

# Arctic Hydrographic Reconnaissance Project

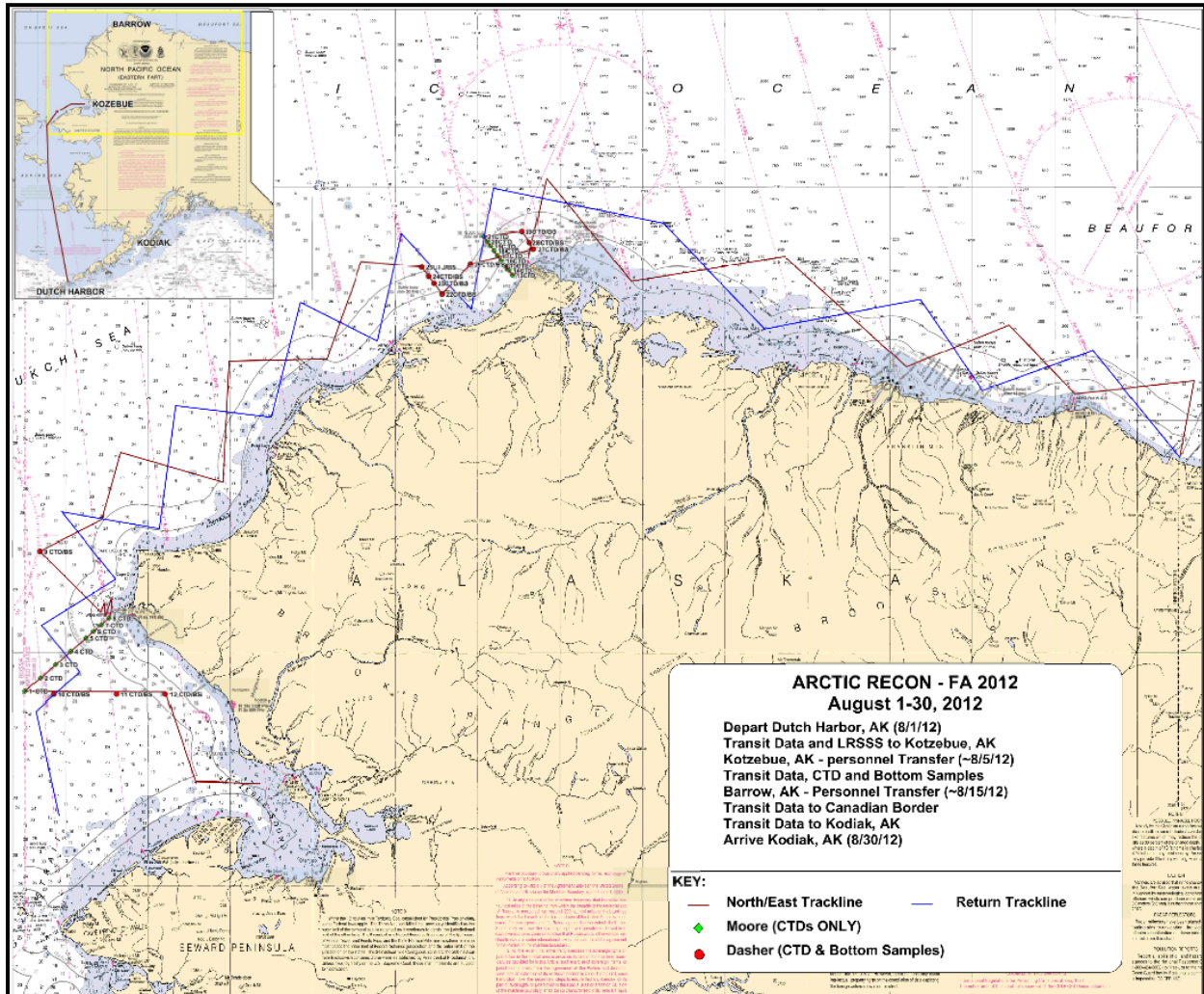
NOAA Ship *Fairweather*

August 1 to 30, 2012

Commander James M. Crocker, NOAA

Commanding Officer

NOAA Ship *Fairweather*



## **Project Overview**

The purpose of this reconnaissance project was to acquire data during the *Fairweather's* transit from Dutch Harbor, Alaska to Demarcation Point, Alaska via the Bering Sea, Chukchi Sea, Beaufort Sea and back. The data acquired will be used to support safe navigation by identifying dangers to navigation and areas in need of updating. The data collected are also being used to validate previously collected data by other organizations.

In conjunction with the ship collecting transit data other institutes such as University of Alaska (Fairbanks), Alaska Department of Environmental Conservation, NOAA/NOA/National Centers for Coastal and Ocean Sciences (NCCOS), NOAA/NMFS Alaska Fisheries Science Center (AFSC), and U.S. Navy Naval Undersea Warfare Center, Keyport Division (Navy) were also onboard to collect various data to support their respective projects.

## **Project Summary**

The ship departed Dutch Harbor on August 1<sup>st</sup> and transited the Bering Sea en route to Kotzebue, Alaska. During the transit the ship towed AFSC's Klein 7180 long range high resolution sonar to acquire data to further support *Fairweather's* 2012 FISHPAC project. The Klein 7180 was most effective in depths greater than 25 fathoms and was recovered west of Nunivak Island where the water depth became shallower than 25 fathoms. On August 5<sup>th</sup> the ship arrived in Kotzebue Sound to transferred personnel at Kotzebue, Alaska and continued along the planned transit track acquiring multibeam and sound speed profile data. The ship stopped at assigned stations to conduct CTD transects and bottom samples to support the Distributed Biological Observatory (DBO) and Alaska State Department of Conservation's AKMAP projects.

Sea ice coverage west of Barrow and in the Beaufort Sea was not favorable for the ship's planned operations requiring the ship to work along the ice edge making several attempts to reach assigned stations that were covered by heavy concentrations of sea ice. Due to the sea ice, the project plan was modified to make the best use of time while waiting for the ice conditions to change. The ship was able to complete all of the southern stations and only 50% of the station west of Barrow before the scientists departed on August 15<sup>th</sup> in Barrow.

The ice remained in high concentration west of Barrow but had receded enough for the ship to make a safe transit to Demarcation Point at the US/Canadian border. Due to the ice forecast the planned route was modified to stay closer to shore and stay inshore of the heavier ice concentrations as the ship transited east. Ice conditions were found to be better than forecast and allowed the ship to transit further offshore on the return west. Heavy ice concentrations were encountered north of Point Barrow and the ship had to modify the planned route to stay inshore

of the ice until the ship was north of Wainwright. At that point the ship continued on the planned track line south to the Bering Sea. Unexpected sea ice was encountered in the Chukchi Seas as we approached the 67° latitude and approximately 2.5 nautical miles east of the US/Russia border. The ice field remained relatively closely packed for approximately 3.5 nautical miles as the ship transited south, after which point the area became sea ice free. The ship transited the Bering Strait on August 23<sup>rd</sup> and through Unimak Pass on August 26<sup>th</sup>.

The high concentrations of sea ice off Barrow and the late movement of ice offshore in the Beaufort had the greatest impact on executing the project as planned. Additionally, the weather and sea state encountered from the Bering Strait south on both the northern and southern transits had the greatest effect on data quality.

Aside from these minor challenges this was a very successful project. Specific observations and issues encountered are addressed in more detail below. Looking forward to more detailed hydrographic survey projects, it is recommended that alternative survey methods be applied for areas along the Arctic coast. Near shore survey operations should be designed for set line spacing surveys run perpendicular to the shore out to 15 fathoms water depth. Line spacing should be established based on product scale and 100 percent side scan sonar, run parallel to the shore and/or bottom contours, should augment the bathymetry out to 15 fathoms. In depths greater than 15 fathoms either complete multibeam or 200 percent side scan sonar should be acquired.

### **Global Positioning System**

The *Fairweather* used an Integrated Differential GPS (DGPS) system offered within the POS MV 320 unit for real-time positioning of the ship for this project. Normal methods for real-time positioning are dependent on broadcast of USCG DGPS correctors. However, there are no USCG DGPS Stations within broadcast range of the Chukchi or Beaufort Seas. The *Fairweather* is equipped with only two of these POS MV 320 units which afford the option of using Satellite-Based Augmentation Systems (SBAS) - such as WAAS - for real-time decimeter level accuracy in position data. This feature is only available if the systems are upgraded to POS MV Firmware version 5.00 or later, MV-POSView version 5.0.0.0 or later, the unit must be integrated with BD960 receiver cards (with GNSS Firmware version 3.65 or later) and the vessel must be using Zephyr II (or comparable) antennas.

During this project there were minimal DGPS data gaps while using the Integrated DGPS causing almost no data quality issues. An adequate satellite constellation was maintained throughout the project. The average number of GAMS SVs visible was between 6-12 satellites. (See Appendix 1 for GNSS Analysis).

For future projects around the Bering, Chukchi and Beaufort Seas, it is recommended that all survey platforms be equipped with this POS MV unit. Using the SBAS/WAAS network via the POS MV does not require a subscription and provides an accurate, reliable, and real-time position solution.

### **Sound Speed Profile and correctors**

Sound velocity data were acquired underway using an AML SVP sensor mounted on the MVP200 (Moving Vessel Profiler) single-sensor towfish. Stationary casts were performed using a Seabird SBE19 Plus CTD sensor at specified Distributed Biological Observatory (DBO) as well as at bottom sampling sites coordinated with Alaska State Department of Conservation projects. High variability in sound speed was experienced in various locations along the trackline, particularly in the Bering Strait and areas west of Point Barrow (See appendix 2 for an 8 hour time span of MVP casts). These areas are particularly well known for their variability due to mixing of Arctic and Pacific water-masses. Analysis done by Jonathan Beaudoin at the University of New Hampshire in which *Fairweather* sound speed trackline profiles were compared to data from the World Ocean Database verify that we experienced the full range of known conditions for the month of August (sound speed variations throughout the entire water column of up to 30 m/s) over the course of an 8 hour period. Sound speed cast intervals were reduced when surveying in these variable areas by *Fairweather* personnel to capture a representative sample of the changing water properties. Ship operations were adapted to allow for continuous casting during high sound speed variability. Additional discussion and documentation of new surveying techniques will have to be incorporated into shipboard procedure for future Arctic missions.

As the 2012 Arctic survey is only for trackline purposes, sound speed variations and artifacts seen in the outer beams of multibeam systems can be filtered. However, for future projects in the area surrounding Point Barrow special consideration should be paid to this sound speed variability when planning for full bottom coverage multibeam or side scan surveys. Sound speed prediction maps and additional tools currently in development at the University of New Hampshire's Center for Coastal and Ocean Mapping may be a reasonable solution in ensuring quality charting in the future for these highly variable sound speed areas.

### **Water Level Correction**

Due to the large coverage area of this project the tide correctors provided included both TCARI grids as well as discrete zoning. TCARI was provided for the south Arctic portion and discrete zoning was used for the north Arctic portion. Data management was a bit challenging do to the amount of data, and the number of TCARI grids and zoning files. Three TCARI grids were provided for this project. A better solution would have been to provide one TCARI grid per project. It is not possible in post-processing to load multiple grids into a project. This processing limitation required some tedious data management.



Water levels in the North Slope were minimal and averaged less than 0.5 meters during this project.

### **Charted to Survey Sounding Comparison**

For most of the data collected the surveyed soundings were noted to be consistent or deeper than the charted depths. However, the vast differences between chart scales makes it difficult to compare; for example, some surveyed soundings were over 1000 meters away from the nearest charted depths.

In a number of areas surveyed soundings were deeper than charted depths by 1 to 10 feet. The largest disagreement between surveyed and charted depths showed surveyed soundings deeper by approximately 200 fathoms. The majority of areas found to be shallower than charted depths were approximately 3 feet shallower on average. However, some areas of chart disagreement have shown surveyed soundings to be as much as 10 fathoms shallower than charted depths. (See Appendix 3 for chart to survey sounding comparison images).

### **Chart Scale and Projections**

The charts for the area transited by the *Fairweather* conspicuously did not meet the expectations of modern mariners. There are small scale charts (1:700,000) that cover the area which have large white spaces devoid of charted depths. Closer to shore there are larger scale charts (1:50,000) along the coast which again have large areas devoid of charted depths. Both scale charts should be updated and new larger (1:20,000) scale charts should be created for heavily transited harbors.

UTM zones were challenging for collecting, data processing and creating products during the transit of the North Slope. In the future, if there are more transit projects which cross a number of UTM zones other projections should be explored.

### **Coast Pilot**

In general the Coast Pilot agreed well with what the ship was seeing along the trackline. A point of note not mentioned in the Coast Pilot are the additional communications requested by certain towns/villages or cities. When transiting in the vicinity of Barrow and Katovik local communication centers requested a call in every 4 hours on VHF-FM CH – 68. The information each requested were name, location and destination.

In the vicinity of Barrow depths can vary to as much as six feet due to ice gouging (see appendix 4 for images). Larger vessels may anchor off shore and receive supplies and transfer personnel

using small boats or landing crafts, however, there is no protection from heavy weather afforded at any anchorages in the vicinity of Barrow.

On the transit east to Demarcation Point the bluffs along the shore are as high as 25 ft and are very steep. There are several huts around Demarcation Bay that seem to be seasonal hunting shelters.

### **Weather and Sea Ice**

During this project weather data were collected and logged hourly using both a scientific computer system as well as manual observations. The *Fairweather* referred to the National Weather Service (NWS) marine forecasts while underway. The ship mainly considered the text product produced for five regions of the Alaskan arctic.

General text forecasts for the region were fairly accurate. The forecasts for visibility, weather and wind remained extremely accurate throughout the forecast regions. Forecasts for wave height however showed some discrepancies. It appeared that when near sea ice, wave height was significantly less than the forecast value. This may be due to the effect that the sea ice has by lessening the open water fetch and therefore lessening the sea wave height. Overall, the forecasts issued by the NWS were reliable, even in the arctic region. (See Appendix 5 for the Arctic Weather Synopsis)

Sea ice observations were supported this season via daily satellite products from The National/Naval Ice Center (NIC) and frequent photos from the National Marine Mammal Laboratory who were conducting a NMFS Marine Mammal Survey. The ship also referenced the National Weather Service Sea Ice Analysis web page. The collaboration of all these products allowed the ship to transit in these waters with confidence.

Localized dense fog was a normal occurrence observed while transiting close to sea ice. The water and sea temperatures change quickly around the ice which produced either fog or created a phenomenon known as the arctic mirage (objects or land appear to be closer or larger than they really are). The ships radar, which is always a key tool during navigation, was able to detect the ice about 3 miles out which assisted in the safe navigation near the ice.

### **Vessel Traffic**

The *Fairweather* recorded vessel traffic that were seen via the AIS (Automated Identification System) the entire transit starting from departing Dutch Harbor and transiting north via the Bering Sea to Chukchi Sea to Beaufort Seas and the return transit back just north of Dutch Harbor. The information recorded included: Date, local time, Vessel name, type, Nav Status, length, width, draft, IMO number, MMSI, Latitude, Longitude, Destination, Arrival Time, and

any notes watchstanders deemed relevant. Vessels were recorded multiple times if they were seen on different days or locations.

The *Fairweather* recorded seeing 49 separate vessels on AIS between August 2 - 26, 2012. Self-reported lengths ranged from 12m to 228m with 8 greater than 100m, 11 between 50m and 100m, and 22 vessels less than 50m in length. 8 Vessels did not broadcast their size. 16 Vessels identified themselves as tugs/towing vessels, 2 as cargo ships, 3 as fishing, 2 as carrying hazardous cargo, 2 as tankers, 2 as passenger ships, and 1 as engaged in military operations. 1 vessel erroneously reported itself as a wing-in-ground, as officers reported visually identifying a large ship. Often vessels would report arrival times that were already past.

Passenger Ship *The World* was seen on Aug 21<sup>st</sup> headed for Herchel Island. Passenger ship *Hanseatic*, seen Aug 18<sup>th</sup>, reported that it was East bound for the Northwest Passage. The northernmost vessel seen was the Tor Viking, which was underway using engines at 71° 35.70'N 155° 49.30'W. In total, *Fairweather* recorded 19 vessels north of 70°N. (See Appendix 6 for completed AIS report.)

### **Project Support Logistic**

Logistics for the entire project were coordinated between the Operations Branch, Visiting Scientists, USCG, Harbor Masters, Perto-Star, National Weather Service, DLA, Bowhead Marine and *Fairweather* Personnel.

The Operations Branch provided the ship with the project instructions for the entire project which included collection of transit data as well as the other small piggy back projects from the visiting scientist. As soon as the scientists were identified the ship coordinated directly with them for ship scheduled locations, arrival and departure times, loading and offloading gear and other project coordination.

Dutch Harbor port of call logistics were initiated through the USCG LOGREQ system sent via email to D17-DG-M-K-BaseKodiak-PCD-PortServices@uscg.mil. After the initial LOGREQ, logistics for port calls were made through direct email correspondence with the City of Unalaska - Port of Dutch Harbor - Harbormaster.

Refueling in Dutch Harbor was handled by direct correspondence with Perto-Star and with the assistance of MOC-P Resource Management Branch. Another option for refueling logistics the USCG pursued was having Crowley and Delta Western enroll in the "SEA Card" open market program. Such enrolment should make it relatively easy to take on fuel at sea directly from one of their fuel barges operating off the North Slope. However, refueling at sea would undoubtedly require close communication with the USCG and would likely warrant inclusion in the USCG

NEPA. POC for the USCG at sea refueling are; CDR James Robinson (James.P.Robinson@uscg.mil) and CDR Frank McConnell (Frank.V.McConnell@uscg.mil).

Several options for stores replenishment at Barrow were investigated including; purchasing stores from the USCG commissary in Kodiak, using a USCG C-130 logistics flight from Kodiak to Barrow and transferring the stores to the ship via USCG HH-60 vertical replenishment. This option was disregarded in favor of ordering stores through DLA Sysco Alaska Food Service and subsequently delivered on a commercial air flight. To recover and transport the stores from the airport a vehicle was borrowed from the NWS office in Barrow and a private landing craft barge was hired to transport the stores to the ship's anchorage location. This replenishment was conducted in tandem with a crew transfer in which visiting scientists were disembarked and taken to the airport. The stores replenishment was relatively small (approximately one pallet) and there was no guarantee that the commercial air shipment would arrive in the narrow window of opportunity to utilize the barge to transfer the stores to the ship (the barge was available for approximately 12 hours). For future, larger, and/or more time sensitive stores replenishments it is recommended to use the USCG C-130 logistics flight and HH-60 VERTREP. The POC for USCG logistics and replenishment flights is: David Seris ([David.M.Seris@uscg.mil](mailto:David.M.Seris@uscg.mil))

# Appendix

**Analysis of GNSS data collected for Project M-S974-FA-12**

Data were gathered with the ship's POS MV 320 in segments using internal logging mode. Each segment is delineated with an extension of .xxx, where xxx equals the number of the segment. All analysis was done using POSPac MMS v5.4.2.0. The purpose of this analysis was to determine areas where the ship lost its DGPS corrector and relevant satellite information during this period. Below are the results.

Using 2012\_225\_S220.069 through .096:

8/14/2012 1132 through 8/16/2012 0344

NO DGPS Time Outs

GAMS SVs: 6-12, average 9-10

Using 2012\_229\_S220.000 through .017:

8/16/2012 0603 through 8/17/2012 0041

NO DGPS Time Outs

GAMS SVs: 6-12, average 10

Using 2012\_229\_S220.017 through .041

8/16/2012 2339 through 8/18/2012 0132

NO DGPS Time Outs

GAMS SVs: 6-12, average 9-10

Using 2012\_229\_S220.041 through .054

8/18/2012 0030 through 8/18/2012 1434

NO DGPS Time Outs

GAMS SVs: 7-12, average 9-10

Using 2012\_232\_S220.000 through .021

8/19/2012 0230 through 8/20/2012 0117

NO DGPS Time Outs

GAMS SVs: 7-12, average 10

Using 2012\_232\_S220.019 through .043

8/19/2012 2253 through 8/21/2012 0004

NO DGPS Time Outs

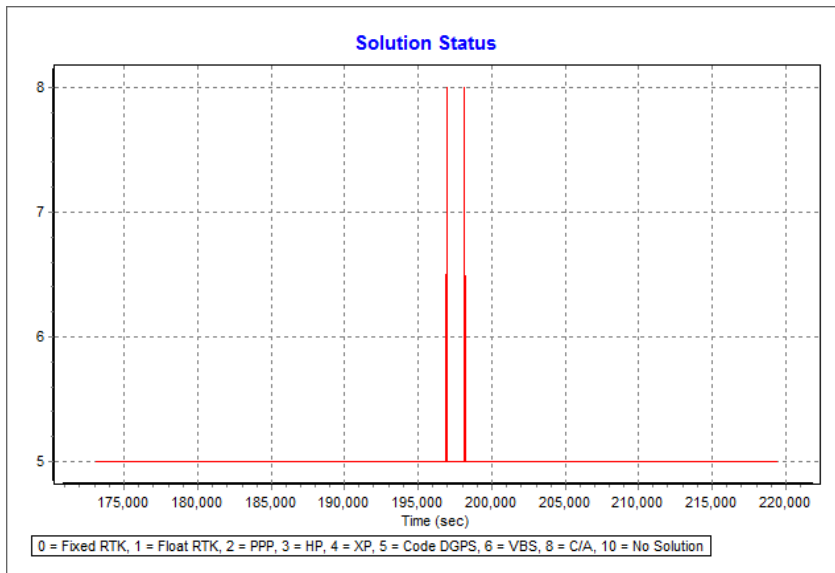
GAMS SVs: 6-12, average 9-10

Using 2012\_232\_S220.044 through .056

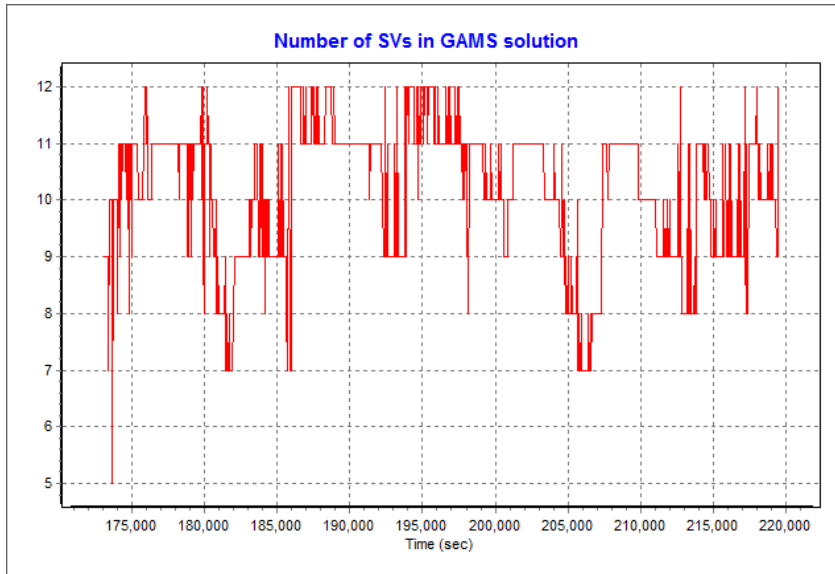
8/21/2012 0004 through 8/21/2012 1259

Two instances of running in C/A mode, approximately 0910 and 0925, see Figure 1

**Figure 1: 8/21/2012 GNSS Solution Status, POSPAC Report screen**



GAMS SVs: 5-12, average 9, see Figure 2

**Figure 2: 8/21/2012 GAMS SVs, POSPAC Report screen**

Using 2012\_232\_S220.056.068 through 2012\_232\_S220.056.092

(Note: These file names are correct, I believe they were simply setup incorrectly)

8/21/2012 2325 through 8/23/2012 0120

One instance of running in C/A mode, at approximately 8/23/2012 0010

GAMS SVs: 6-12, average 9-10

Using 2012\_232\_S220.092 through 2012\_232\_S220.115

8/23/2012 0018 through 8/24/2012 0110

Two instances of running in C/A mode, at approximately 8/23/2012 0030 and 0245

GAMS SVs: 6-12, average 9-10



### Sound Speed Variability

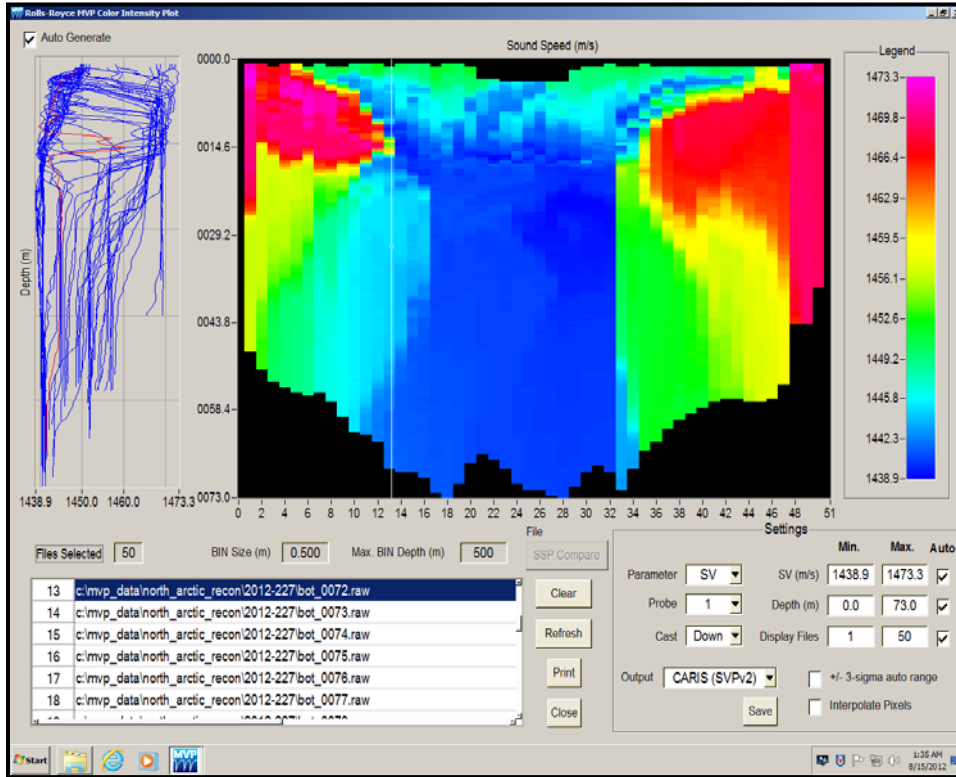


Image 1: Sound Speed data collected over 8 hours (trackline highlighted in yellow below)

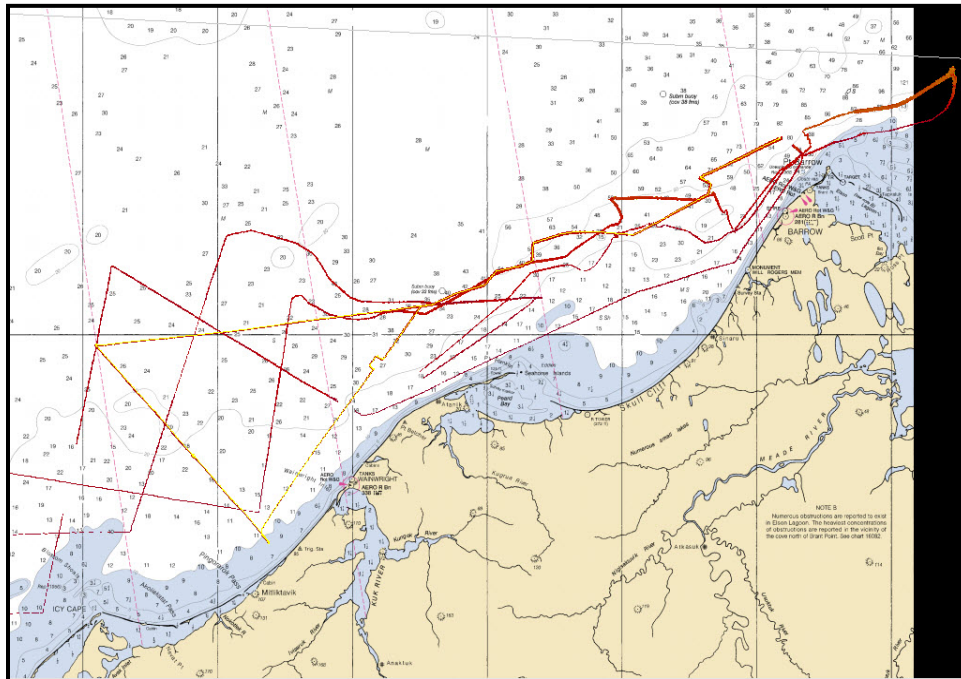
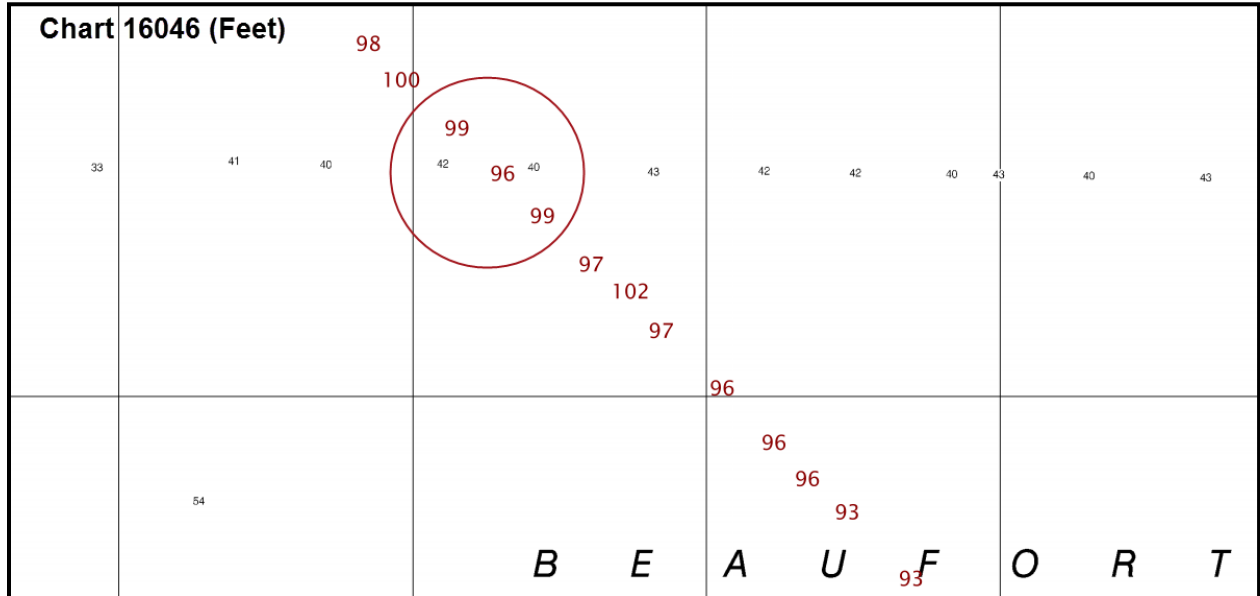
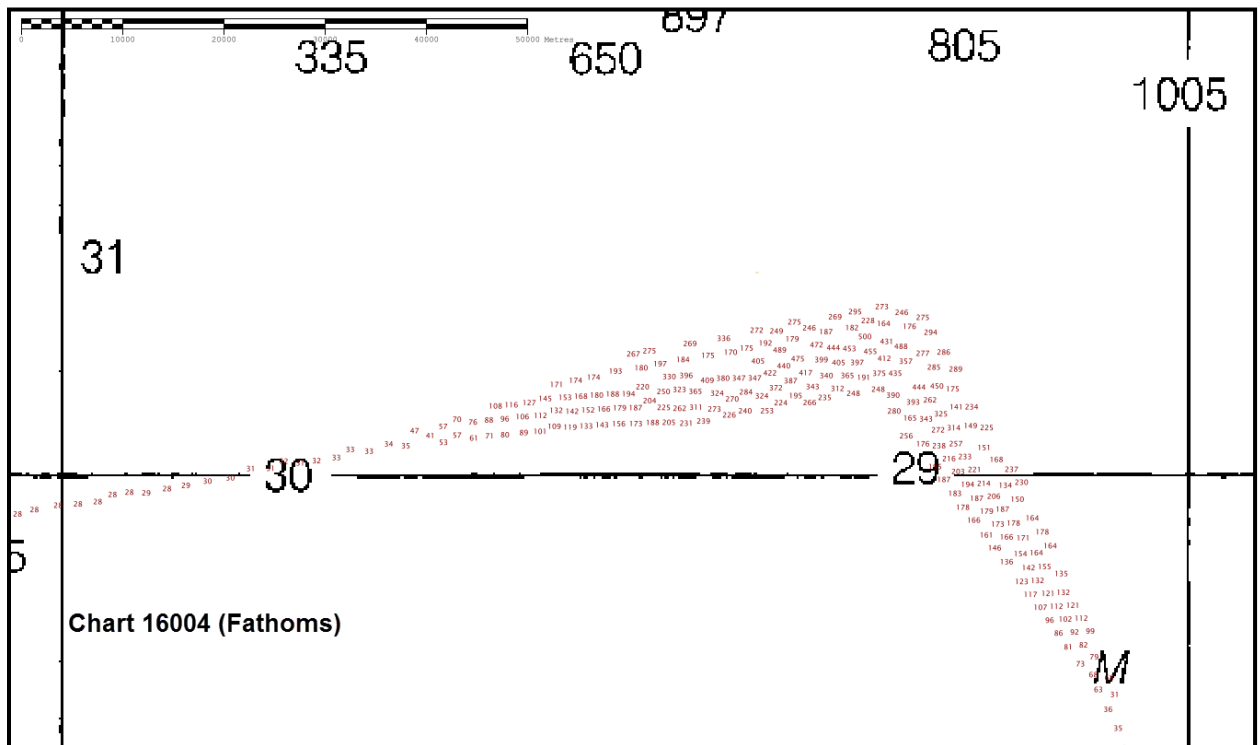


Image 2: West of Point Barrow Tracklines

Chart to Survey Sounding Comparison



**Image 1: Surveyed soundings approximately 50 feet deeper than charted depths.**



**Image 2: Surveyed soundings over 200 fathoms deeper than nearest charted depth.**

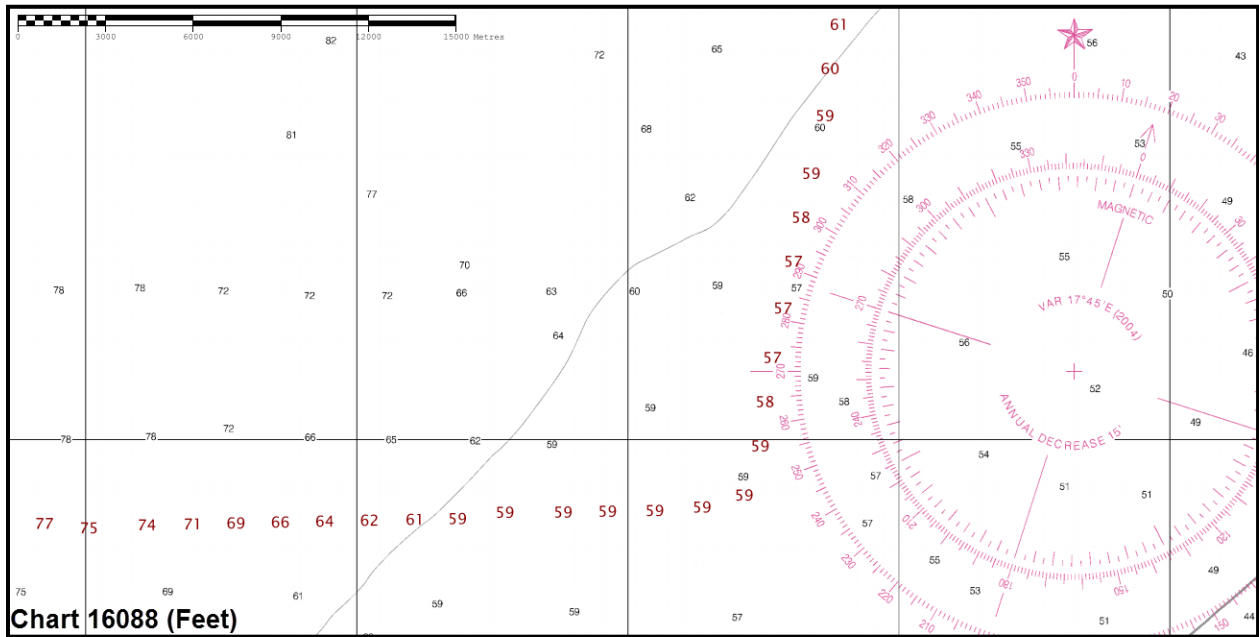


Image 3: Surveyed soundings and charted depths agree well.

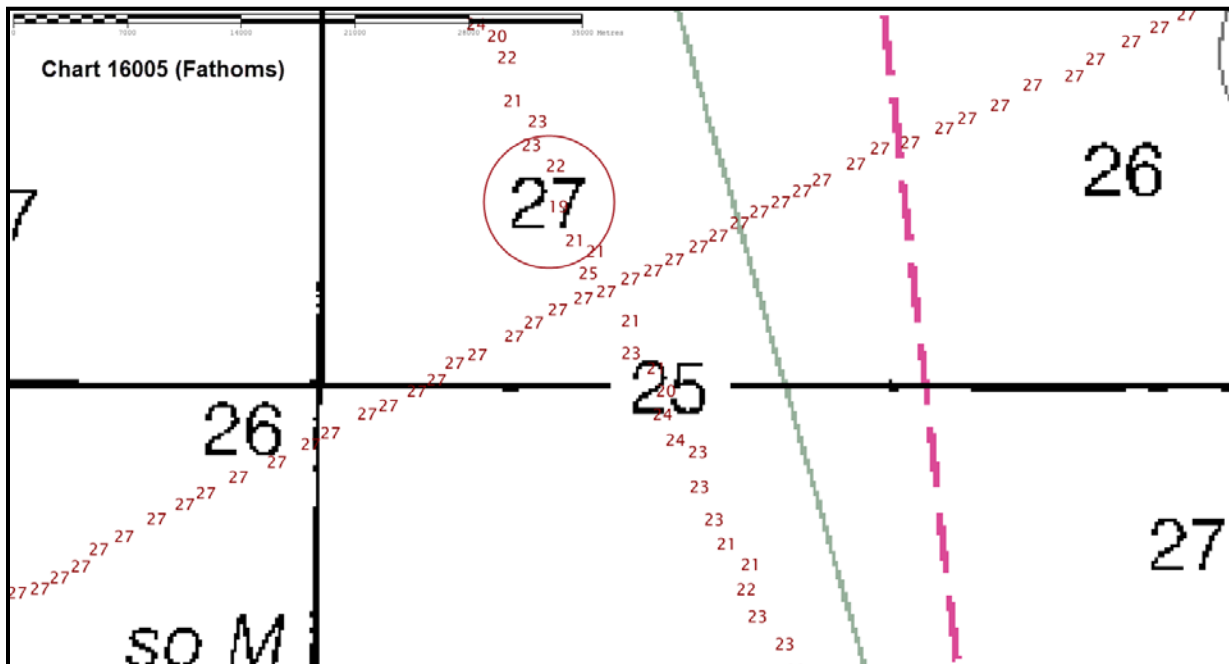
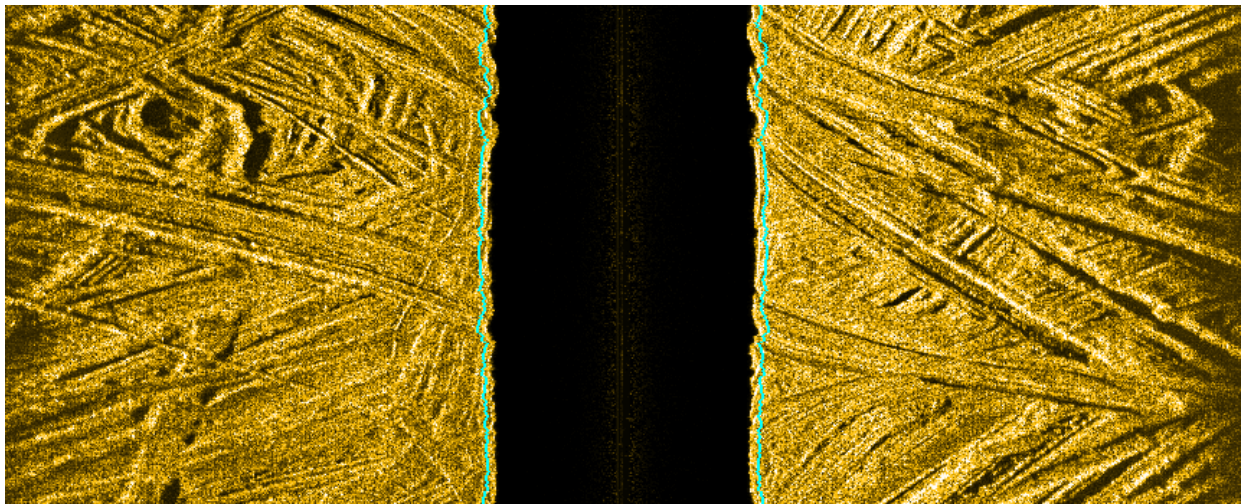
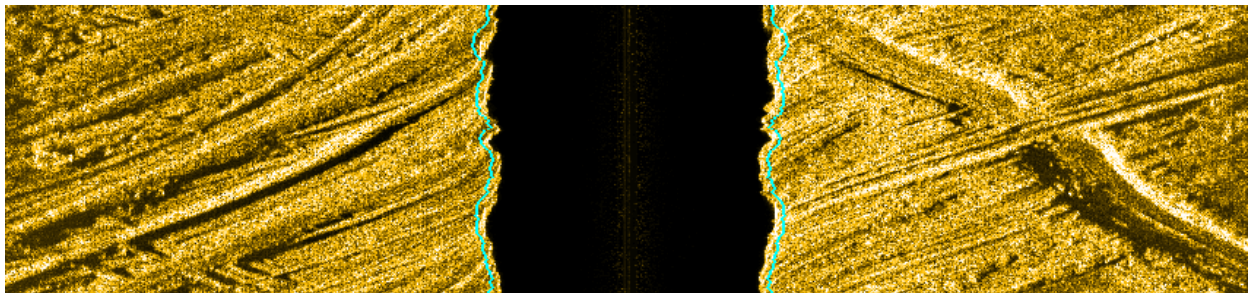
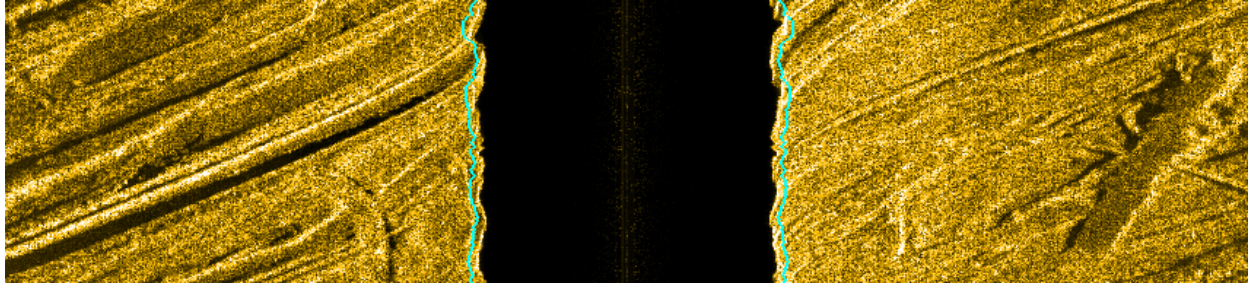


Image 4: Surveyed soundings 5-8 fathoms shallower than charted depths.

Ice Gouging images off Barrow, AK





## Arctic Weather Synopsis

NOAA Ship Fairweather (S-220), Arctic Reconnaissance, August 2012

Over the month of August, 2012, the NOAA Ship Fairweather conducted an arctic reconnaissance mission to demarcation point Alaska. During this mission weather data was collected and logged hourly using both an scientific computer system as well as manual observations. Below is a summary of the hourly manual observations taken by the ship as well as the map of the observation's locations. Attached with this document is a full copy the ship's weather log for the month of August.

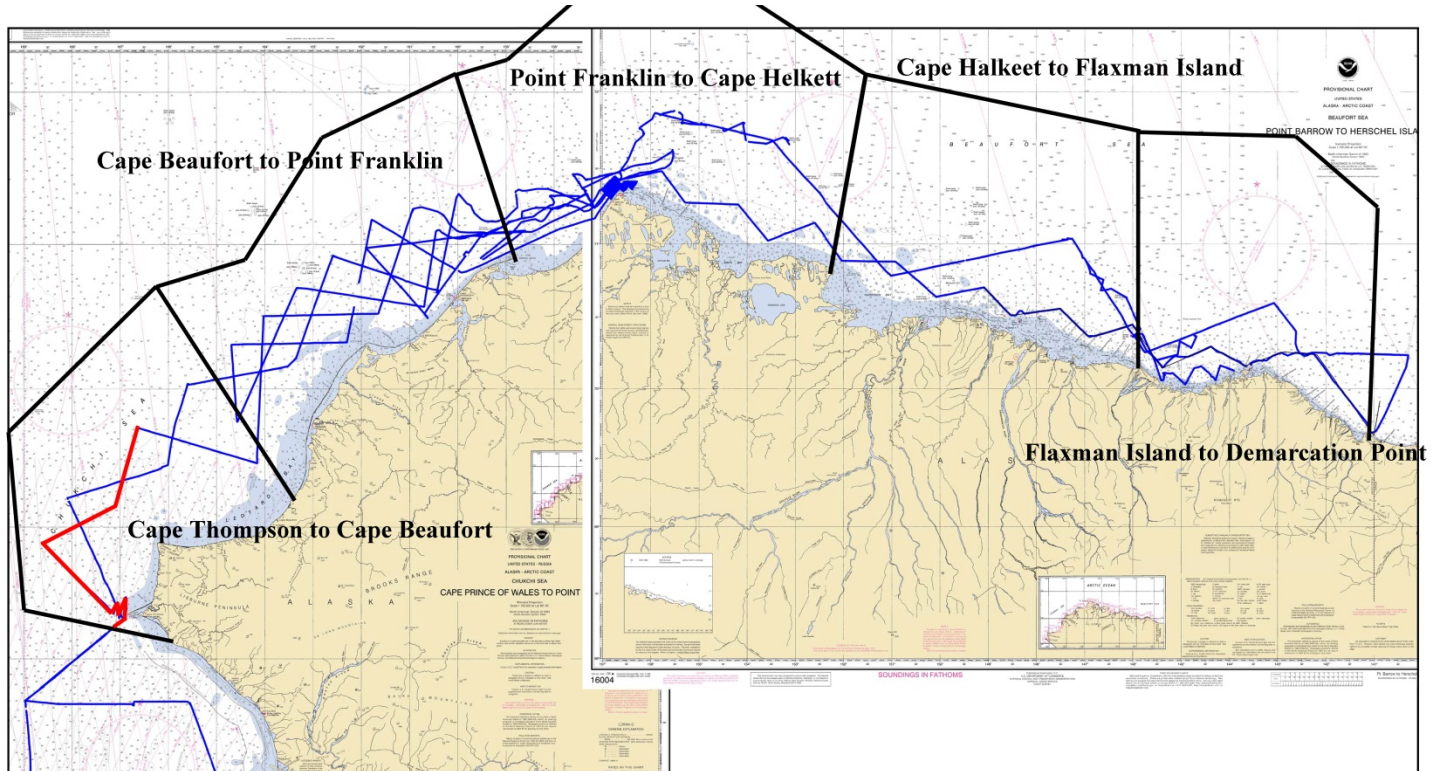
### General NWS Forecast Observations

Fairweather referred to the National Weather Service (NWS) marine forecasts while underway. The ship mainly considered the text product produced for five regions of the Alaskan arctic. The forecast regions have been denoted on the ship's location images.

General text forecasts for the region were fairly accurate. The forecasts for visibility, weather and wind remained extremely accurate throughout the forecast regions. Forecasts for wave height however showed some discrepancies. It appeared that when near sea ice, wave height was significantly less than the forecast value. This may be due to the effect that the sea ice has by lessening the open water fetch and therefore lessening the sea wave height. Overall, the forecasts issued by the NWS were reliable, even in the arctic region.

**Aug 8, 2012**

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
<b>Morning</b>	OVC, 10+ Visibility	8-10	1-2
<b>Afternoon</b>	MC, 10+ Visibility	15-16	1-3

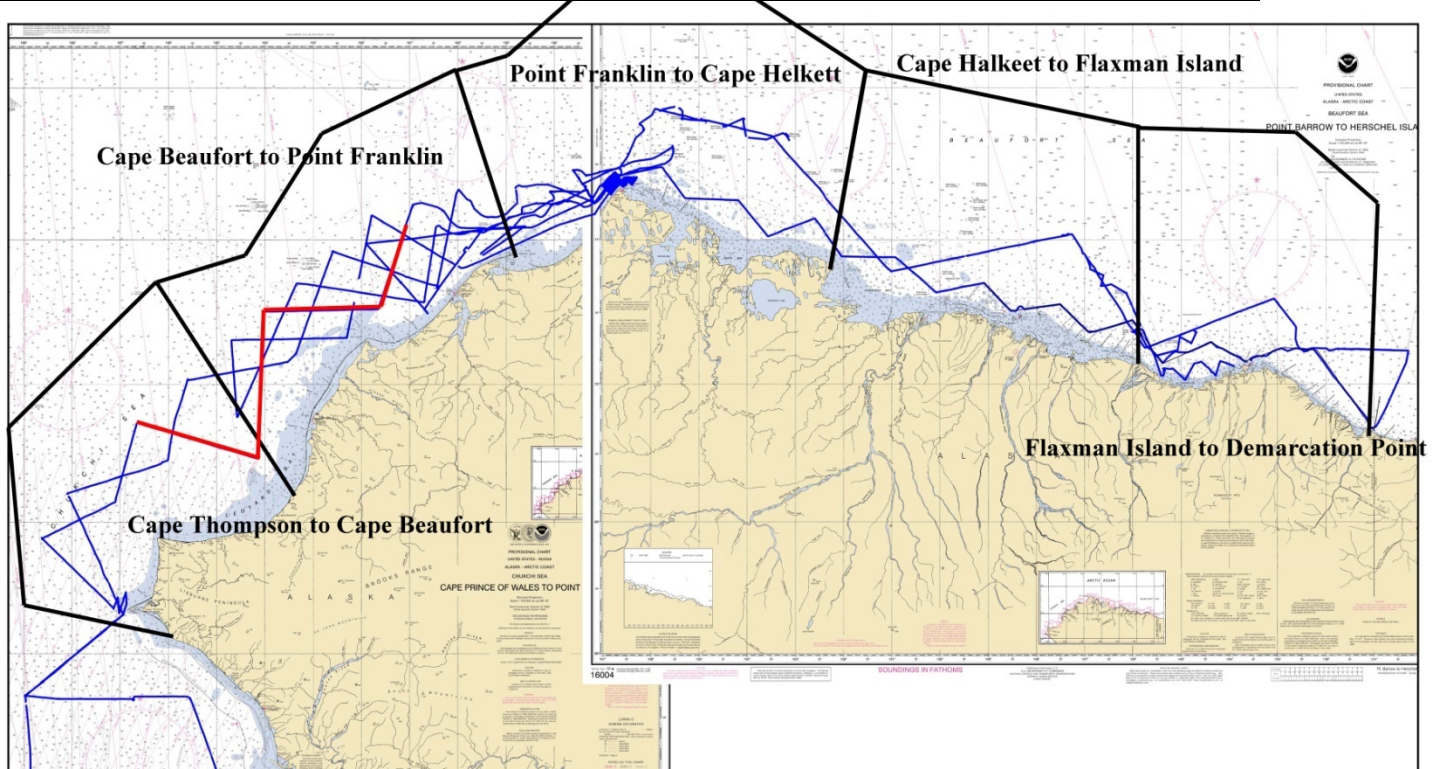


**Note:** The ship's location during the day is denoted in red.



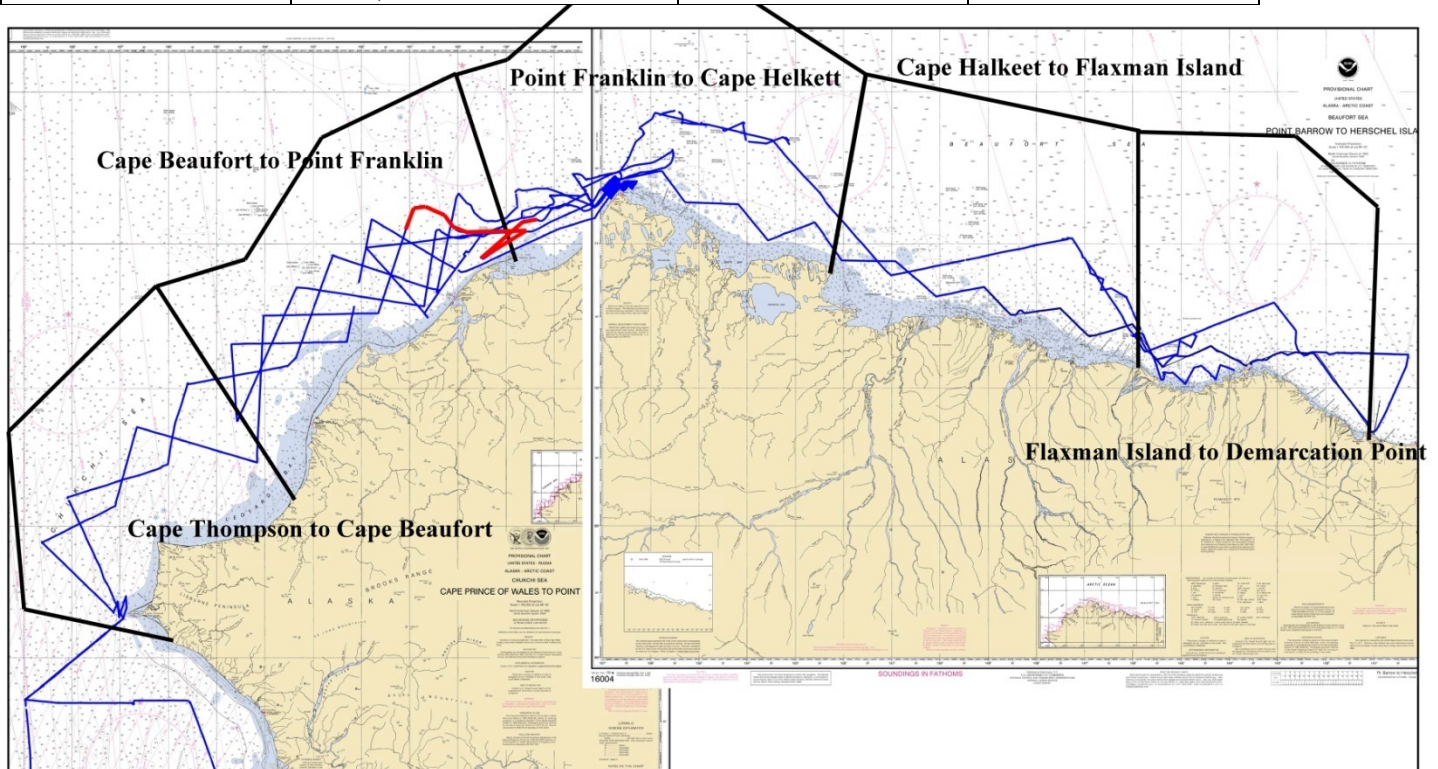
Aug 9, 2012

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
<b>Morning</b>	OVC, 10+ Visibility	10-14	3
<b>Afternoon</b>	FG, ½ Visibility	15-19	1-2



Aug 10, 2012

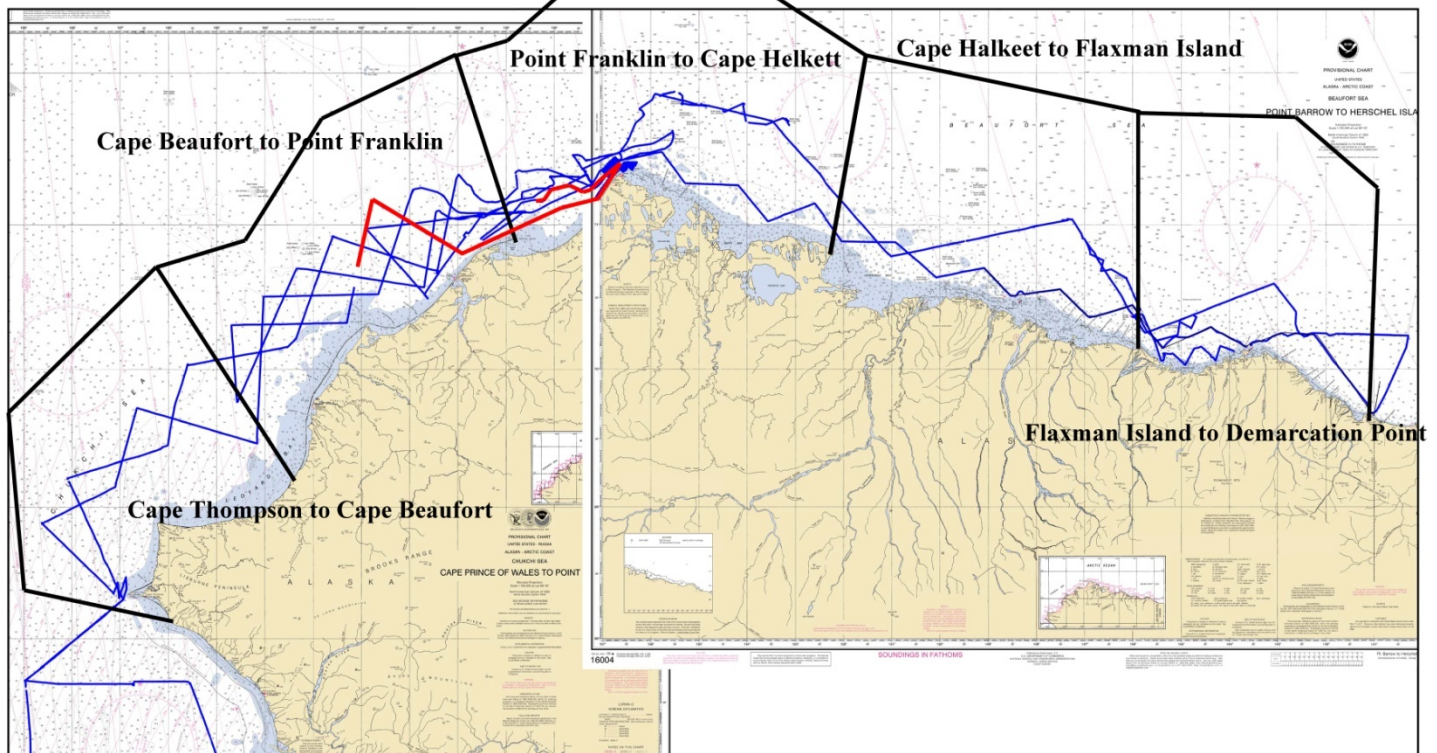
	Weather (Vis in nm)	Wind (kts)	Wave (ft)
<b>Morning</b>	MIST, 1-4 Vis	0-1	0-1
<b>Afternoon</b>	MIST, 1-4 Vis	0	0





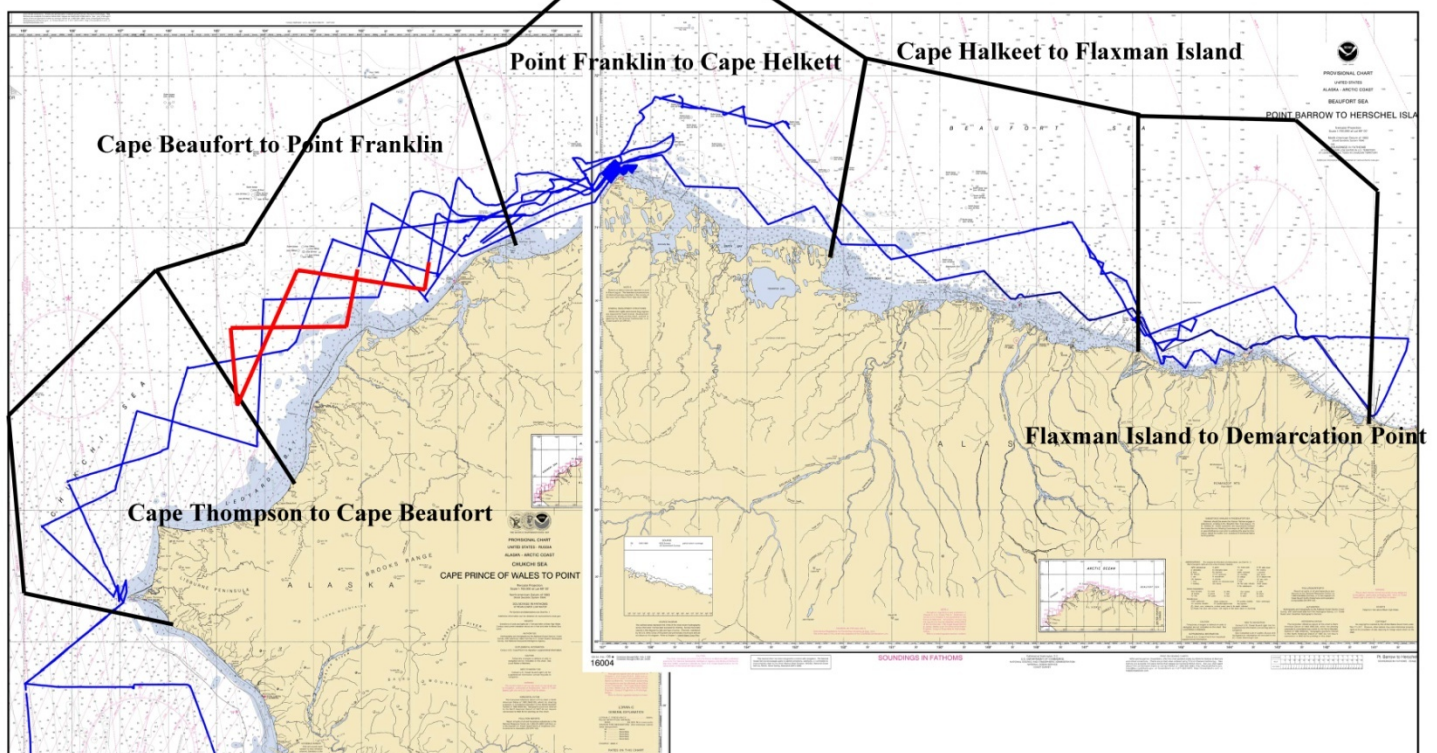
Aug 11, 2012

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	OVC, 7-10Vis	5	0
Afternoon	OVC, 10+ Vis	8-9	0



Aug 12, 2012

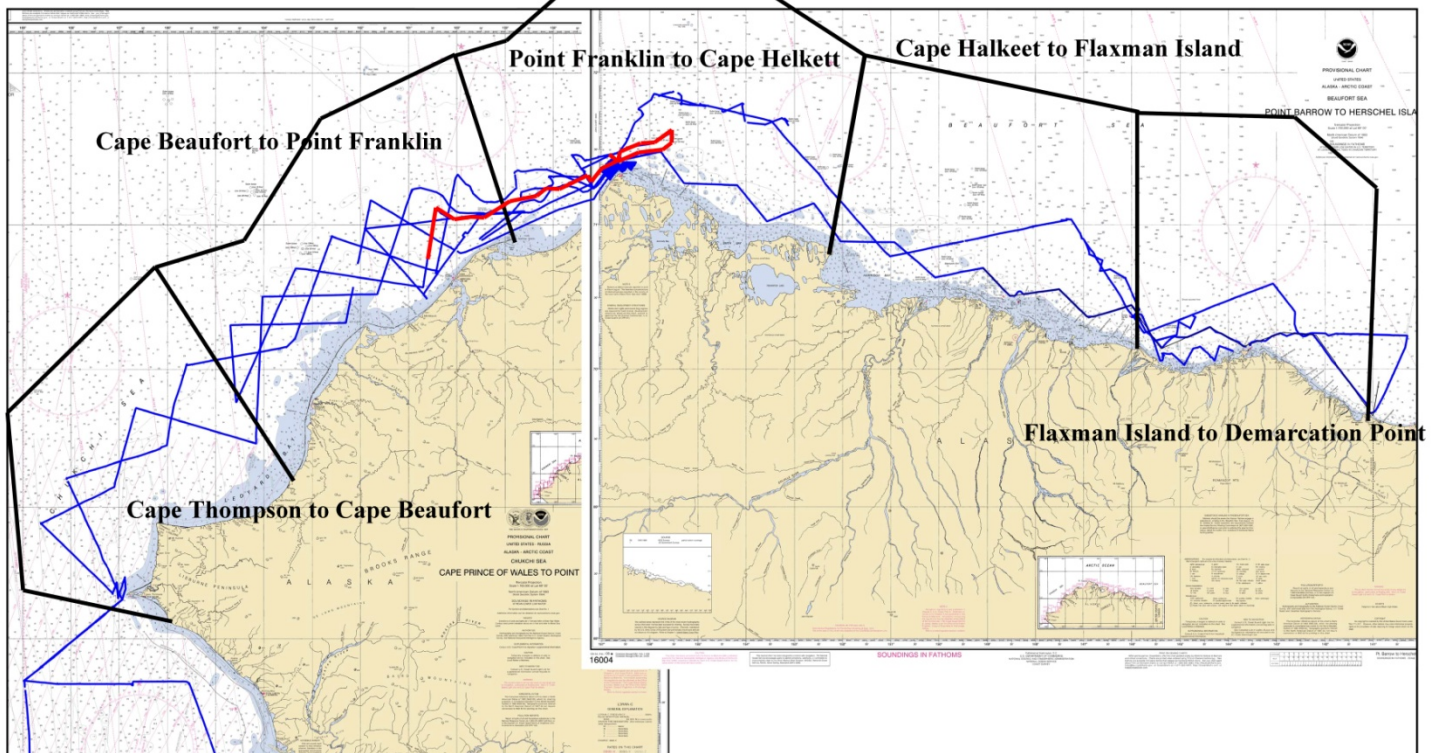
	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	OVC, 10+ Vis	5-10	0
Afternoon	MCLR, 10+ Vis	10-12	0





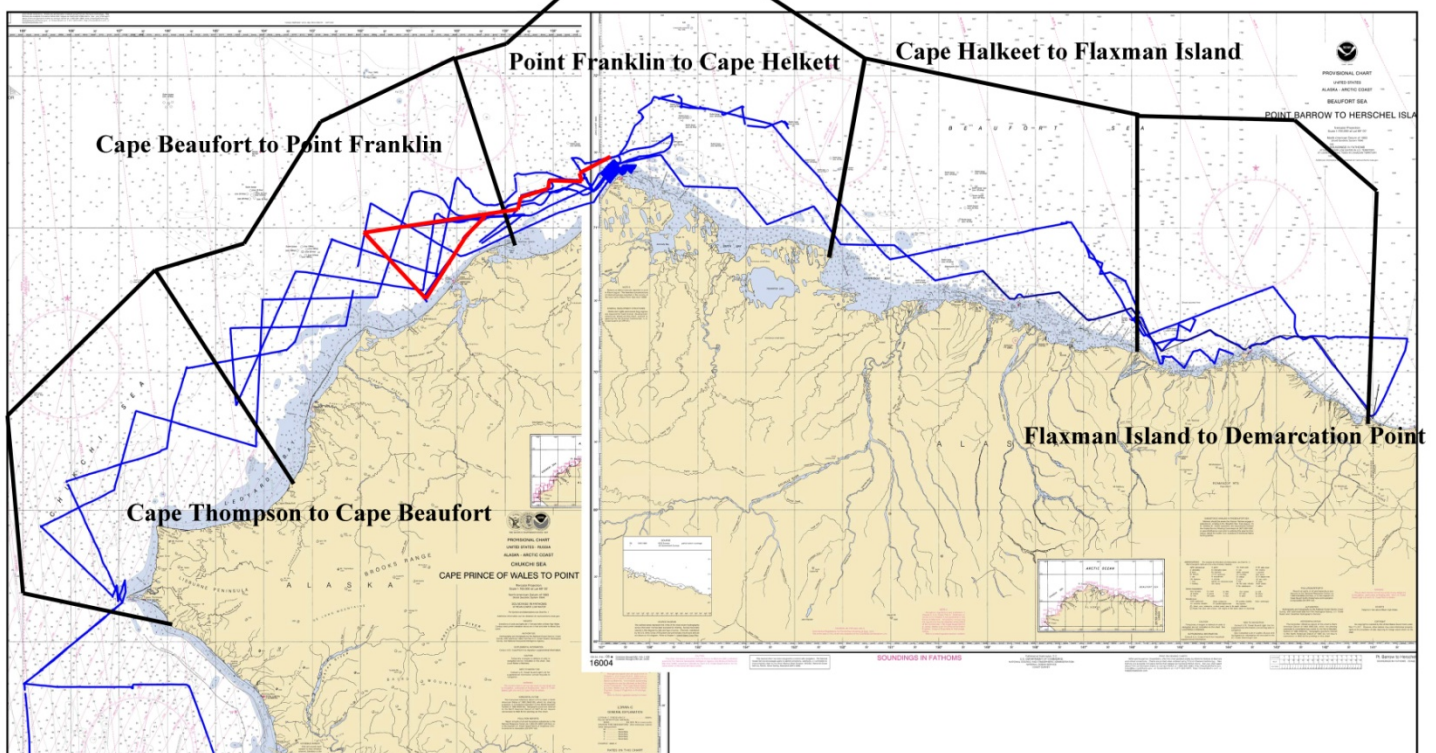
Aug 13, 2012

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	MCLR, 10+ Vis	10-14	0-1
Afternoon	MCLR, 10+ Vis	15-20	0



Aug 14, 2012

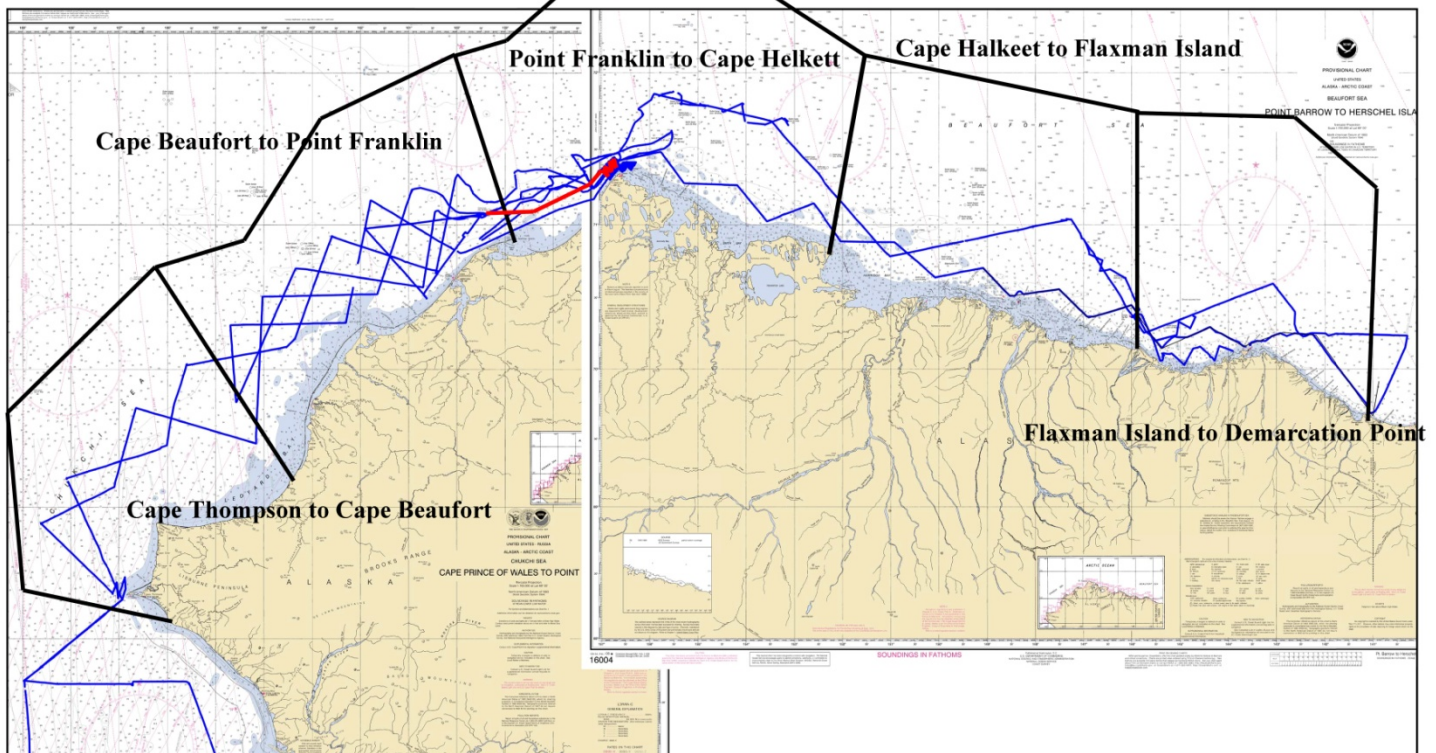
	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	OVC/FG, ½ Vis	LGT	0
Afternoon	OVC/RA, 10+ Vis	7-10	0





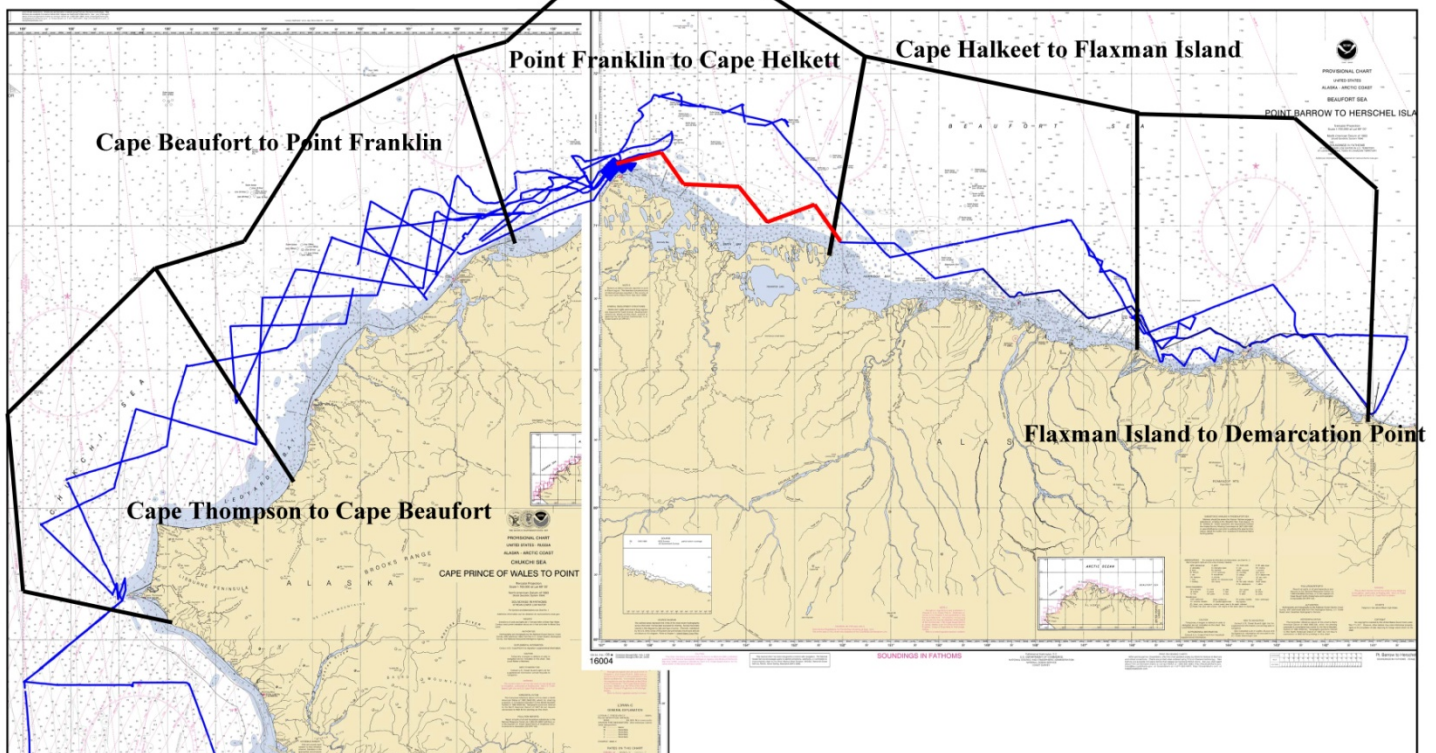
Aug 15, 2012

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	-RA/FG, ½ Vis	5-10	0-2
Afternoon	OVC, 7 Vis	10-20	0



Aug 16, 2012

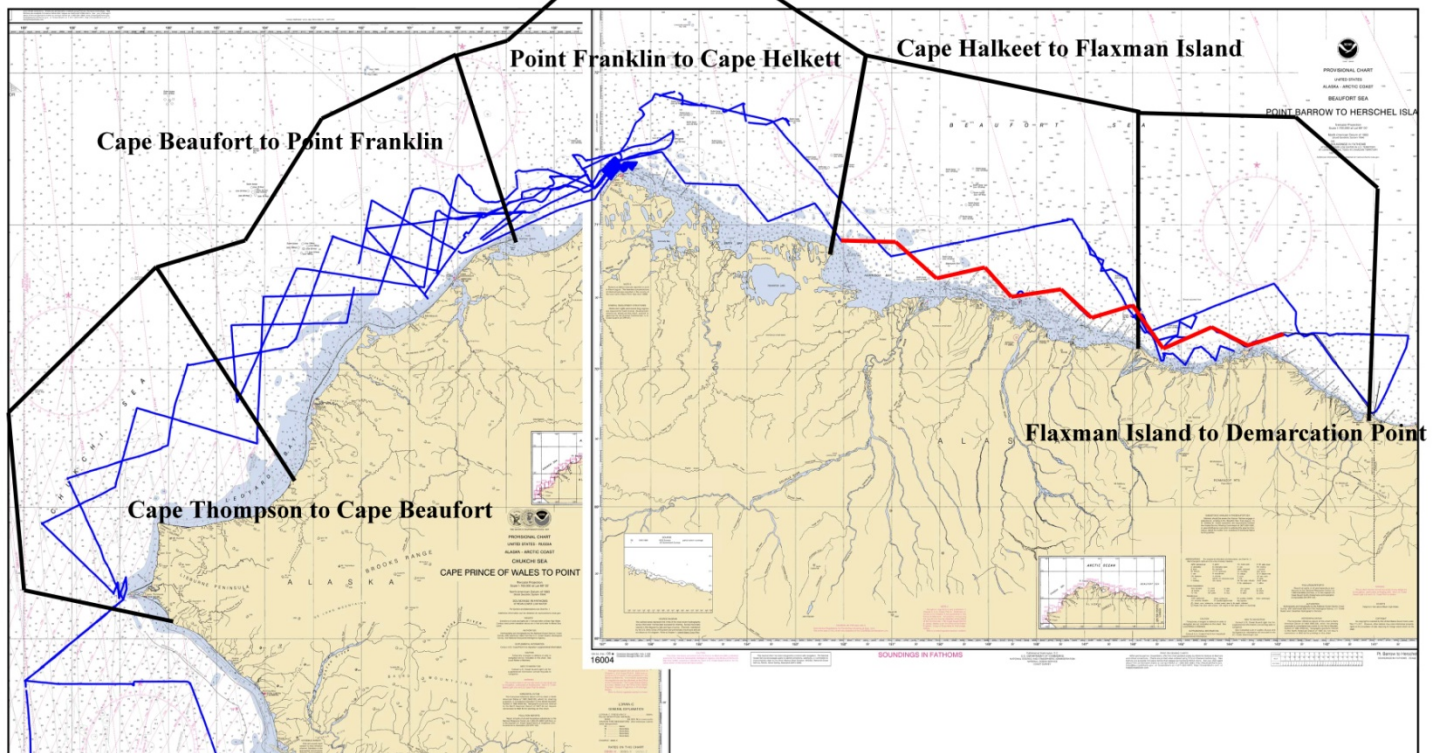
	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	OVC, 6-9 Vis	15-20	2-4
Afternoon	MCLR, 10+ Vis	10-20	1-3





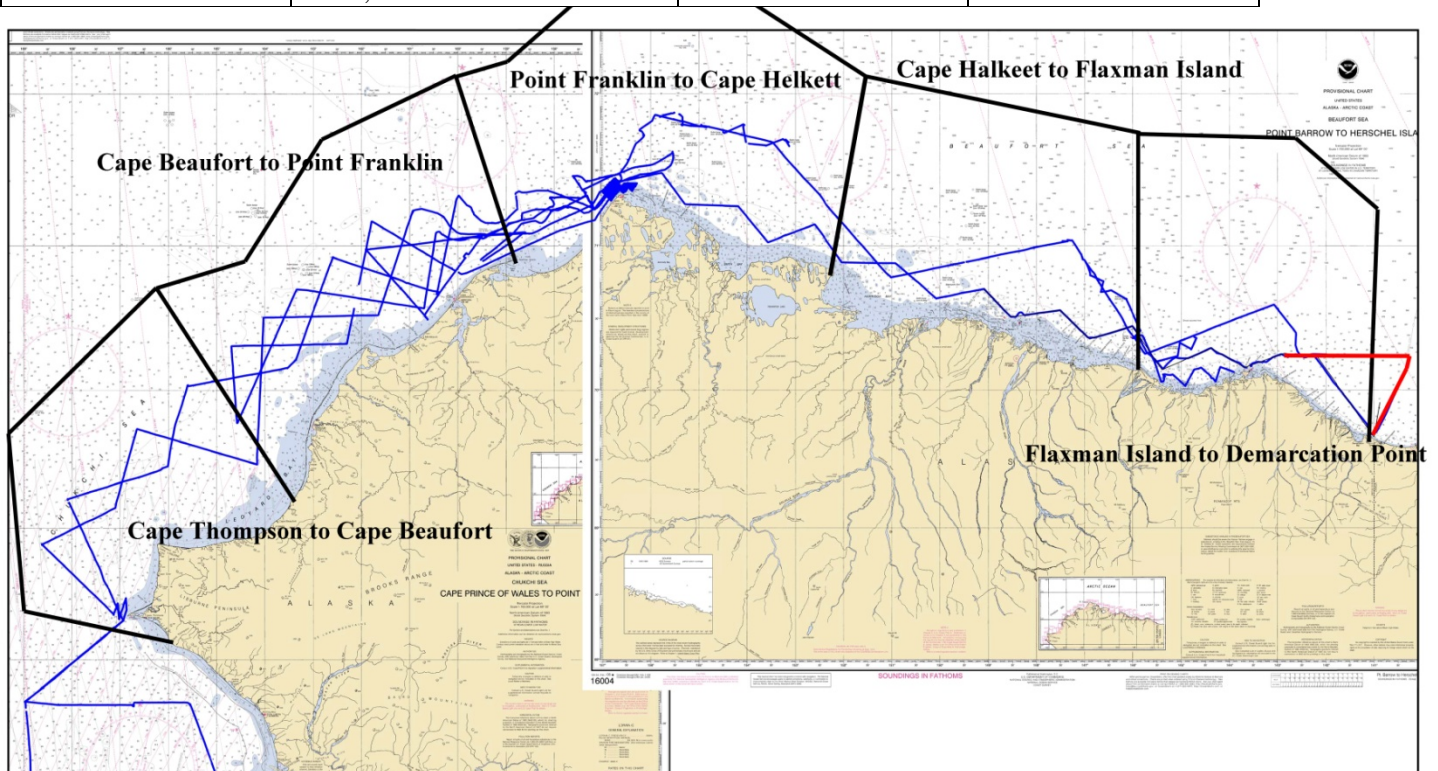
Aug 17, 2012

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
<b>Morning</b>	OVC, 10+ Vis	10-12	0-1
<b>Afternoon</b>	PC, 10+ Vis	8-10	0



Aug 18, 2012

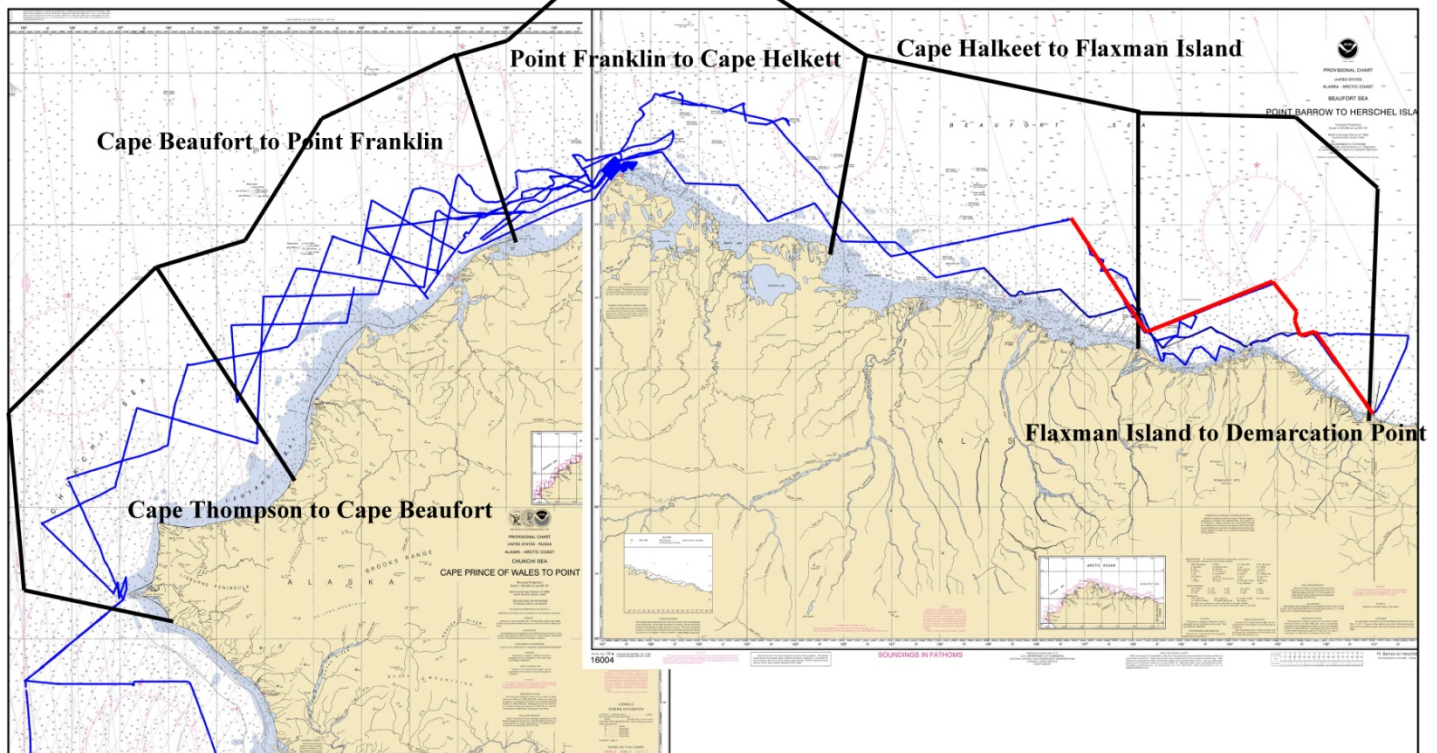
	Weather (Vis in nm)	Wind (kts)	Wave (ft)
<b>Morning</b>	MCLR, 8-10+ Vis	0-10	0
<b>Afternoon</b>	CLR, 10+ Vis	10-12	0





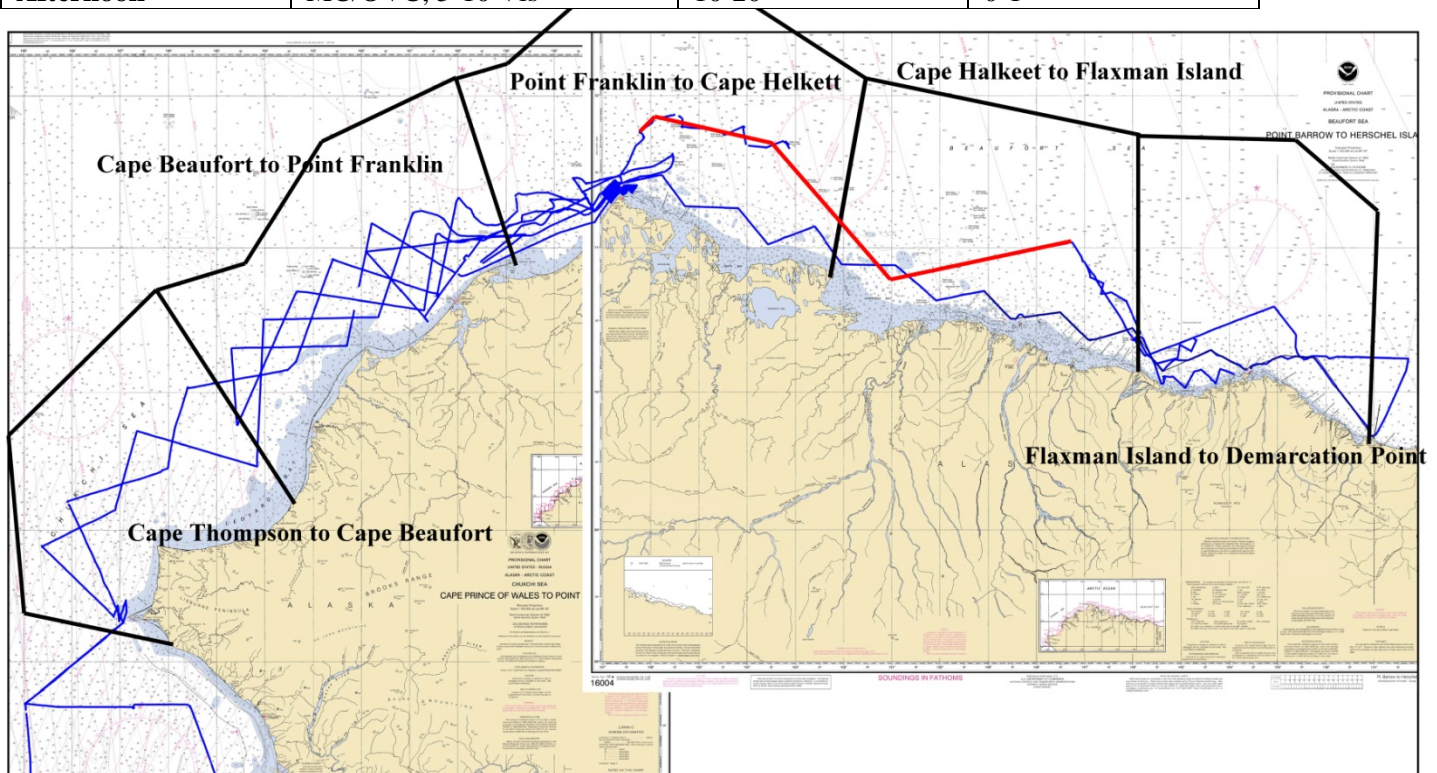
Aug 19, 2012

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	MCLR, 10+ Vis	6-14	0-1
Afternoon	MC, 8-10 Vis	10-15	0-3



Aug 20, 2012

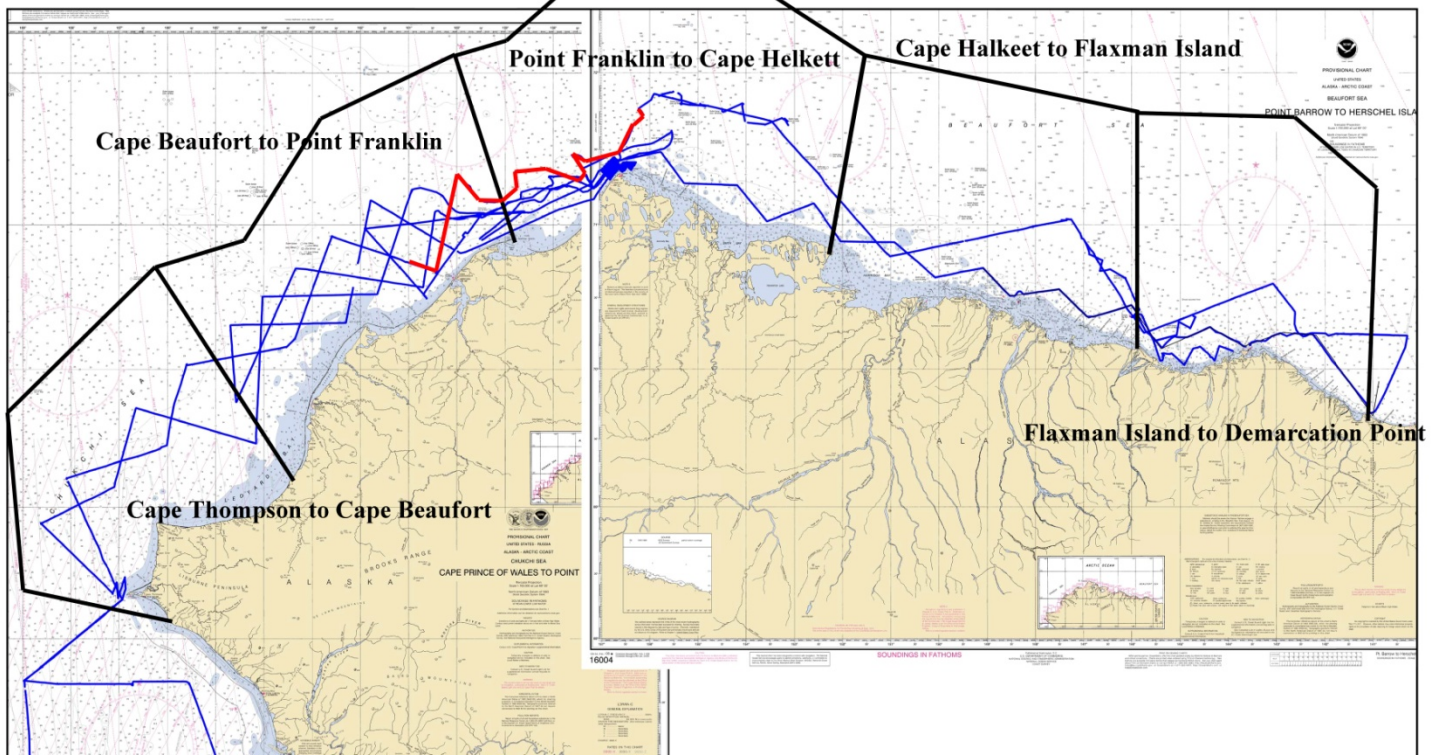
	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	MC, 10+ Vis	10-15	0-1
Afternoon	MC/OVC, 5-10 Vis	10-20	0-1





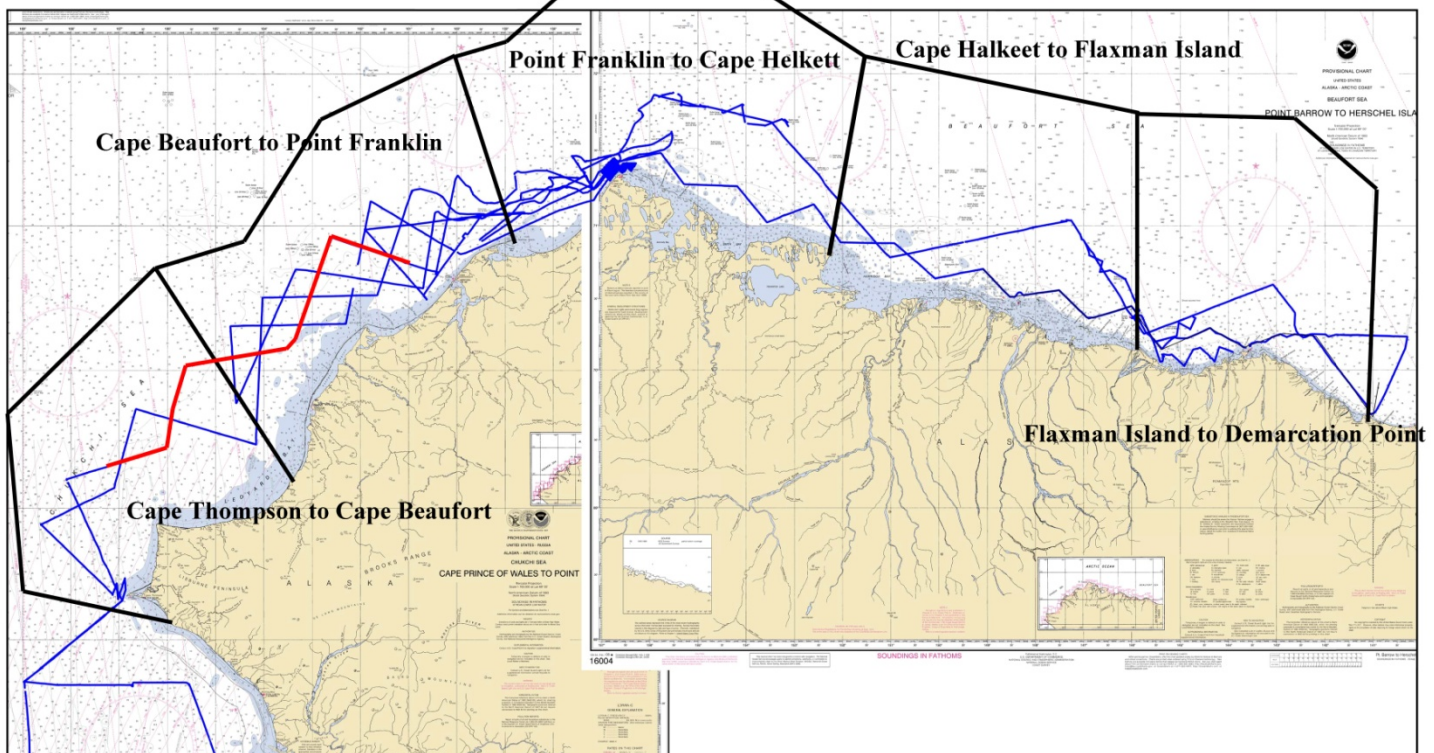
Aug 21, 2012

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	MC/OVC/MST, 1-10 Vis	5-10	0-1
Afternoon	OVC, 8-10 Vis	10-20	2-6



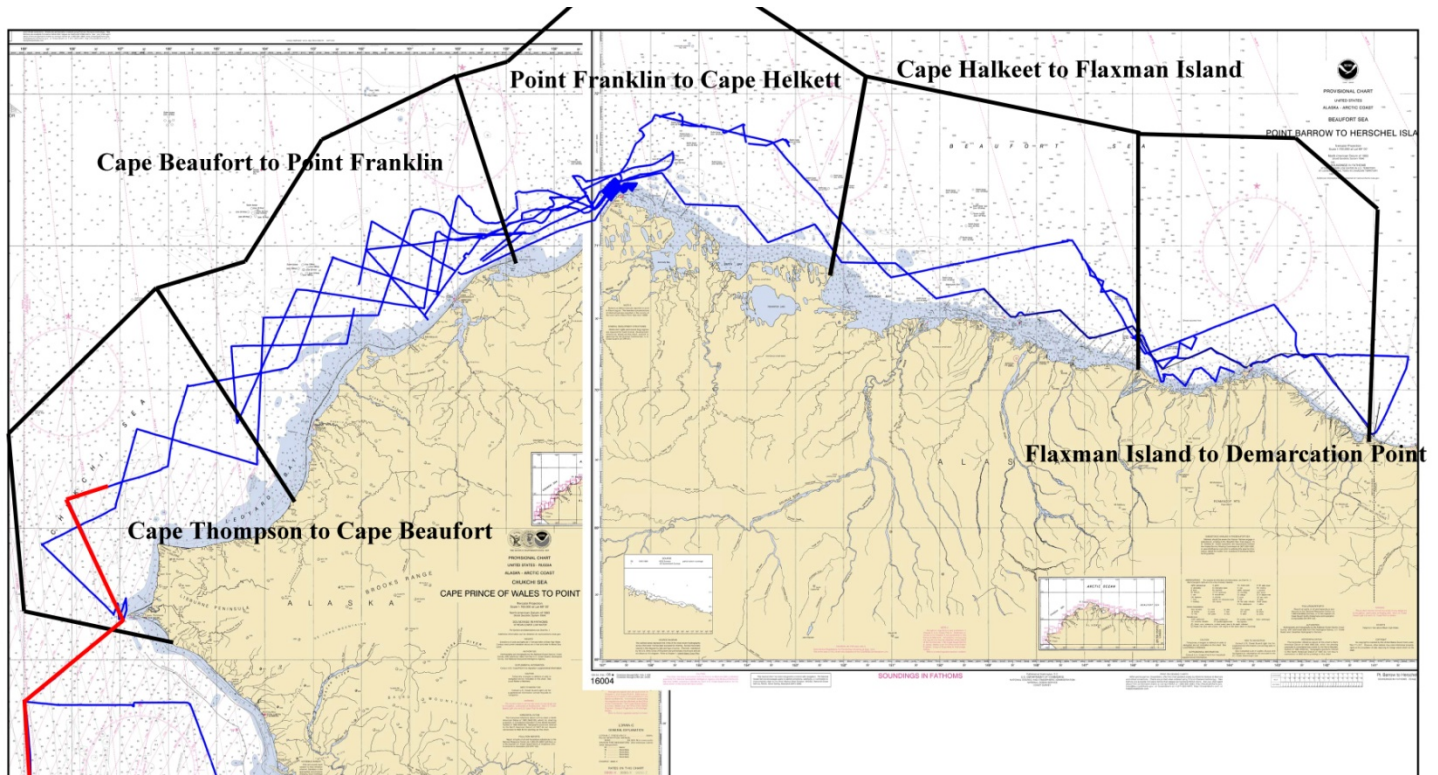
Aug 22, 2012

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
Morning	OVC, 10+ Vis	20-22	10-12
Afternoon	OVC/MST, 3-8 Vis	10-15	3-4



Aug 23, 2012

	Weather (Vis in nm)	Wind (kts)	Wave (ft)
<b>Morning</b>	FG/OVC, ½ Vis	0-5	2-4
<b>Afternoon</b>	MC/OVC, 5-10+ Vis	10 → 40	0 → 14







25-Aug-12	2205	Alaskan Lady	Carrying DG, HS, or MP IMO Hazard or Pollutant Category B	Engaged in Fishing	70	15	14	007742358	367528690	58° 09.30'	167° 09.18'	Dutch Harbor	31 July 1200	no mistake in recording type for Ocean Peace & Alaskan Lady
25-Aug-12	2251	Alaska Spirit	Fishing	U/W using engines	70	12	6	007397091	366705860	58° 15.67'	166° 21.76'	Dutch Harbor	9 Dec 0300	
25-Aug-12	2255	Katie Ann	Fishing	U/W using engines	96	14	6	006931055	366499000	57° 54.68'	167° 25.80'	Dutch Harbor	5 Aug 1200	
26-Aug-12	0300	Alaskan Endeavor	-	U/W using engines	39	9	3.7	793355550	367650000	56° 46.02'	166° 23.67'	Meat Patch	-	>2 hrs
26-Aug-12	0300	Alaska Juris	-	Engaged in Fishing	72	13	6.7	341003073	341003073	56° 34.00'	166° 16.65'	-	12AUG 1712	>2 hrs
26-Aug-12	0300	Seafreeze Alaska	Other	Reserved Future Use	-	-	-	000517242	367390380	56° 45.37'	166° 24.31'	-	-	>2 hrs