coastal boundaries.
- The reflected and incident waves combine together to give the observed tide.
- Reflection produces a fixed pattern of *standing waves*
 - Has alternative **nodes** : position where amplitude is 0, and **antinodes**: where amplitude is at a maximum
 - Separated by a distance of $\lambda/4$ (λ is the wavelength of the original progressive wave)



- At the **nodes** there is **no net change of water level**
 - Currents have maximum amplitude
- At the **antinodes** there is a **maximum change of water level**
 - No currents



- This is the theoretical relationship between tidal height and tidal stream in the case of progressive and standing waves
- In reality neither of these waves occur alone

Nature of Tidal Streams

- It is known from observations that tidal streams in most cases do not simply flow to and fro in one direction
 - Change direction and *rotate* in the tidal period.
- Tidal streams in the open are, by their very nature, **rotary**
 - They only tend to flow back and forth (rectilinear) when constrained by land masses and shoals
- The sense of rotation is controlled by many factors
 - Tide raising forces
 - Coriolis accelerations
 - Coriolis deflects currents to the **left** in the **southern** hemisphere and to the **right** in the **northern** hemisphere.
 - Shelving coast
 - Combinations of oscillations and progressive waves
 - Bathymetry.



Nature of Oceanic Currents

- Currents in the deep oceans are set up by a number of mechanisms
 - Astronomical tide generating forces
 - Coriolis
 - Prevailing winds (wind generated gravity waves)
 - Atmospheric pressure gradients
 - Density gradients
 - Density varies with salinity, temperature and pressure (depth)
 - Cooling in the polar regions



Questions?



Tidal Levels and Datums

- When conducting a survey, the surveyor needs to measure heights & depths above or below certain fixed levels - **datums**
 - Either given to you by tidal department (CD)
 - Choose your own (SD)
 - Must be fixed connected to a fixed land datum
- In RSA, LLD = MSL = 0
 - This is only when MSL is a reference level with no value attached to it.



The diagram shows a cross-section of a ship's hull and a depth sounder. The ship's draft is corrected for dynamic transducer and draft. The observed depth is measured from the ship's keel to the seabed. The actual depth is the true depth, which is the observed depth plus tide correction and sound velocity correction. The chart depth is the depth shown on a nautical chart, which is the actual depth plus tide correction. The reference datum is the fixed land datum used for the chart.

Mean Sea Level



- **Mean Sea Level**
 - Natural reference level of the geoid
 - Average level taken up by the sea over a 19 year interval (over all tide readings)
 - Best vertical reference level ∴ basic reference level for tides
- Observed MSL subject to change:
 - Polar melting / glacial activity
 - Meteorological effect (frequently not local)
 - Short period effects (sea, swell, surges)
 - Tectonics
 - Astronomical effects





- MSL can only be found by observation:
 - Mean of all tide readings over long period (30days - 19 years)
 - Mean of 39 hourly observations (method involves applying filters)
 - Mean of 25 hourly observations (very poor method)
- **MSL is considered a level surface over a long stretch of coast, mean tide level which varies from place to place.**
- In this case: $MSL \neq LLD$





- **Mean Tide Level (MTL)**
 - Mean of all the HW's and LW's over a period of time and is area specific
 - MSL cannot be converted to MTL (or vice versa)
- **DO NOT CONFUSE ACTUAL MSL, WHEN $MSL = LLD$ and MTL**

- When tide is mainly diurnal the values of **MHHW & MLLW** are used in place of MHWS & MLWS
- MHHW
 - Mean higher high water
 - Average height of the higher of the two daily high water levels experienced over a period of time at a given location. When only one HW occurs in a day, this is taken as the higher high water.
- MLLW
 - Mean lower low water
 - Average height of the lower of the two daily low water levels experienced over a period of time at a given location. When only one LW occurs in a day, this is taken as the lower low water.



- Symbols used:
 - Z_{oo} = value of MSL relative to CD
 - Z_o = height of MSL above CD from individual analysis
 - S_o = height of MSL above zero of the tide gauge from an individual analysis
 - A_o = height of MSL above arbitrary datum, other than CD or the zero of observation

- Sounding datum (SD)
 - The low-water plane to which soundings are reduced and above which drying heights are given on a bathymetric sheet.
 - Datum that is established in the field by the surveyor

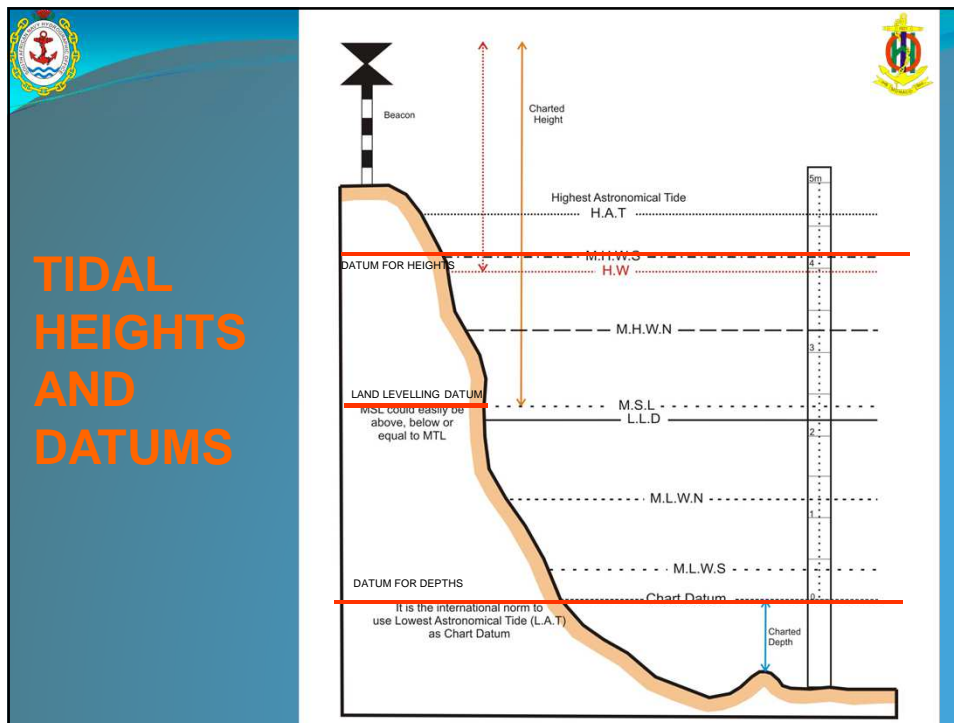
- Chart datum (CD)
 - The datum to which all soundings on large scale navigational charts of an area are reduced
 - The datum to which tidal heights are referred
 - Lowest astronomical tide in RSA
 - The water level will seldom fall below this level
 - Should vary gradually from area to area
 - Avoid errors of discontinuities with adjoining charts

- The surveyor **does not** establish CD in the field


- Lowest Astronomical Tide (LAT)
 - The lowest level of tide that can be predicted to occur under average meteorological conditions and under any combination of astronomical conditions.
 - This level may not be reached every year.
 - Calculated from 19 years worth of tidal predictions

- In RSA and United Kingdom: CD = LAT and is port dependent
- In USA: MLLW for Sounding and Chart Datum
- In Canada: CD= surface of Lower Low Water, Large Tide (LLWLT)
- THE IHO Has adopted LAT as Chart Datum



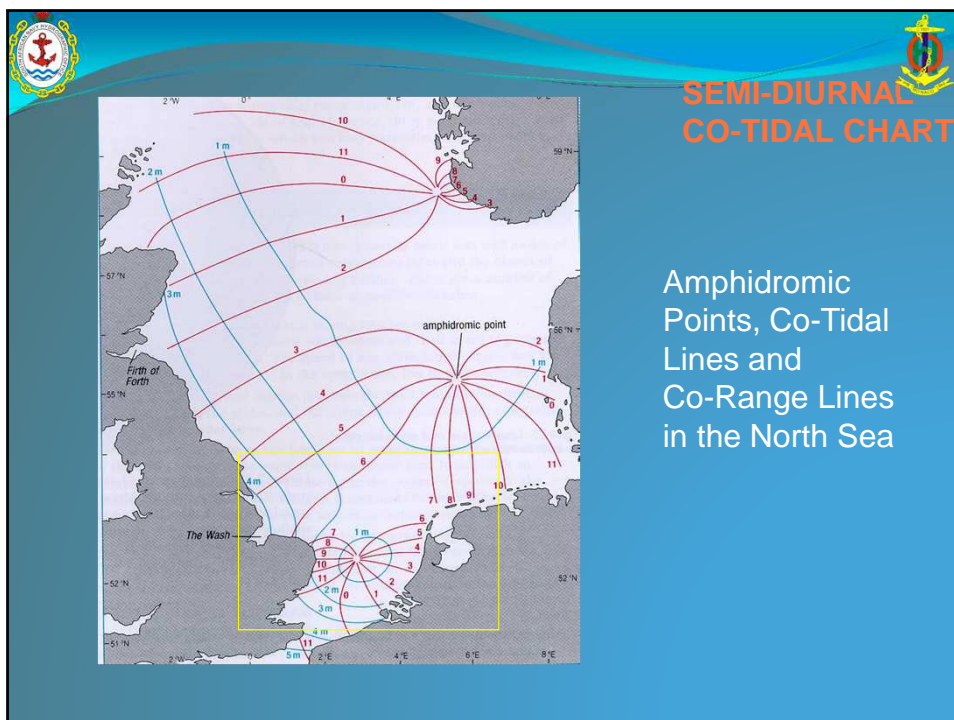
Co-Tidal Charts

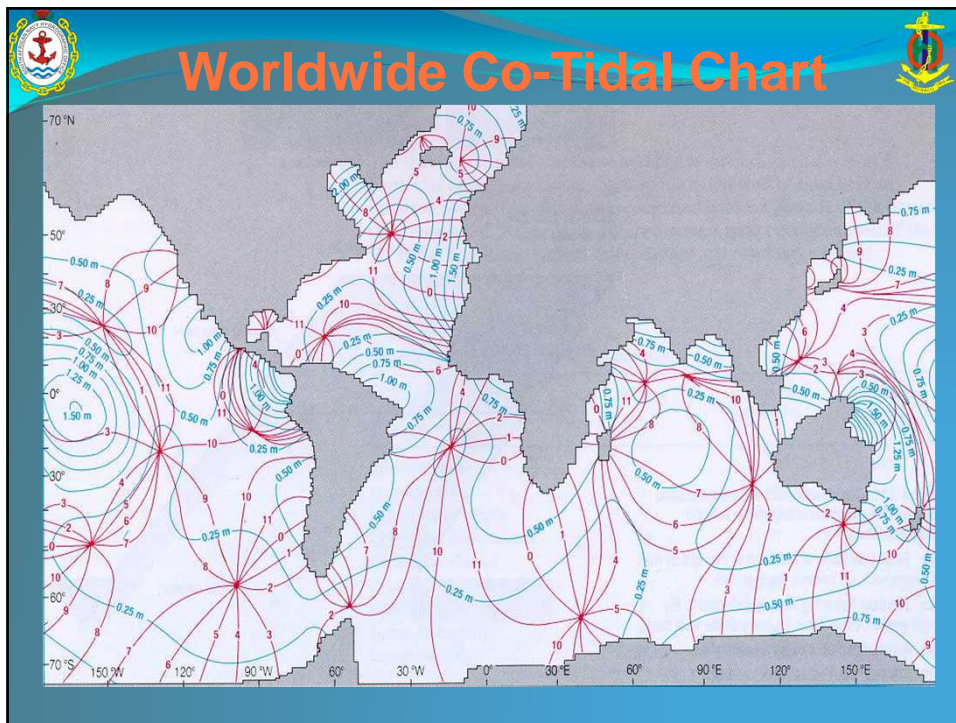
- Chart showing lines joining places having (say) HW at the same time, & joining places having equal tidal ranges.
 - Published co-tidal charts cover critical areas
 - Surveyor may construct his own from tide tables or own observations.
- Used to establish a datum at a point off-shore that is relative to a datum at a port ashore
 - Soundings obtained offshore can be reduced using tidal observations from the port ashore.
- Shows both **co-tidal** and **co-range** lines



- **Co-tidal lines**
 - Joins places at which HW (or LW) occurs simultaneously.
 - Needs careful definition (**read the fine print!!**)
 - Some charts show the line at intervals of 30° in the phase lag of the average tide (m_2) - hours of lunar time (lunitidal interval)
 - Some charts are in solar time



- **Co-range lines**
 - Joins places of equal range
 - Can be split to show lines of mean spring range and mean neap range.







Questions?

The slide features a blue background with a crest in the top right corner.



Observations Equipment and Procedures

Tides and Tidal Streams



Types of Tide Gauges

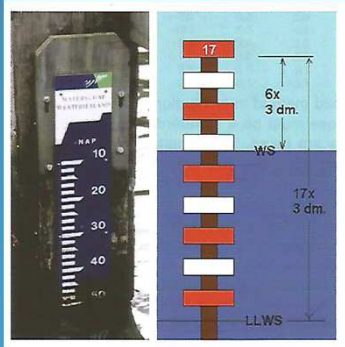
- A tide gauge (TG) is an instrument for measuring the height of the tide. Basic classification
- TG's divided into two groups:
 - Non-registering gauges which require the presence of an observer to take and record the height of the tide.
 - Self-registering or automatic gauges which automatically record the rise and fall of the tide while unattended.
- **Nowadays, manual readings by tide staff, probes and tapes are mainly used for frequent gauge/staff comparisons during deployment to assist in assuring measurement stability and minimizing processing type error**

Types of Tide Gauges

Level/ Tide Pole:

- Most commonly used in Surveys
- Read Manually by an observer
- Zero local Chart Datum

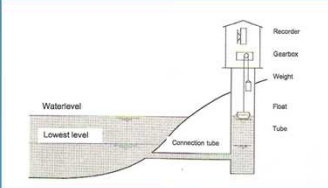
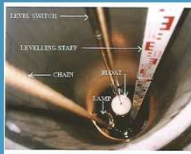
- **Advantages:**
 - Cheap, easy to install
 - Extremely common
 - Harbours, sluices, bridges
- **Disadvantages:**
 - Not automated
 - Needs to be near a tide gauge
 - Generally checked infrequently
 - Degrades level of accuracy




Float Actuated:


- Vertical tube with a float inside attached to a recording device.
 - Movement of float recorder by a stylus on paper or on an electronic sensor.
- Zero local Chart Datum

- **Advantages:**
 - reliable
 - accurate
- **Disadvantages:**
 - Biological and non- biological fouling
 - Regular cleaning required
 - Temperature variations
 - Inside and outside the tube


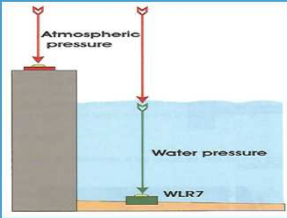







Pressure Gauge:




- Quartz pressure sensor or manometer
 - Measures height of water column above the sensor.
- Zero local Chart Datum
- Advantages:
 - Can be used in areas that have inaccessible locations and greater water depths
 - No structure above the water level
- Disadvantages:
 - Measured data **MUST** be corrected
 - Variations in atmospheric pressure and sea water density
 - Ambient atmospheric pressure
 - Separate pressure sensor on the surface
 - Source of errors.









Altimeter:




- Measures height of water level from a known point above the waterline
- Two types:
 - Measures up (Placed on sea bottom)
 - Inverted echo sounder
 - Measures above water to waterline
 - Laser, radar or acoustic.
- Zero local Chart Datum
- Advantages:
 - Can be constructed relatively easily
- Disadvantages:
 - Susceptible to noise.




Capacity type tide gauges:



- Measures height of water level in-between two iron bars
- Voltage applied over both bars
 - Creates resistance (capacity)
- The resistance (capacity) is different depending on if the bars have water or air between them.
 - Can be used to calculate water height
- Disadvantages:
 - Susceptible to salinity variations
 - Requires regular calibration and cleaning
 - Biological fouling.








My Tide Gauge

- How do I decide what gauge is best for me?
 - Research the different gauges on the market,
 - Speak to /email colleagues about their experiences,
 - Decide what type of gauge will be best for your environment,
 - Budget – expensive is not always better!
- If possible, try and bench test the equipment you want to buy
- Consider the costs of maintenance, upgrades/replacement, peripherals.






- Decide on a location for installation.
 - Effective planning and field reconnaissance is very important.
 - Physical Environment:
 - Is there swash/ oscillations?
 - Is there a benchmark network or will one need to be established?
 - Availability of benchmark data.
 - Are there existing structures I can use or will these need to be built?
 - Is there power available?
 - Local stability/ solar/ batteries
 - How will data be retrieved?
 - Landline/ 3G to an FTP site/ Manually

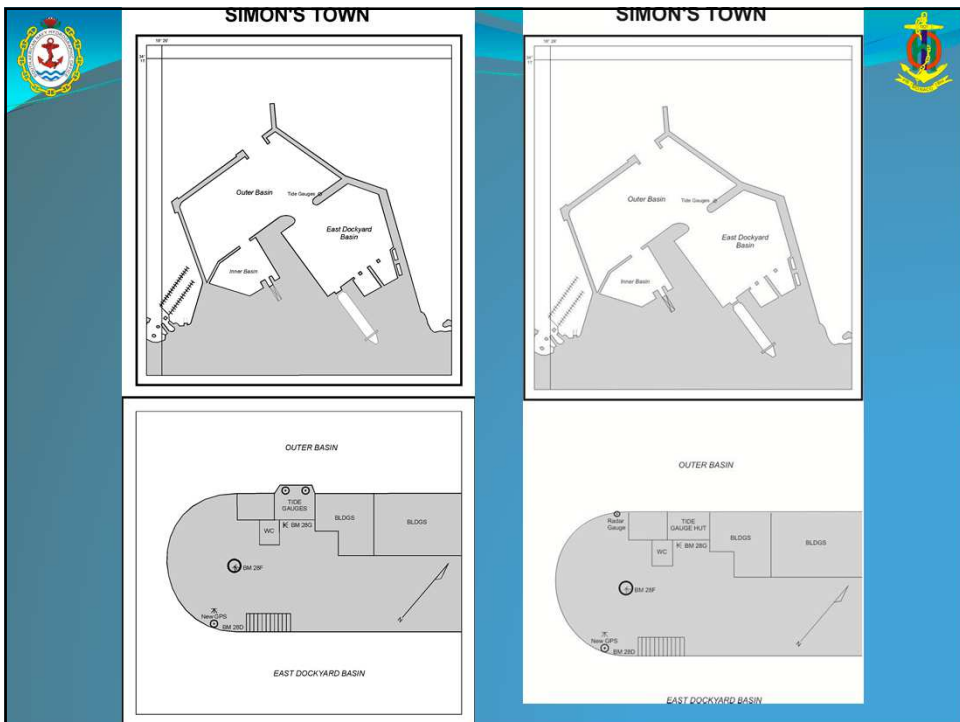






- Security of the equipment and the data?
 - Will access be restricted?
 - Are people able to tamper with the equipment
- Calibration and routine maintenance
 - How easy/ difficult will it be to service, calibrate, maintain?
 - Can this be done with one or two people or is a boat and crew required.
 - Is specialized equipment needed?
 - Lifespan of the equipment
 - Corrosiveness of the water/air
 - How often should the gauge be leveled and calibrated?
 - Minimum of once a year
 - High or low biological fouling?




- Each station must have its own file
 - Tide station report
 - Nautical chart section
 - Benchmark Sketch
 - Photographs of component parts and location
 - “To Reach” description
 - Benchmark descriptions and photographs
 - Leveling Records
 - Calibration records
 - Maintenance records



**LIGGINGSKETSJE VAN HOOGTEMERKE
LOCALITY SKETCHES OF BENCH MARKS**

Roete _____ Bladsy _____
Route _____ Page _____

Merk Mark SA WF 7 Graadvierkant Degree Square 3318 CD

Beskrywing Description KOTENKENS in SEMENT LAMIES PLAAR

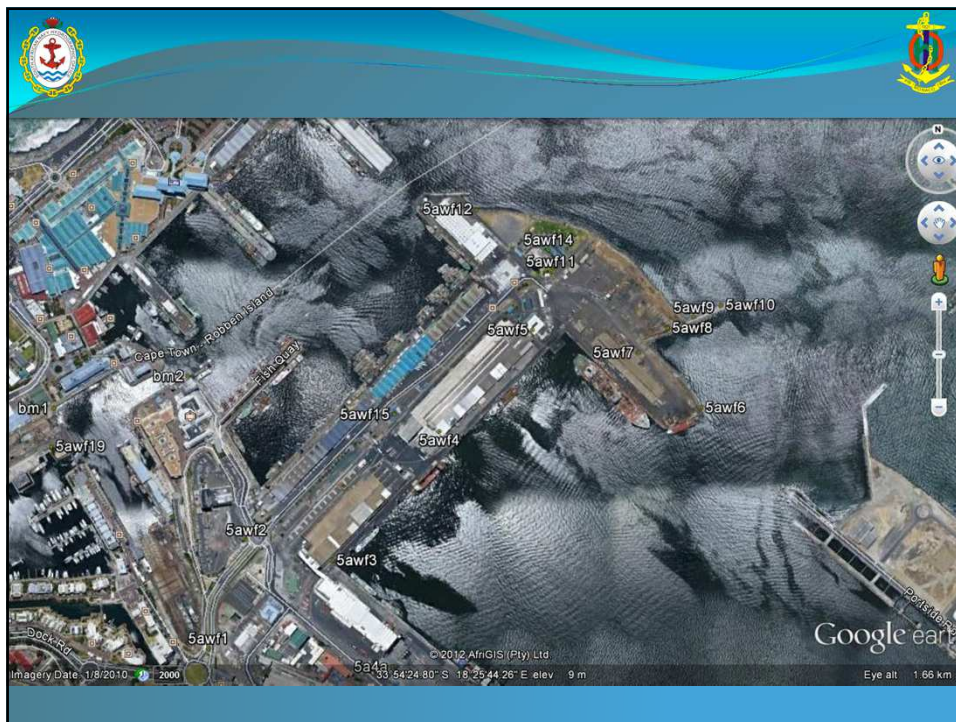
Datum Date 10/96 Geteken Signed _____


Merk Mark SA WFS, WFS, WFS Graadvierkant Degree Square 3318 CD

Beskrywing Description KOTENKENS in NETJES OP BRICKWARK MUR

Datum Date 10/96 Geteken Signed G.P. BOTTEMA


WFS - WFS 44,70m
WFS - WFS 68,57m





Durban

7 May 2011



Port Elizabeth

1. Upon Arrival, at approximately 1350h, borrowed the NSRI keys to get into the building. Removed the old antenna cable, replaced it with the new cable, and put up the new antenna. Put the GPS back up onto the roof. Satellite system is now back up and running.

2. Put in a new modem- was unable to check if the modem was working as cell phone cannot be used as a modem line at the moment. Upgraded the software and reprogrammed the logger.

3. Will calibrate and level on Monday 9 May as the weather has deteriorated and the wind is howling.

09 May 2011

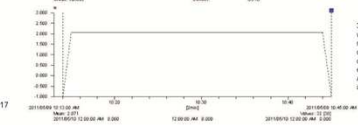
1. Upon arrival, put down short stay as the tide had not gone out enough to put down long. Met up with Vinesh from NPS and he handed over our new keys to the building. There is a lot of damp in the walls and some of the paint is blistering. Vinesh will get this sorted out.

2. leveled- results as follows:

| BM 493 | Tide Gauge |
|--------|------------|
| 1.7601 | 0.6431 |
| 1.7602 | 0.6431 |
| 1.7601 | 0.6431 |
| 1.7601 | 0.6431 |
| 1.7601 | 0.6430 |
| 1.7601 | 0.6431 |
| 1.7601 | 0.6431 |
| 1.7601 | 0.6430 |
| 1.7601 | 0.6430 |
| 1.7601 | 0.6431 |
| 1.7601 | 0.6431 |
| 1.7600 | 0.6431 |
| 1.7601 | 0.6431 |

Difference= 1.117

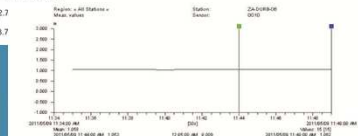
3. At long stay, readings from 1013B to 1045B gave an average= 2.071. This is 2mm l than what it should be.



4. Put down long stay at 1134h. Derek from Neotel (ex-transtel) was on site as the mc-27890 is still not connecting and has not since the cable was replaced. It appears that the protocols on 1.1210 the line may not be correct- I also spoke to Derek's boss, Andre and they will try to get the line sorted out ASAP.

Thus ref face = 3.9100
new CD = 0.9130
Height of ref face above CD = 4.8230

5. At long stay, readings from 1134B to 1149B gave an average= 1.056. This is 15mm lower than what it should be and will need to be monitored. No adjustments were made to the reference level.






1. TG should read @ short stay = 4.423 - (2.7) = 2.073m
2. TG should read @ long stay = 4.423 - (3.7) = 1.073m


17 May 2007

1. Upon arrival, noticed the structure that was going to be used to secure the antenna to had been removed. Spoke to Harry Casson and he said it was ok to secure the antenna to the side of the quay above the hut door.

2. Put up the antenna with rail bolts. Drilled a hole through the door frame to feed the antenna cable and GPS cable through.

3. Installed the HDR and checked that everything was grounded as per instructions from PCL. Put in the new LOGOSENSZ that was pre-programmed at the office. This unfortunately led to the CSIR/NSRI connection being lost, however the wiring and modems etc belonging to CSIR are still plugged in and working. All the lights on the HDR did as they were supposed to and the transmission light was on for the required time.




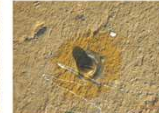
4. (total of 120 readings)

mission had gone and the LOGOSENSZ was not the LOGOSENSZ and the plate of the


5m 1355: to 1410 (total of 156 readings)

6. No transmissions since the reprogram and none since. I checked all connections and wiring as well as the power and antenna direction. The antenna cable had come loose and after tightening it up tightly, transmissions started coming through as they should have been all along.


7. Took photographs of all the benchmarks on the quay near the tide gauge. Images are taken from the town to the tide gauge.

11. Will leave the settings as they are for now.



Installing A Radar Type Tide Gauge





Leveling the Transducer






- The transducer needs to be level on the davit
 - Spirit level








- After Installation:
 - Gauge must be levelled into local benchmark network and a reference level programmed into the logosens.
 - Must know
 - Exact height of benchmarks above LLD
 - what LLD is.
- In RSA LLD = MSL = 0
 - Anything above MSL is height or elevation
 - Anything below MSL is a depth.
- Thus benchmarks are heights above MSL
- CD is LAT \therefore CD is a value below MSL
 - Durban CD is MSL – 0.913







- So a benchmarks height can be converted to a height above CD
 - Height of benchmark above MSL + CD for the port
 - $A + C = B$

- Identify benchmarks and check their location with a site map (left)
- Benchmark heights can be obtained from
 - Land Surveyor
 - Town Planners Office
- WF9 = MSL + 2.331m
- WF10 = MSL + 2.343m
- NEW GPS = MSL + 2.329m

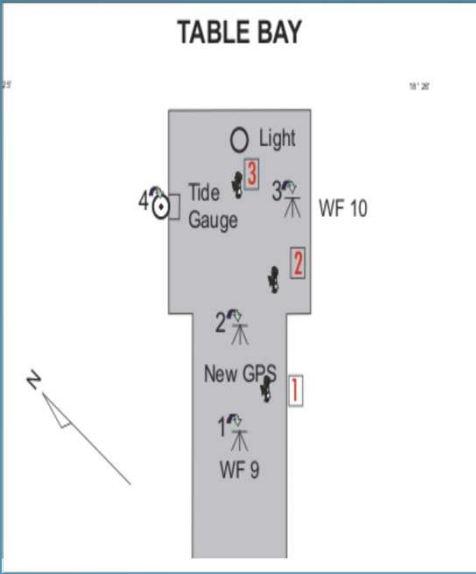



- The tripod, with dumpy, must be positioned $\frac{1}{2}$ way between each benchmark.
- The tach staff will be placed (level) on the benchmark stud






- Surveyor stands at positions **1, 2 & 3**
- Person holding the tach staff places it on the benchmarks marked 1, 2, 3 & on the tide gauge transducer at 4



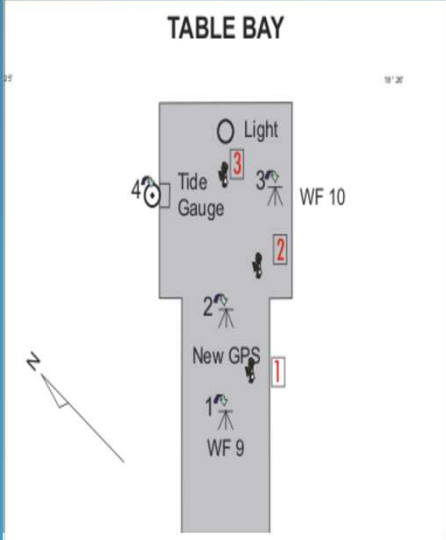
- You stand at 1
 - Assistant at 1
 - Take readings
 - You turn, without moving the tripod, to 2
 - Assistant moves to 2
 - Take readings
- You move to 2
 - Assistant stays at 2, turning to face you without lifting the tach staff off the benchmark stud
 - Take readings.



- You turn, without moving the tripod, to 3
 - Assistant moves to 3
 - Take readings
- You move to 3
 - Assistant stays at 3, turning to face you without lifting the tach staff off the benchmark stud
 - Take readings.







- You turn, without moving the tripod, to 4
- Assistant moves to 4
 - Take readings
- Repeat this process “leap-frogging” back to where you will be taking reading with the tach staff on position 1
- If correctly done:
 - Forward = backward
 - Σ forward readings –
 - Σ backward readings = 0

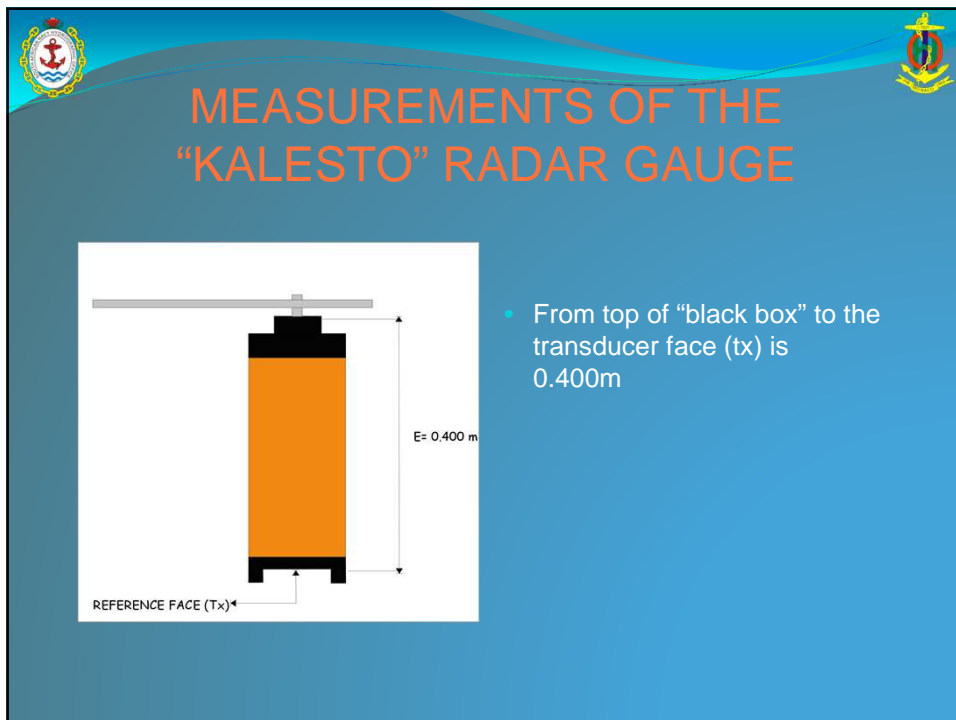
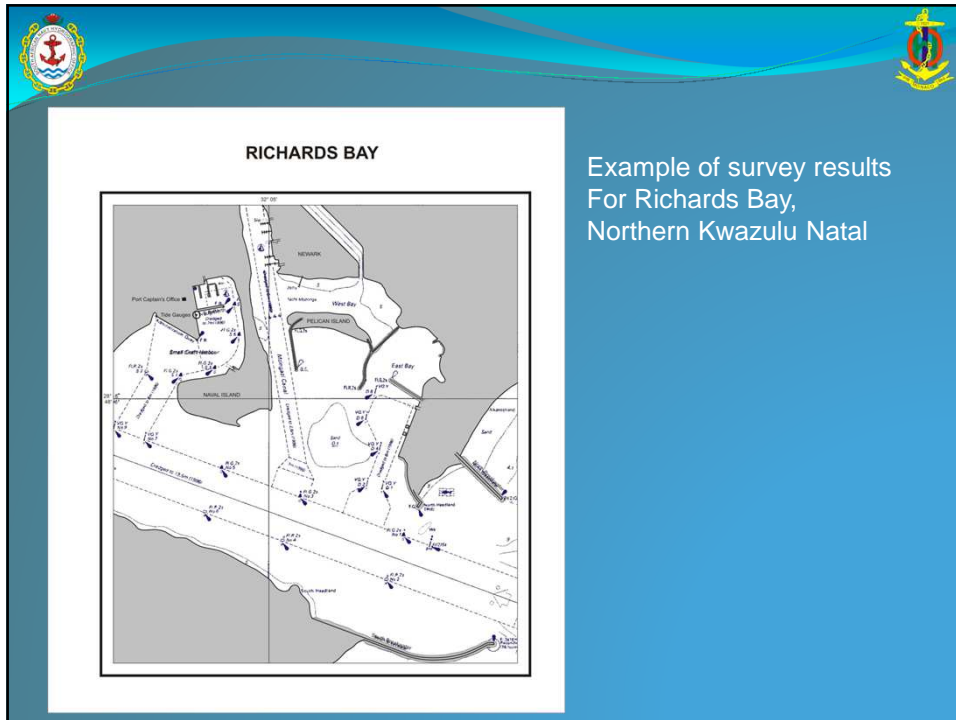
TABLE BAY



- When placing the tach staff on the transducer
 - Always place it on the “black box”
 - Never on the bracket.
- You can get the STD tach staff (1)
 - Graduations that can be read off manually
- And the electronic tach staff (2)
 - barcoded



SURVEYING AND CALIBRATION

Handwritten notes and calculations for a surveying instrument:

- All 50x50x6mm SS 316 Grade: or ELMIS material (Gross Part 522+255) uni decim
- 4 of 1.8m = 8.2m = 1 x 6m
- 2 of 1.5m = 4.2 = 1 x 6m
- 2 of 0.7 = 1.4 = 1 x 6m
- 2 of 0.8 = 1.6 = 1 x 6m

Total length: 15.0m @ 146.64/m + VAT = R3000.05



Notes: All Plans can be found by FMA; 10 x UPAT vs E's; 13.07 cu; 10 x 50 bolts; 10 mm x 20; 3.07; 30; 43.70; VAT 1845.35; From Bolt Nut; 08 Goodwood Kempfroude; Tel: 534 5576

Diagram labels: 1500m, 0.600m, 1.200m, 50x50 angle, 90+80° angle, 16 mm diam hole, ball, ball, ball, ball, ball.

"KALESTO" RADAR GAUGE IN SITU (Richards Bay)




Two photographs illustrating the "KALESTO" radar gauge:


- The left photograph shows the radar gauge mounted on a metal structure on a pier, secured with orange ropes. The gauge is a yellow and black cylindrical device.
- The right photograph shows the radar gauge in situ, mounted on a wooden structure over the water. The gauge is a yellow and black cylindrical device.

"KALESTO" RADAR GAUGE

Platform For Easy Access To Gauge During Leveling And Calibration. (Richards Bay)



Calibration rods



Richard's Bay



East London

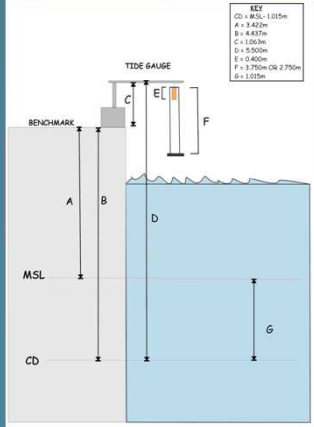


Knysna



Simon's Town

Calibrating a Radar Gauge



- Example of a calculation for check calibration of radar gauge, if
A= 3.422m (known value for local benchmark)
- Av. A above CD = Av B

Av A = MSL + 3.422

Δ (D-B) = + 1.063

less E to Tx = - 0.400

∴ Ref Face = MSL + 4.085

CD = MSL - 1.015

+5.100

∴ Ht of Tx = 5.100m above CD

∴ readings @ short stay:
5.100 - (2.750 - 0.400) = 2.750m

∴ readings @ long stay:
5.100 - (3.750 - 0.400) = 1.750m

| SCH3 | SAN84.2 | Tide Gauge |
|--------|---------|------------|
| 1.7207 | 1.7271 | 0.6649 |
| 1.7207 | 1.7271 | 0.6649 |
| 1.7207 | 1.7271 | 0.6649 |
| 1.7208 | 1.7271 | 0.6649 |
| 1.7207 | 1.7271 | 0.6649 |
| 1.7207 | 1.7271 | 0.665 |
| 1.7207 | 1.7271 | 0.6649 |
| 1.7206 | 1.7271 | 0.6649 |
| 1.7207 | 1.7270 | 0.6649 |
| 1.7207 | 1.7271 | 0.6649 |
| 1.7207 | 1.7271 | 0.6649 |
| 1.7207 | 1.7271 | 0.6649 |
| 1.7207 | 1.7271 | 0.6649 |

Difference A2 = 1.0558


Difference A1 = 1.0622



| | SCH3 | SAN84.2 |
|-----------------------------|---------|---------|
| Height of Bmark above MSL | 3.4290 | 3.4220 |
| Diff B/Box and Bmark | 1.0558 | 1.0622 |
| Less: to Tx Face | -0.4000 | -0.4000 |
| Thus ref face = | 4.0848 | 4.0842 |
| new CD | 1.0150 | 1.0150 |
| Height of ref face above CD | 5.0998 | 5.0992 |

AV= 5.0995

∴ TG should read @ short stay = 5.0995 - (2.750-0.400) = 2.7495m

∴ TG should read @ long stay = 5.0995 - (3.750-0.400) = 1.7495m







| Tide G | Tide Gauge |
|--------|------------|
| 1.7383 | 0.6498 |
| 1.7383 | 0.6498 |
| 1.7384 | 0.6498 |
| 1.7383 | 0.6498 |
| 1.7383 | 0.6492 |
| 1.7382 | 0.6492 |
| 1.7382 | 0.6498 |
| 1.7382 | 0.6498 |
| 1.7383 | 0.6498 |
| 1.7386 | 0.6497 |
| 1.7383 | 0.6497 |
| 1.7383 | 0.6497 |
| 1.7384 | 0.6497 |
| 1.7383 | 0.6497 |

Difference= 1.0886

| | Tide G |
|-----------------------------|--|
| Height of Bmark above MSL | 2.8120 |
| Diff B/Box and Bmark | 1.0836 (minus 5mm for calibration plate) |
| Less: to Tx Face | -0.1170 |
| Thus ref face = | 3.7786 |
| new CD | 0.9130 |
| Height of ref face above CD | 4.6916 |

∴ TG should read @ short stay = 2.0586m
 ≈ 2.059m
 ∴ TG should read @ long stay = 1.0586
 ≈ 1.059m



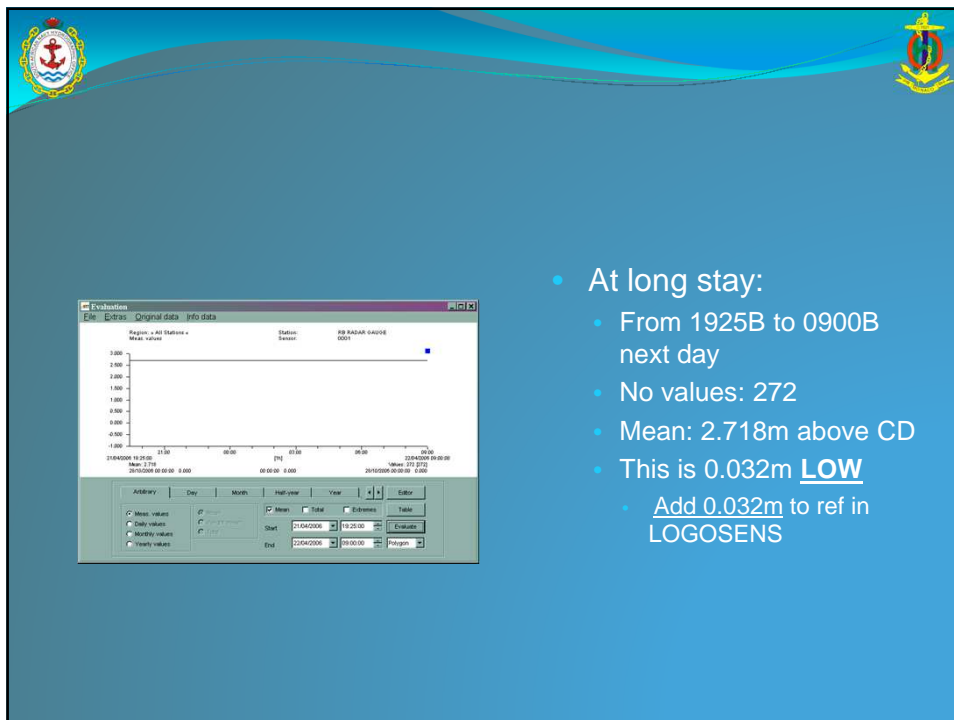
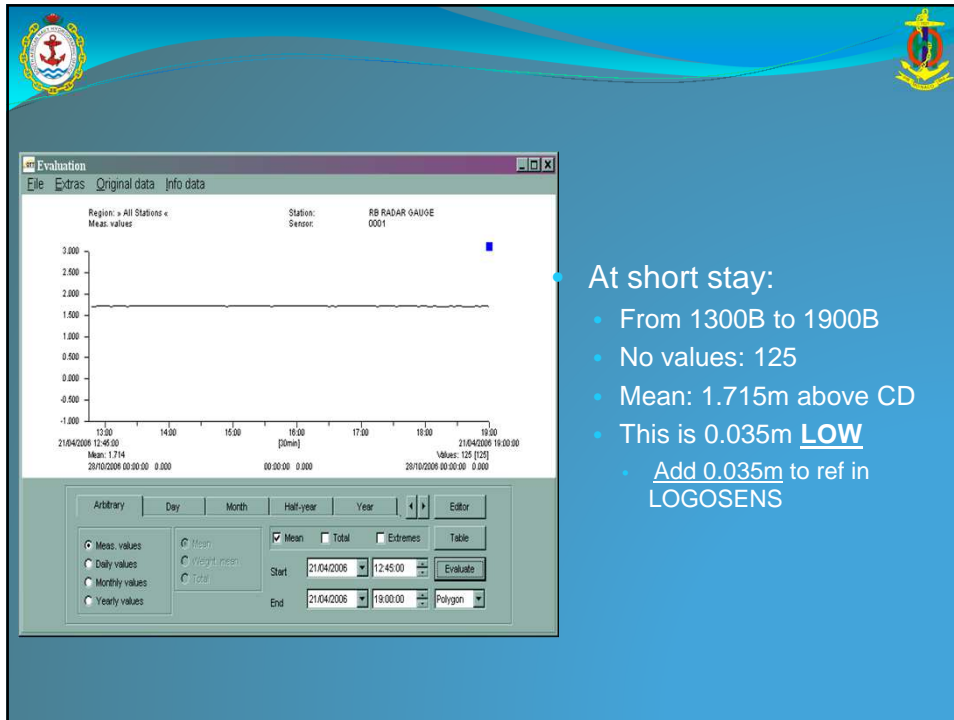


CALIBRATING THE "KALESTO" RADAR GAUGE





- Program the reference level into the LOGOSENS
 - With USB or RS232 cable
 - Create station in the office before departure to the installation site.
- "Play" with the software




- After resetting the reference level in the LOGOSENS
- At long stay:
 - From 0935B to 0955B
 - No values: 7
 - Mean: 2.753m above CD
 - This is 0.003m **HIGH**
 - This 3mm is perfectly acceptable to be out by.

- This is how the previous information would be displayed once it is downloaded for a longer period of time.
- Calibration records are digitally stored in this method.

SOME USEFUL TIPS

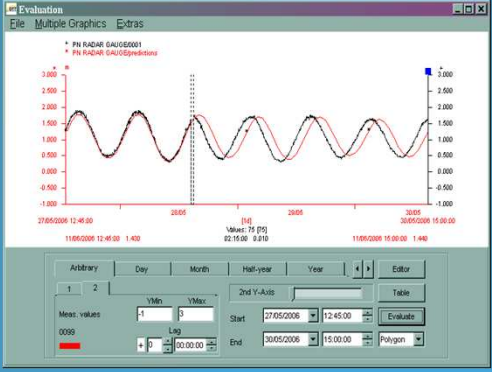
- Always print weekly graphics.
 - Errors can be noted and corrected timeously
 - Battery not working
 - No power
 - Telephone lines down
 - Assists with analysis of tides
 - Shows “spikes” very clearly.
- Insert your predictions into the software program, if possible
 - Check accuracy of your predictions
 - Overlay actual and predictions
 - Can pick up time/ clock errors timeously

EXAMPLES OF HYDRAS3 GRAPHICS



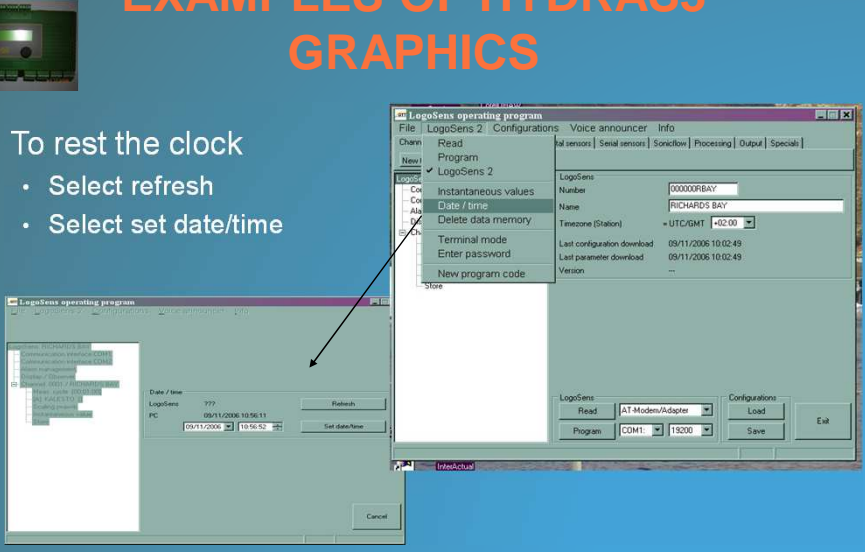
- No power, battery has not “kicked” in
 - Data lost.

EXAMPLES OF HYDRAS3 GRAPHICS

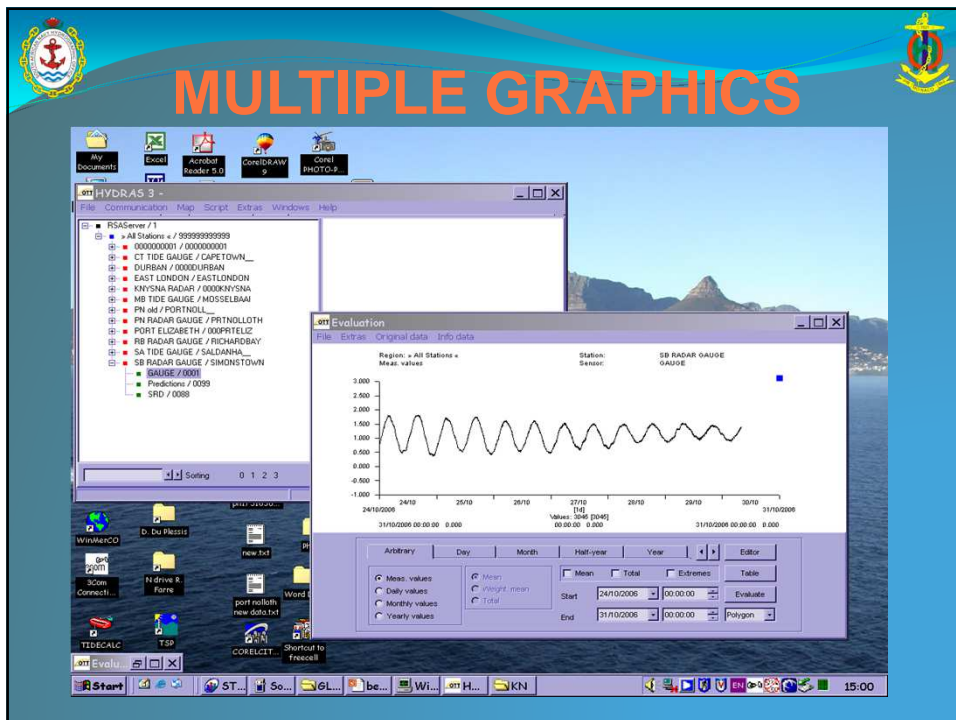
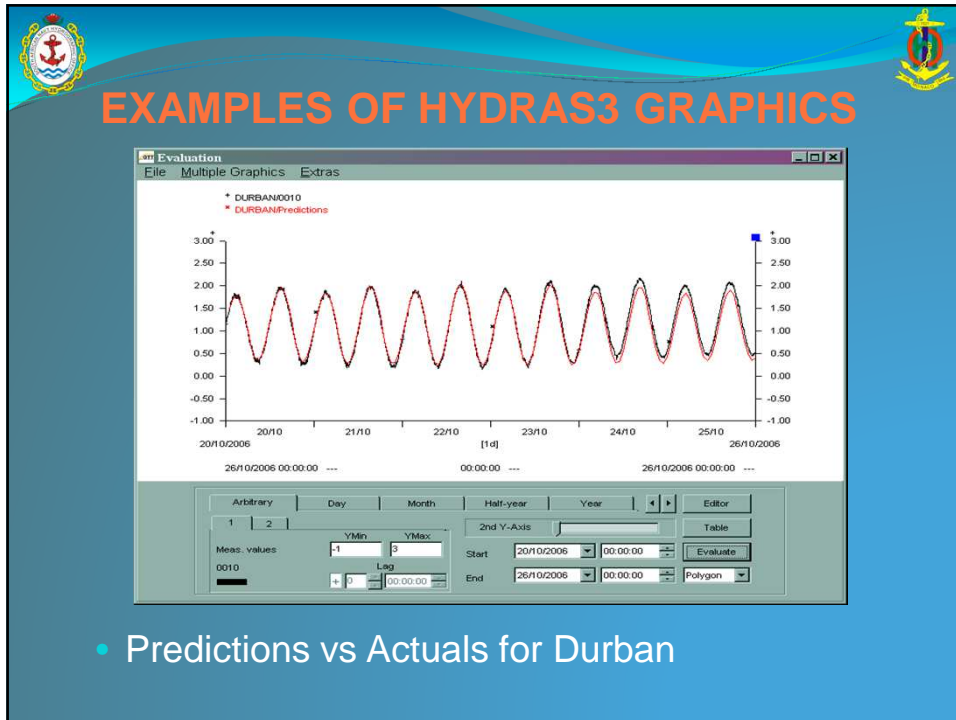


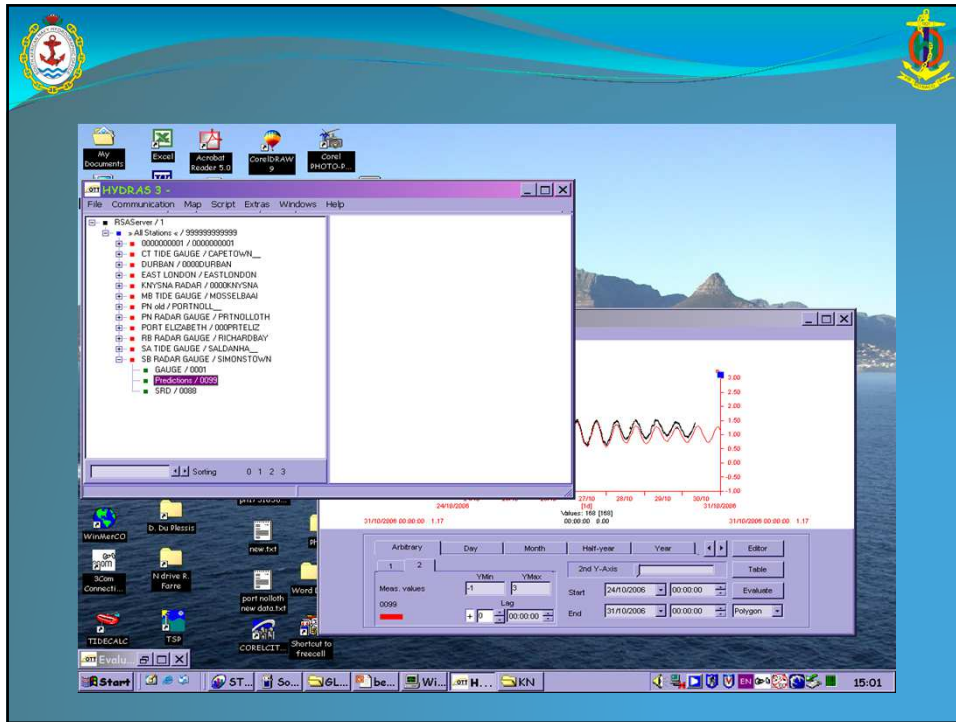
- No power, battery has not “kicked” in
 - Data lost.
 - Clock stopped ∴ data out of phase
- Reset clock immediately!
- Data will have to be manually moved back into phase

EXAMPLES OF HYDRAS3 GRAPHICS



- To rest the clock
 - Select refresh
 - Select set date/time

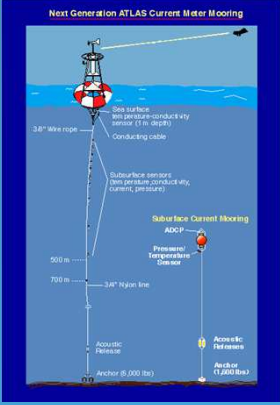






Questions?

Measurement of Tidal Stream

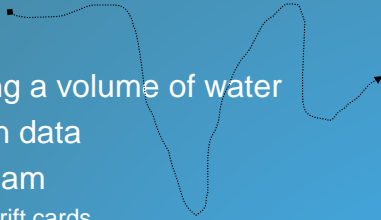



- Tidal stream or current observations require careful planning and application if the results are to be reliable
- Traditionally
 - Tidal stream measuring is uneconomical
 - Even if the greatest care is taken, the resulting stream prediction will **never** be as accurate as vertical tide predictions
- Trend in equipment is towards instruments that permit continuous data with the ship underway
 - Buoy-moored current meter



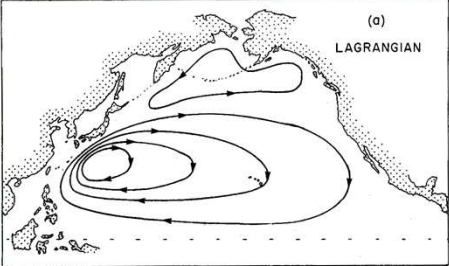
- Ideally
 - Measurements made hourly or ½ hourly for lunar month (29 days)
 - This is for buoy moored current meters
- In practice
 - Obtain a minimum of 25 hour/ ½ hour intervals
 - Weather should be good (i.e. several days of low winds)
 - At springs (streams are strongest and errors will be minimized)
 - Repeat at a time other than springs

- Measurement techniques fall into two categories
- Lagrangian
 - Labeling and tracking a volume of water
 - Physical observation data
 - Moving with the stream
 - Pole logship. Dyes, drift cards
- Eulerian
 - Monitoring flow past a point
 - Current meter

(a)
LAGRANGIAN



Lagrangian v. Eulerian Descriptions

(b)
EULERIAN

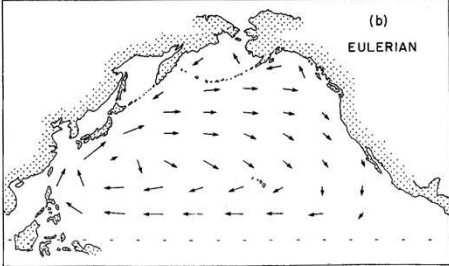


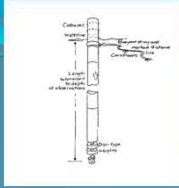




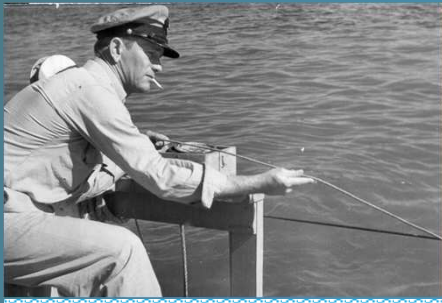
FIG. A.4 Flow pattern described in (a) Lagrangian manner (flow lines), (b) Eulerian manner (velocities at points).

Pole Logship





- Pole logship can be either free-floating or tethered
 - Gives average flow rate
 - Direction over pole depth
- Disadvantages:
 - Immobilizes ship or boat and personnel for long periods of time
 - Handling problems
 - High accuracy fixing required
 - Inaccurate results
- Logship usually 15-30 ft long
 - Weighted so that it floats upright (only a few inches above surface to reduce wind resistance)
 - Top of pole fitted with small light and cats eyes (for tracking at night)



Pole and log-line

Z



Tethered logship

- Pole attached to ship by buoyant line (first 15-30m unmarked, rest marked as for a lead-line)
- Precise method for measuring vessels position required
- Allow logship to drift away from vessels influence
- At zero of logline, start stopwatch, fix vessel
 - Note bearing of logship, ship's head and amount of line out
- After 1-2 min, stop stopwatch, fix vessel
 - Note bearing of logship, ship's head and amount of line out
- Obtain 3 sets of observations in quick succession
 - Note meteorological conditions
- Plot all 3 runs and combine to obtain mean rate and direction of flow



Free-floating logship

- The same pole can be used, without the distance line and marked with a small buoy
- The logship is released and it's position fixed.
 - NB the boat must not approach the logship too closely
- Re-fix the logship 2 or 3 times at regular intervals
 - Take time to the nearest second
- Recover the logship and repeat the sequence once or twice more.
 - Note the meteorological conditions
- Plot fixed positions of the logship
 - Calculate the rate and direction for each run and average
 - Refer average to mean time of observations
- Can be tracked by high-definition radar

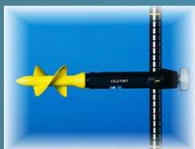
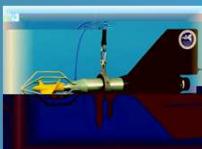

Flow Meters



- A current meter is the most versatile method of measuring rate and direction of flow at any depth (even in deep oceans)
- May be ship-tethered, bottom- or structure- mounted or buoy-moored
- Readout is either direct to a control unit on the ship, or remotely recorded within the meter
- Meters in use today employ one of 3 methods for measuring rate and direction
 - Impeller or rotor
 - Electromagnetic current meter
 - Acoustic Doppler Current Profiler (ADCP)



Impeller or rotor


- The impeller rotates in the current at a speed proportional to current rate
 - Vane on the instrument keeps it facing current flow.
- Pulses sent to the control unit
 - Current rate displayed in knots or m/s
 - Direction is sensed by aircraft type magnetic compass
- Dnc-3n current meter
 - Measures direction and velocity
 - Underwater unit consists of 3 parts
 - Nose cone
 - Rear tube
 - Fin/ impeller guard assembly





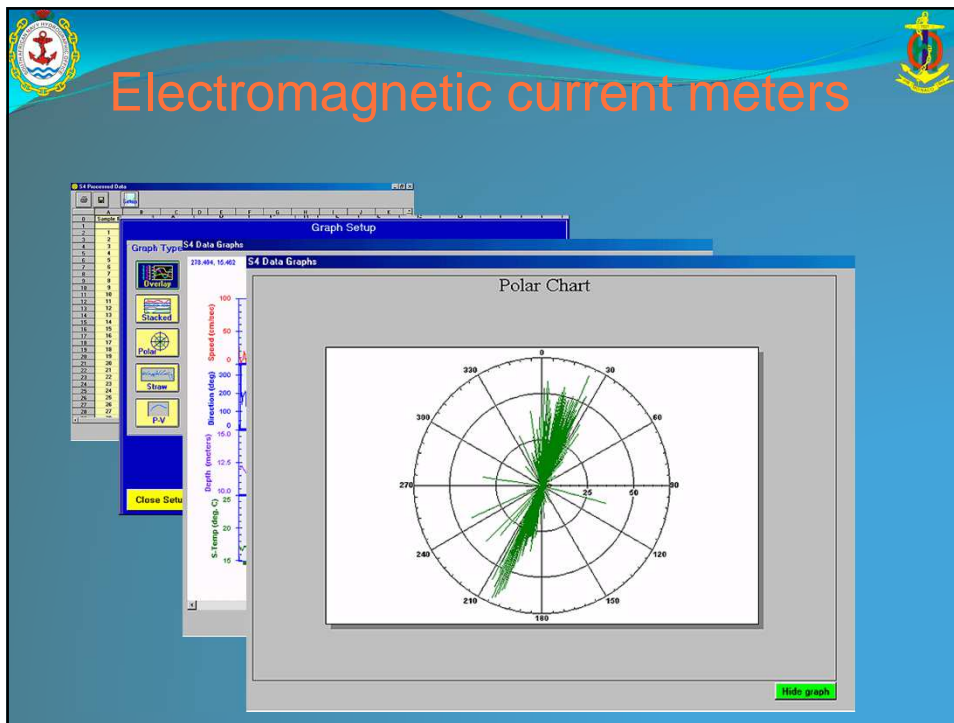
- Surface unit consists of
 - All electronics and display units
 - Interconnecting cable is of oceanographic type
 - Combines function of strain cable and data transfer
- DNC-3N individual parameters
- Direction
 - Determined by precision double mounted compass
 - Sample rate 3X/second
 - Resultant digital signal converted to analogue, transmitted to surface
- Velocity
 - Impeller magnetically coupled to an optical sensing mechanism which converts the rotation to an electrical signal
- For greater accuracy atmospheric pressure compensations should be applied to all readings





- Electromagnetic current meter
- No moving parts
 - No risk of interference by floating debris
- Use faraday's law of electromagnetic induction
 - Law of relating the electromotive force (emf) induced a circuit to the change in magnetic flux threading it
 - $\varepsilon = -D\phi/dt$
 - ε : Electromotive force, ϕ : Magnetic flux, t : Time
- A polar co-ordinate vector is obtained which represents the flow rate and direction







- Acoustic Doppler Current Profilers (ADCPs)
- There are no moving parts
- Can measure up, down or sideways
- Configuration of transducers to examine doppler frequency shifts
- Doppler effect
 - The apparent change in frequency of a sound wave received, with respect to the frequency emitted, when the source and receiver are in relative motion
 - Example: train whistle

The image shows a photograph of an Acoustic Doppler Current Profiler (ADCP) sensor. It is a cylindrical device with a blue top and a white body, mounted on a metal pole. The sensor is used for measuring water current velocity and direction.

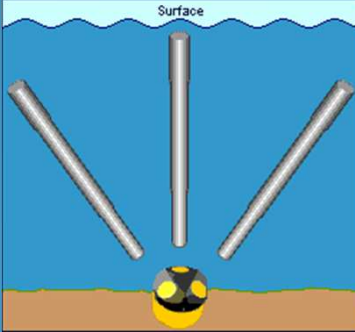
- ADCP uses the doppler effect by transmitting sound at a fixed frequency and listening to echoes returning from sound scatterers in the water
 - Sound scatterers are small particles or plankton that reflect sound back to ADCP.
 - On average they move at the same horizontal velocity as the water
- Sound scatterers scatter sound in all directions
- Most of the sound goes forward
- The small amount that reflects back is analysed for its doppler shift.

Acoustic Doppler Current Profilers

Example shows the display of data corresponding to the various depth cells within the water column. Each depth cell contains the average of the data collected by a series of transmitted sound pulses ("pings").

- (a) Several pings are transmitted by the ADP each second.
- (b) Pings are reflected back to the ADP after bouncing off particulate matter in the water.
- (c) Pings are processed (i.e. "averaged") by the ADP for recording and display.



| | Current Speed | Current Direction |
|----|---------------|-------------------|
| 1m | | |
| 3m | | |
| | 0 cm/s | 10° 30° |

Velocity accuracy:

- 1200, 600: $\pm 0.25\%$ of the water velocity relative to the ADCP $\pm 2.5\text{mm/s}$
- 300: $\pm 0.5\%$ of the water velocity relative to the ADCP $\pm 5\text{mm/s}$

Velocity resolution: 1mm/s
 Velocity range: $\pm 5\text{m/s}$ (default); $\pm 20\text{m/s}$ (maximum)

Compass (fluxgate type. Includes built-in field calibration feature)

- Accuracy: $\pm 2^\circ$
- Precision: $\pm 0.5^\circ$
- Resolution: 0.01°



OVER 1,000 NOW OPERATING—WORLDWIDE

IT'S WHAT INSHORE SURVEYORS ASKED FOR

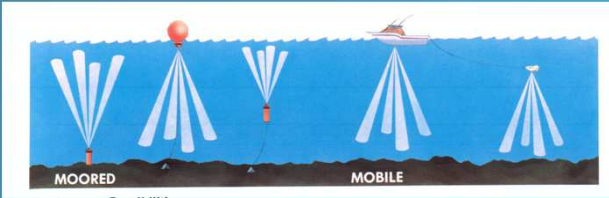


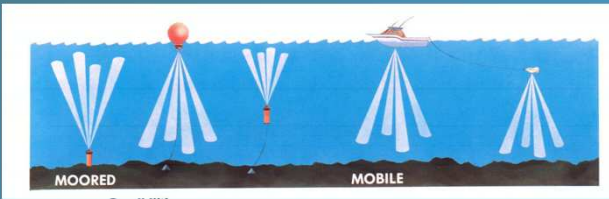
PATENTED!

GREAT RANGE, LOW INSTALLATION COSTS



| Frequency | Range | Cell Size |
|-----------|-----------|-----------|
| 38 kHz | 800-1000m | 24m |
| 75 kHz | 560-700m | 16m |
| 150 kHz | 380-425m | 8m |



- Multiple Beams
- ADCP using multiple beams pointed in different direction it senses different velocity components
- Trigonometric relations can convert current speed into compass components
 - One beam is required for each current component
 - \therefore To measure 3 velocity components (eg E, N, + UP), there must be at least 3 acoustic beams
- Four beams are used in the “Janus Configuration”

- Deployment possibilities for ADCP
- Fixed on a stationary platform
- Suspended on a mooring
- Housed in bottom frames
- Attached to surface buoys
- Towed behind or mounted on a vessel (surface or submerged)

- Remote sensing
- Radar backscatter
 - Commercial VHF and HF radar backscatter system
- Experimental systems- military radar
 - Shows benefits of a long range horizontal coverage possible
- Variety of systems available
- Interpretation is not simple
 - Inter-comparisons between radar and drifter measurements are important
- Radar yields excellent information
 - Only surface movement is detected
 - Wind-driven surface currents can be obscured by tidal flow

- Satellite observation
 - Of ocean currents and wind have long been sought
 - Laboratory developments of radar backscatter models to satellite measurements needs more observations.

transmitted wave

backscattered wave

HF-Radar Antenna

$\lambda_m = 10 \text{ m}$

$\lambda_m = 5 \text{ m}$

50

40

30

20

10

0

-1 0 +1

Hz


Hz

First Order Peak


Second Order Peak

Doppler Shift at no Relative Current






Tidal Analysis and Predictions



- The term tides can be defined as being **periodic** movements, which are directly related in **amplitude and phase** to some **periodic** geophysical force.
 - The emphasis of the definition being on the **periodic** and **regular** nature of the motion.
 - Each tide reading can be thought of as an observation for which an equation can be written.

- The unknowns are the values of mean sea level , h and g for each constituent.
 - Provided that there are more observations than unknowns it would be possible to solve the set of simultaneous equations by least squares analysis and derive values for the unknowns.
 - In theory a solution for MSL and the four primary constituents should be possible from ten or more tide readings.
 - In practice this would be the equivalent of fixing a position with three virtually parallel position lines, so data for a much longer period is required.





- Movements due to the regular movements of the moon-earth and earth-sun systems are called **gravitational tides**.

- The smaller movements due to regular meteorological forces, which are called **radiational tides** because they occur at periods directly linked to the solar day.


- Any sequence of measurements of sea level will have a tidal component and a non-tidal component.

- The non-tidal component which remains after analysis has removed the regular tide is called the **meteorological surge residual** (usually referred to as a surge).







- Tidal analysis of data collected by observations of sea levels (and currents) has two purposes:
 - A) A good analysis provides the basis for predicting tides at future times.
 - B) The results of an analysis can be interpreted scientifically in terms of the hydrodynamics of the seas and their responses to tidal forcing.
- The process of analysis reduces many thousands of numbers, eg: a year of hrly sea levels consists of ± 8760 values, which contain the soul or quintessence of the record (Godin 1972).



- In tidal analysis the aim is to reproduce significant time stable parameters which describe the tidal regime at the place of observation.
 - Should be in a form suitable for prediction,
 - Should be related physically to the process of tide generation
 - Should have some regional stability.
- The parameters are often termed **tidal constants** on the implicit assumption that the responses of the oceans and seas to tidal forcing do not change with time.
- Also implicit in the use of this term is the assumption that if a sufficiently long series of levels is available at a site, then a true value for each constant is obtained by analysis.



- The longer the period of data available for analysis, the better will be the approach to the true value,
 - Except in places subject to natural or man-made changes in the topography.
 - At such places the tidal "constants" obtained from analysis of a long period may have changed during that period.
 - An extreme example is the building of the causeway connecting Singapore to Johore, which actually reversed the direction of streams in the Johore Strait.
 - Less dramatic, but still significant, changes can occur as a result of dredging or natural shifting of sand banks.





- The close relationship between the movements of the moon and sun, and the observed tides, makes the lunar and solar co-ordinates a natural starting point for any analysis scheme.
- The **equilibrium tide** defines a tidal level at each point on the earth's surface as a function of time and latitude.
- The observed tides differ very markedly from the equilibrium tide
 - Real depth and boundaries.
 - In shallow water the tides are further distorted by the loss of energy through bottom friction and the preservation of the continuity of water flow.
- However, LaPlace's principle, states that: "the frequencies inherent in a forced system, however damped, show the same frequencies as the forcing system".

The diagram illustrates the relationship between tidal forcing and response. It shows two parallel paths starting from 'FORCING SYSTEM (TIDE RAISING FORCES)'. The top path goes through a box labeled 'Hypothetical Ocean (Perfect Response)' to 'EQUILIBRIUM'. The bottom path goes through a box labeled 'Ocean Basins (Damped Response)' to 'REAL TIDE'. The word 'TIDE' is positioned to the left of the top path.



- The observed real tides have their energy at the same frequencies as the equilibrium tide.
 - The NB of the equilibrium tide lies in its use as a **reference** to which the observed phases and amplitudes of harmonic tidal constituents can be related, when preparing models for tidal prediction.
 - It also gives an indication of the important harmonic constituents to be included in a correct tidal analysis model.

- Typically performed on observed hourly height time series to obtain amplitude and phase of each tidal constituent
- Four basic processes
 - Initial separation of individual constituents from the observations
 - Orientation of the constituent tides with the astronomical elements (tidal potential)
 - Nodal factor adjustment
 - Elimination from each constituent the effects of other nearby tidal constituents
- Two types typically used:
 - Fourier Analysis – usually used for short time series (less than 29 days)
 - Least-squares Analysis – usually used for time series > 180 days

Analysis of Tidal Stream Data

- Two methods for analysis of tidal stream data
- Harmonic analysis
 - Similar to that used for the vertical movement of tides
 - 25 or 50 hourly observations have been obtained only the four main tidal constituents can be determined
- Semi-graphic methods
 - Maintain an empirical relationship between tidal stream at a place and the tide at a suitable std port.
 - Cannot handle diurnal inequalities in tidal stream
 - Assumes the stream is purely semi-diurnal

Prediction

- This is the easy part...
- Where the tide has been analysed it is possible to predict the tidal height at any time by evaluating the tidal equation for all known constituents.
- The tide tables publish data for mean sea level, the four primary constituents, M_2 , S_2 , K_1 and O_1 and quarter and sixth diurnal shallow water constituents, in part iii.
- The astronomical data from table vii is an adjustment of the pure data for the four primary constituents to take account of the effect of a further 20 constituents.
- The shallow water data is not for true constituents but describes the effect in relation to the amplitude and speed of the combination of M_2 and S_2 .

